

Revealing invisible spatial structure of Quantum Squeezed Vacuum.

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Pratik J. Barge, Hwang Lee, Lior Cohen²

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Charris Gabaldon



Irina Novikova



Lior Cohen



Hwang Lee



Savannah Cuozzo



Ziqi Niu



Pratik Barge



Narayan Bhusal

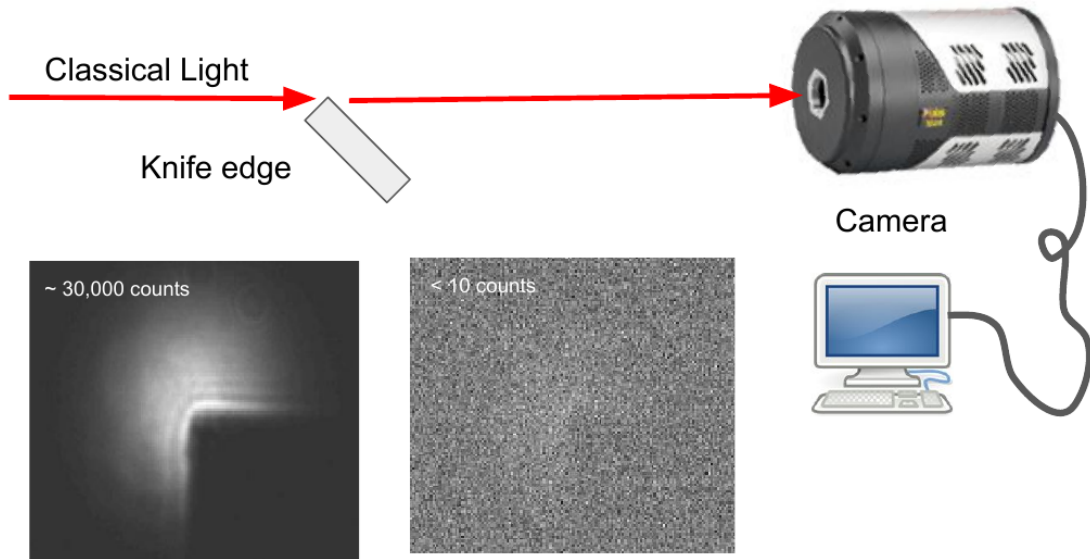


Nikunj Kumar Prajapati

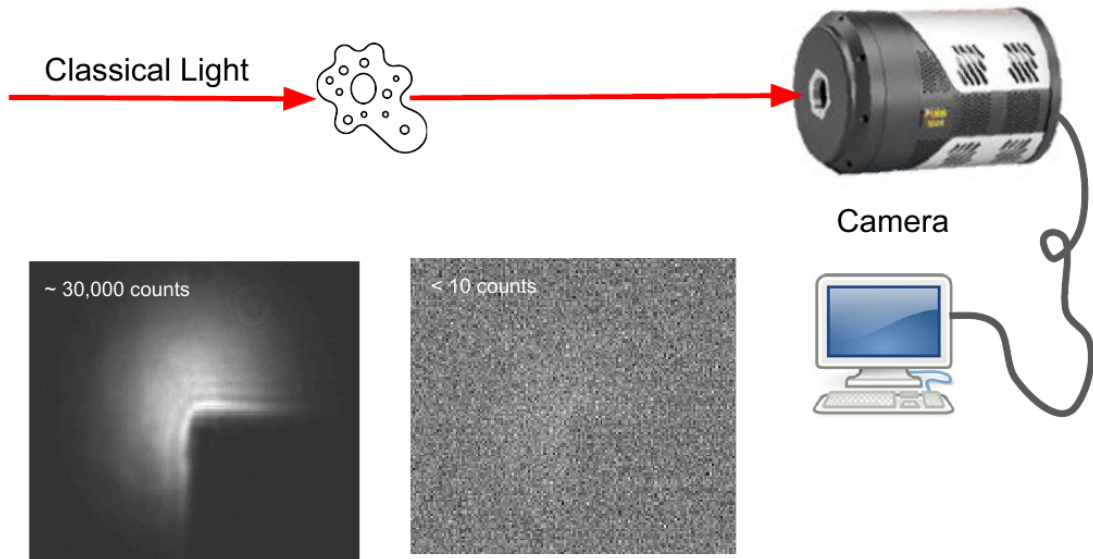


Jon Dowling (1955-2020)

