

Homework #1 (solution)

Problem 1:

Slowly varying approximation

$$\left| \frac{\partial E_0}{\partial t} \right| \ll \omega E_0; \quad \left| \frac{\partial \varphi}{\partial t} \right| \ll \omega$$

$$\left| \frac{\partial E_0}{\partial z} \right| \ll k E_0; \quad \left| \frac{\partial \varphi}{\partial z} \right| \ll k$$

$$\left| \frac{\partial P}{\partial t} \right| \ll \omega P; \quad \left| \frac{\partial P}{\partial z} \right| \ll k P$$

We also assume that the effect of the medium is weak, so that $P/E_0 \ll 1$

$$\frac{\partial E}{\partial t} = -i\omega E + \underbrace{\frac{1}{\epsilon} \frac{\partial E_0}{\partial t} e^{ikz - i\omega t + i\varphi} + i \frac{\partial \varphi}{\partial t} E}_{\text{small terms}}$$

$$\frac{\partial^2 E}{\partial t^2} = -\omega^2 E - 2i\omega \left(\frac{\partial E_0}{\partial t} e^{ikz - i\omega t + i\varphi} + i \frac{\partial \varphi}{\partial t} E \right) + \left\{ \text{terms } \frac{\partial^2 E_0}{\partial t^2}, \frac{\partial^2 \varphi}{\partial t^2}, \left(\frac{\partial E_0}{\partial t} \frac{\partial \varphi}{\partial t} \right) \right\}$$

neglect due to smallness

Similarly

$$\frac{\partial^2 E}{\partial z^2} = -k^2 E + 2ik \left(\frac{\partial E_0}{\partial z} e^{ikz - i\omega t + i\varphi} + i \frac{\partial \varphi}{\partial z} E \right)$$

And we are keeping only the leading term for P

$$\frac{\partial^2 P}{\partial t^2} = -\omega^2 P e^{ikz - i\omega t + i\varphi}$$

Wave equation

$$-\frac{\partial^2 E}{\partial z^2} + \frac{1}{c^2} \frac{\partial^2 E}{\partial t^2} = -\mu_0 \frac{\partial^2 P}{\partial t^2}$$

$$k^2 E - 2ik \left(\frac{\partial E_0}{\partial z} e^{ikz - i\omega t + i\varphi} + i \frac{\partial \varphi}{\partial z} E_0 \right) + \frac{\omega^2}{c^2} E - \frac{2i\omega}{c^2} \left(\frac{\partial E_0}{\partial t} e^{ikz - i\omega t + i\varphi} + i \frac{\partial \varphi}{\partial t} E_0 \right) = \mu_0 \omega^2 P e^{ikz - i\omega t + i\varphi}$$

$$(k^2 - \omega^2/c^2) E = 0 \Rightarrow k = \omega/c$$

$$-2ik \left[\frac{\partial E_0}{\partial z} + i E_0 \frac{\partial \varphi}{\partial z} + \frac{1}{c} \frac{\partial E_0}{\partial t} + i E_0 \frac{\partial \varphi}{\partial t} \right] = \mu_0 \omega^2 P$$

$$\left[\frac{\partial E_0}{\partial z} + \frac{1}{c} \frac{\partial E_0}{\partial t} \right] + i E_0 \left[\frac{\partial \varphi}{\partial z} + \frac{1}{c} \frac{\partial \varphi}{\partial t} \right] = +i \frac{\mu_0 \omega^2}{2k} P$$

Separating real and imaginary parts

$$\frac{\partial E_0}{\partial z} + \frac{1}{c} \frac{\partial E_0}{\partial t} = -\frac{k}{2\epsilon_0} \text{Im}(P)$$

$$\frac{\partial \varphi}{\partial z} + \frac{1}{c} \frac{\partial \varphi}{\partial t} = \frac{k}{2\epsilon_0} \text{Re}(P)$$

$$\frac{\mu_0 \omega^2}{2k} = \frac{\mu_0 \omega c}{2} = \frac{k}{2\epsilon_0}$$

since $c^2 = 1/\mu_0 \epsilon_0$

$$2) (a) |\psi\rangle = \begin{pmatrix} e^{-i\varphi/2} \cos \theta/2 \\ e^{i\varphi/2} \sin \theta/2 \end{pmatrix}$$

$$\begin{aligned} \langle \hat{S}_x \rangle &= \langle \psi | \hat{S}_x | \psi \rangle = \langle \psi | \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} | \psi \rangle = \\ &= \begin{pmatrix} e^{i\varphi/2} \cos \frac{\theta}{2} & e^{-i\varphi/2} \sin \frac{\theta}{2} \end{pmatrix} \begin{pmatrix} e^{i\varphi/2} \sin \theta/2 \\ e^{-i\varphi/2} \cos \theta/2 \end{pmatrix} = \\ &= (e^{i\varphi} + e^{-i\varphi}) \cos \frac{\theta}{2} \sin \frac{\theta}{2} = \cos \varphi \sin \theta \end{aligned}$$

Similarly

$$\langle \hat{S}_y \rangle = \langle \psi | \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} | \psi \rangle = i(-e^{i\varphi} + e^{-i\varphi}) \cos \frac{\theta}{2} \sin \frac{\theta}{2} = \sin \varphi \sin \theta$$

$$\langle \hat{S}_z \rangle = \langle \psi | \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} | \psi \rangle = \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} = \cos \theta$$

It is easy to notice that $\langle \hat{S}_x \rangle$, $\langle \hat{S}_y \rangle$ and $\langle \hat{S}_z \rangle$ corresponds to the x, y and z component of a unit vector in spherical coordinates

(b) In the presence of magnetic field the $|\uparrow\rangle$ and $|\downarrow\rangle$ states ~~are~~ become non-degenerate, shifting by $\pm \hbar \Omega_L / 2$

Thus, the time evolution of the original quantum state is

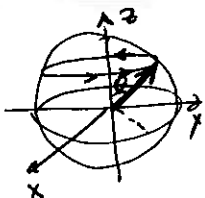
$$|\psi(t)\rangle = \begin{pmatrix} e^{-i\varphi/2 + i\Omega_L t/2} \cos \frac{\theta}{2} \\ e^{i\varphi/2 - i\Omega_L t/2} \sin \frac{\theta}{2} \end{pmatrix} = \begin{pmatrix} e^{-i\varphi(t)/2} \cos \theta/2 \\ e^{i\varphi(t)/2} \sin \theta/2 \end{pmatrix}$$

where $\varphi(t) = \varphi - \Omega_L t$

Thus, using results from (a)

$$\langle \hat{S}_x(t) \rangle = \cos(\varphi - \Omega_L t) \sin \theta, \quad \langle \hat{S}_y(t) \rangle = \sin(\varphi - \Omega_L t) \sin \theta, \quad \langle \hat{S}_z(t) \rangle = \cos \theta$$

That corresponds to the rotation of the unit vector about z -axis at frequency Ω_L



HW # 2

Homework #2 (solutions)

P1.

$$\begin{cases} \dot{C}_1 = \frac{i}{2} R c_2 \\ \dot{C}_2 = \frac{i}{2} R (C_1 + C_3) \\ \dot{C}_3 = \frac{i}{2} R c_2 \end{cases}$$

$$\therefore \dot{C}_k(t) = -\frac{i}{\hbar} \sum_k C_k(t) e^{i\omega_{2k}t} \langle 2|H_{\pm}|k \rangle$$

$$\langle 1|H|1 \rangle = \langle 2|H|2 \rangle = \langle 3|H|3 \rangle = 0$$

$$\therefore \dot{C}_1 = -\frac{i}{\hbar} C_2 e^{i\omega_1 t} \langle 1|H|2 \rangle - \frac{i}{\hbar} C_3 e^{i\omega_3 t} \langle 1|H|3 \rangle$$

$$\therefore \langle 1|H|3 \rangle = 0$$

$$-\frac{i}{\hbar} e^{i\omega_1 t} \langle 1|H|2 \rangle = \frac{i}{2} R$$

$$\langle 1|H|2 \rangle = \frac{-\hbar R}{2} e^{i\omega_2 t}$$

$$C_3 = -\frac{i}{\hbar} C_1 e^{i\omega_3 t} \langle 3|H|1 \rangle - \frac{i}{\hbar} C_2 e^{i\omega_3 t} \langle 3|H|2 \rangle$$

$$\langle 3|H|1 \rangle = 0$$

$$-\frac{i}{\hbar} e^{i\omega_3 t} \langle 3|H|2 \rangle = \frac{i}{2} R$$

$$\langle 3|H|2 \rangle = \frac{-\hbar R}{2} e^{i\omega_3 t}$$

$$c_2 = -\frac{i}{\hbar} c_1 e^{i\omega_{n1}t} \langle 2|H|1 \rangle - \frac{i}{\hbar} c_3 e^{i\omega_{23}t} \langle 2|H|3 \rangle$$