From bright to low light imaging

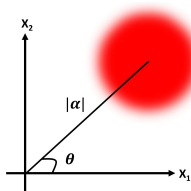


From bright to low light imaging

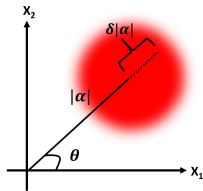


Let's look at quantum picture

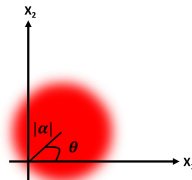
Bright state in



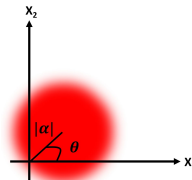
Bright state out



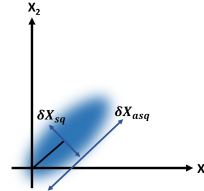
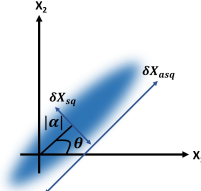
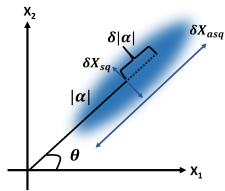
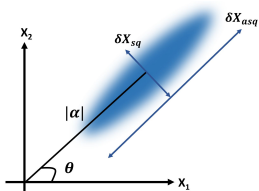
Low-light state in



Low-light state out

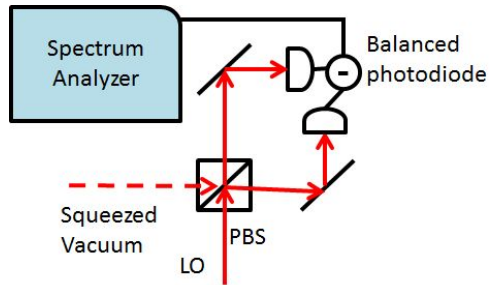
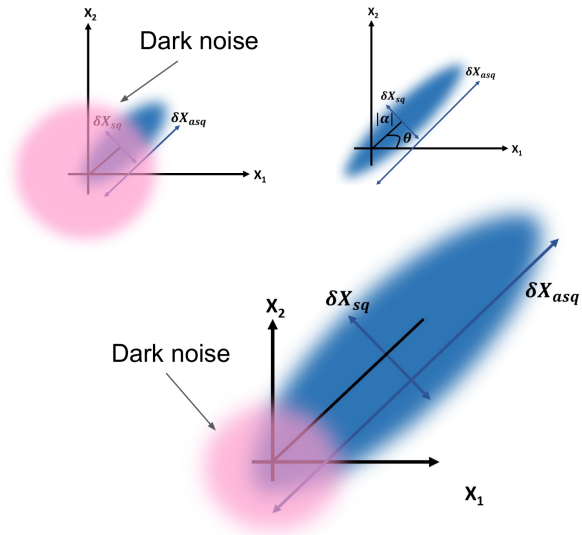


$$\alpha_{out}^2 = \alpha_{in}^2 T$$

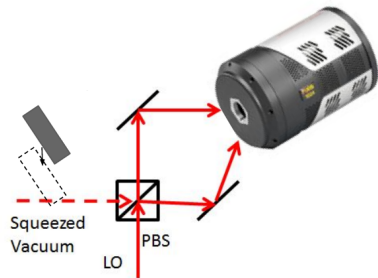
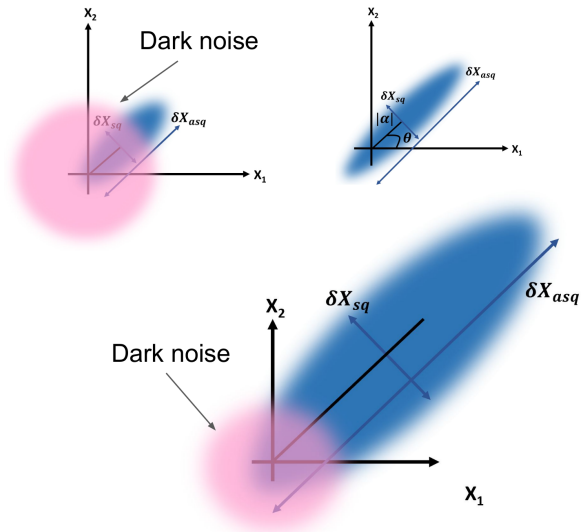


$$V = 1 + (\delta X_{sq/asq}^2 - 1) |\mathcal{O}|^2 T$$

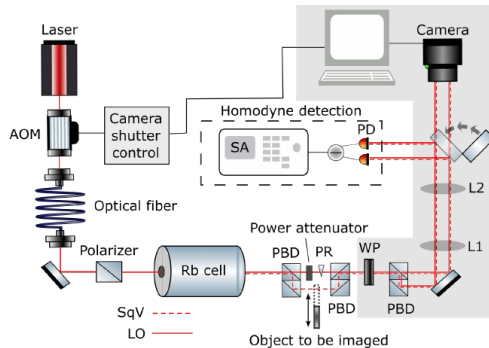
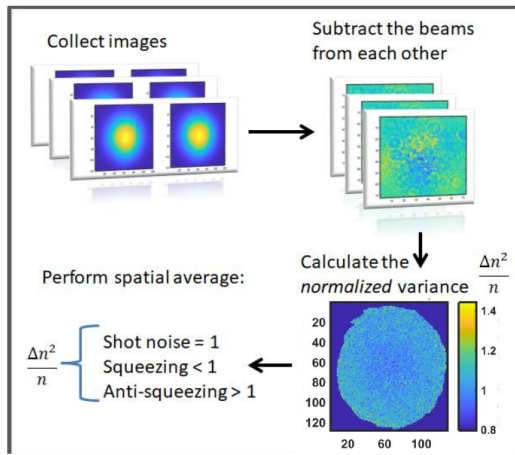
Detector dark noise



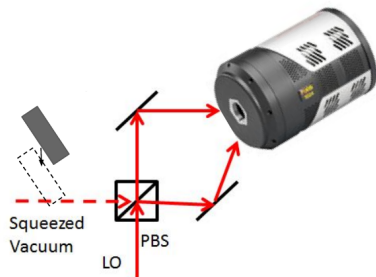
Detector dark noise



Imaging quantum noise

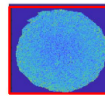


Imaging quantum noise with binning

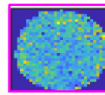


$$V = 1 + (\delta X_{sq/asq}^2 - 1)|\mathcal{O}|^2 T$$

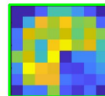
- Single pixel analysis = shot noise limited



Binning = 1

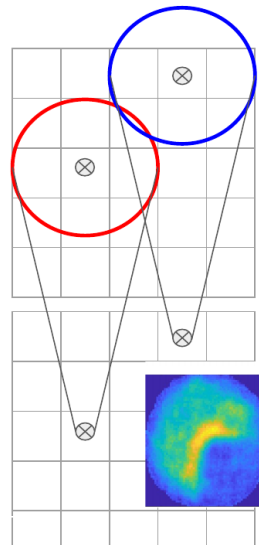


Binning = 4

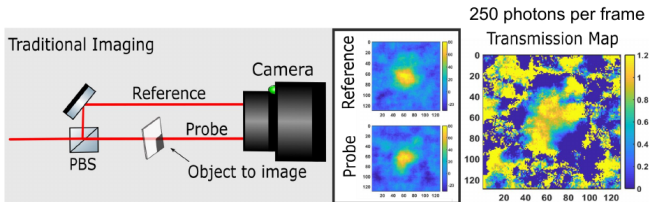
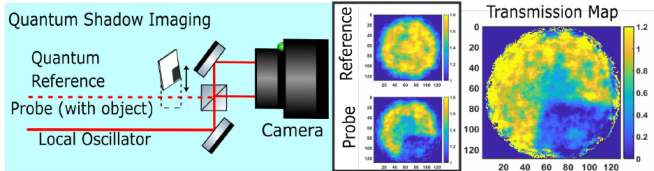