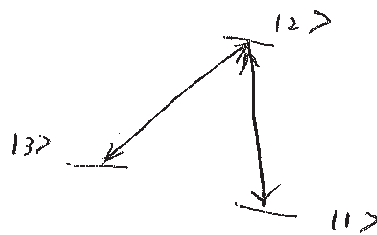
$$\begin{cases} -\frac{i}{\hbar} e^{i\omega_{n1}t} \langle 2|H|1 \rangle = \frac{i}{2} R \\ -\frac{i}{\hbar} e^{i\omega_{23}t} \langle 2|H|3 \rangle = \frac{i}{2} R \end{cases}$$

$$\langle 2|H|1 \rangle = \frac{-\hbar R}{2} e^{-i\omega_{n1}t}$$

$$\langle 2|H|3 \rangle = -\frac{\hbar R}{2} e^{-i\omega_{23}t}$$

$$\therefore H_I = \frac{-\hbar R}{2} \begin{pmatrix} 0 & e^{i\omega_{n1}t} & 0 \\ e^{i\omega_{n1}t} & 0 & e^{i\omega_{23}t} \\ 0 & e^{i\omega_{23}t} & 0 \end{pmatrix}$$

$$\omega_{E_k} = \frac{E_0 - E_k}{\hbar}$$



Rabi oscillations for $\Delta \neq 0$

$$\begin{cases} \dot{c}_a = i\Delta c_a + i\Omega c_b \\ \dot{c}_b = i\Omega^* c_a \end{cases}$$

$$\ddot{c}_a = i\Delta \dot{c}_a + i\Omega \dot{c}_b = i\Delta \dot{c}_a - \Omega^2 c_a$$

$$c_a = e^{i\lambda t} : \quad -\lambda^2 = -\lambda\Delta - \Omega^2$$

$$\lambda^2 - \lambda\Delta - \Omega^2 = 0$$

$$\lambda_{1,2} = \frac{\Delta}{2} \pm \sqrt{\frac{\Delta^2}{4} + \Omega^2}$$

$$c_a(t) = A_1 e^{i\lambda_1 t} + A_2 e^{i\lambda_2 t} = e^{i\frac{\Delta t}{2}} \left[A_1 e^{i\sqrt{\frac{\Delta^2}{4} + \Omega^2} t} + A_2 e^{-i\sqrt{\frac{\Delta^2}{4} + \Omega^2} t} \right]$$

$$c_a(0) = 0 \Rightarrow A_1 = -A_2 = A/2i$$

$$c_a(t) = A e^{i\Delta t/2} \sin \sqrt{\frac{\Delta^2}{4} + \Omega^2} \cdot t$$

$$c_b(t) = \frac{1}{i\Omega} (i\Delta c_a - i\Omega c_b) = \frac{1}{i\Omega} A \left[\frac{i\Delta}{2} c_a + \sqrt{\frac{\Delta^2}{4} + \Omega^2} e^{i\frac{\Delta t}{2}} \cos \sqrt{\frac{\Delta^2}{4} + \Omega^2} t - i\Delta c_a \right] = \frac{A}{i\Omega} e^{i\frac{\Delta t}{2}} \left[\sqrt{\frac{\Delta^2}{4} + \Omega^2} \cos \sqrt{\frac{\Delta^2}{4} + \Omega^2} t - \frac{\Delta}{2} \sin \sqrt{\frac{\Delta^2}{4} + \Omega^2} t \right]$$

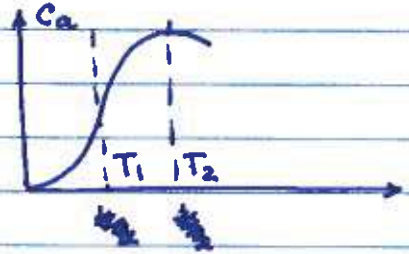
$$\text{since } c_b(t=0) = 1 = \frac{A}{i\Omega} \sqrt{\frac{\Delta^2}{4} + \Omega^2}$$

$$A = \frac{i\Omega}{\sqrt{\frac{\Delta^2}{4} + \Omega^2}}$$

$$P_a(t) = |c_a|^2 = \frac{\Omega^2}{\frac{\Delta^2}{4} + \Omega^2} \sin^2 \left(\sqrt{\frac{\Delta^2}{4} + \Omega^2} \cdot t \right)$$

Rabi oscillations

$$|\psi\rangle = \cos(|\Omega|t) |b\rangle + i \frac{\Omega}{|\Omega|} \sin(|\Omega|t) |a\rangle$$



a) $|\psi\rangle_{\text{target}} = \frac{1}{\sqrt{2}} (|a\rangle + |b\rangle)$

$$T_1 |\Omega| = \frac{\pi}{2} \Rightarrow T_1 = \frac{\pi}{2|\Omega|}$$

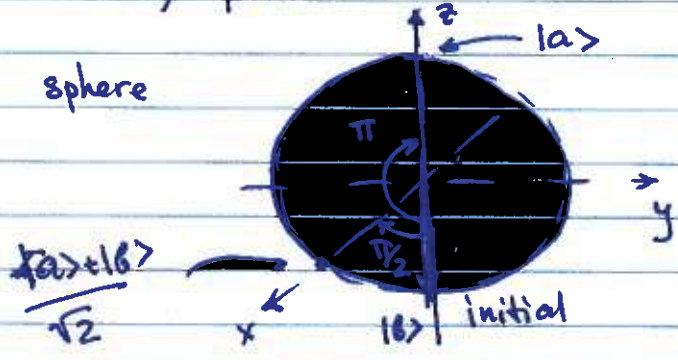
The phase of the optical field must be $-\pi/2$, so that

$$\frac{\Omega}{|\Omega|} = e^{i\varphi} = -i$$

b) $|\psi\rangle_{\text{target}} = |a\rangle$
any phase

$$T_2 |\Omega| = \frac{\pi}{2} \quad T_2 = \frac{\pi}{2|\Omega|}$$

Bloch sphere



5)

$$\begin{cases} \dot{c}_1 = \frac{i}{2} R c_2 \\ \dot{c}_2 = \frac{i}{2} R c_1 + \frac{i}{2} R c_3 \\ \dot{c}_3 = \frac{i}{2} R c_2 \end{cases}$$

Since there is no term $\dot{c}_i = i\Delta c_i + \dots$
we can conclude that there is no detunings
(i.e. all laser fields are tuned exactly on
resonances)

Then, using $i\hbar \frac{\partial |\psi\rangle}{\partial t} = \hat{H} |\psi\rangle$

$$c_i = -\frac{i}{\hbar} \sum_{k \neq i} c_k \langle i | \hat{H} | k \rangle$$

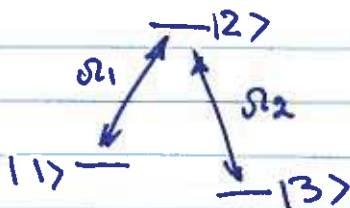
$$c_1 = -\frac{i}{\hbar} (c_2 \langle 1 | \hat{H} | 2 \rangle + c_3 \langle 1 | \hat{H} | 3 \rangle)$$

comparing ~~to~~ to the equations: $\langle 1 | \hat{H} | 3 \rangle = 0$
 $-\frac{i}{\hbar} \langle 1 | \hat{H} | 2 \rangle = \frac{i}{2} R$

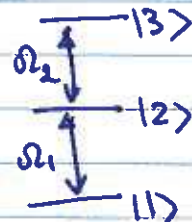
similarly $-\frac{i}{\hbar} \langle 3 | \hat{H} | 2 \rangle = \frac{i}{2} R$

$$\langle 1 | \hat{H} | 2 \rangle = -\rho_{12} \Omega_1 \Rightarrow \Omega_1 = R/2$$

$$\langle 3 | \hat{H} | 2 \rangle = -\rho_{23} \Omega_2 \Rightarrow \Omega_2 = R/2$$



or

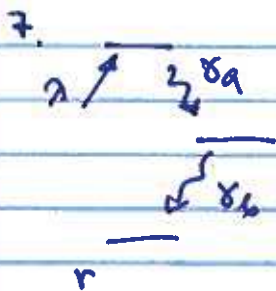


$$6. |\psi_1\rangle = \frac{|a\rangle + |b\rangle}{\sqrt{2}} \Rightarrow |\psi_1\rangle\langle\psi_1| = \begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}$$

$$|\psi_2\rangle = \frac{|a\rangle - 3|b\rangle}{\sqrt{10}} \Rightarrow |\psi_2\rangle\langle\psi_2| = \begin{pmatrix} 1/10 & -3/10 \\ -3/10 & 9/10 \end{pmatrix}$$

$$|\psi_3\rangle = |b\rangle \quad |\psi_3\rangle\langle\psi_3| = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\hat{\rho} = \sum p_i |\psi_i\rangle\langle\psi_i| = 0.3 \begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix} + 0.5 \begin{pmatrix} 1/10 & -3/10 \\ -3/10 & 9/10 \end{pmatrix} + 0.2 \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1/5 & 0 \\ 0 & 4/5 \end{pmatrix}$$



$$\dot{\rho}_{aa} = \lambda - \gamma_a \rho_{aa}$$

$$\dot{\rho}_{bb} = \gamma_a \rho_{aa} - \gamma_b \rho_{bb}$$

Steady-state solution

$$\rho_{aa} = \frac{\lambda}{\gamma_a} \quad \rho_{bb} = \frac{\lambda}{\gamma_b}$$

$$\rho_{aa} - \rho_{bb} = \lambda \left(\frac{1}{\gamma_a} - \frac{1}{\gamma_b} \right)$$

Population Inversion $\rightarrow \gamma_a < \gamma_b$ for any λ .