Binning = 16

- Binning pixels reveals non-classical statistics

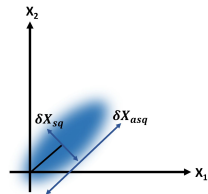


Shadow imaging



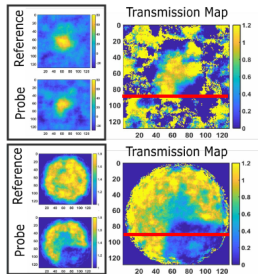
$$V_{pr} = 1 + (\delta X_{ref}^2 - 1) |\mathcal{O}|^2 T$$

$$T = \frac{V_{pr} - 1}{V_{ref} - 1}$$

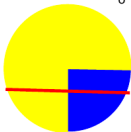


$$T = \frac{|\alpha_{pr}|^2}{|\alpha_{ref}|^2} = \frac{N_{pr}}{N_{ref}}$$

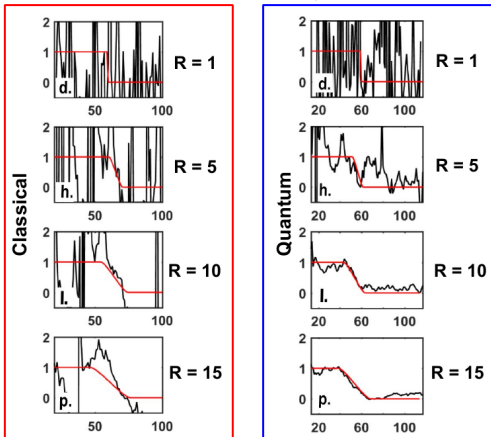
Similarity Parameter



Ideal case: T_o

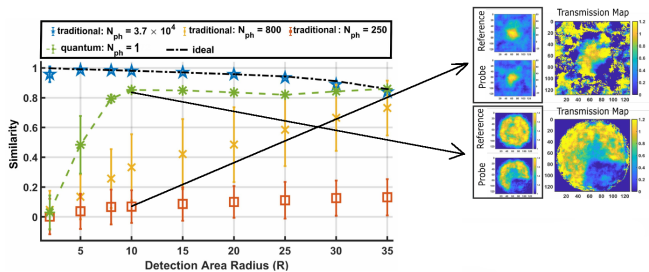


Transmission Map Cross-section



$$S = \frac{\sum T_{exp} T_o}{\sqrt{\sum T_{exp}^2 \sum T_o^2}}$$

Similarity Parameter

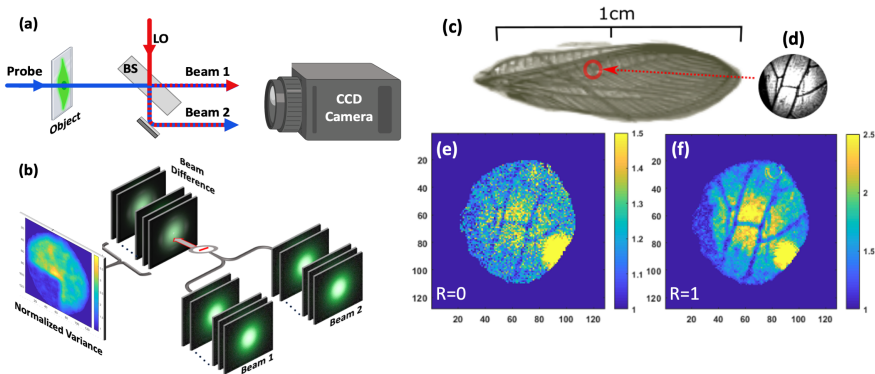


Savannah Couzzo

$$S = \frac{\sum T_{exp} T_o}{\sqrt{\sum T_{exp}^2 \sum T_o^2}}$$

"Low-Light Shadow Imaging Using Quadrature-Noise Detection with a Camera", Advanced Quantum Technologies, 2100147, (2022).

Imaging with thermal light



Ziqi Niu

"Weak Thermal State Quadrature-Noise Shadow Imaging", Optics Express, Issue 16, 30, 29401–29408, (2022).

Structural light imaging: single pixel camera

Single-pixel imaging 12 years on: a review

GRAHAM M. GIBSON,^{1,2}  STEVEN D. JOHNSON,^{1,3}  AND MILES J. PADGETT^{1,4} 

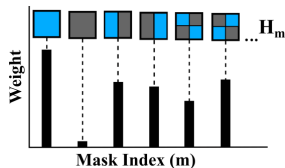
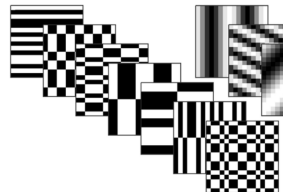
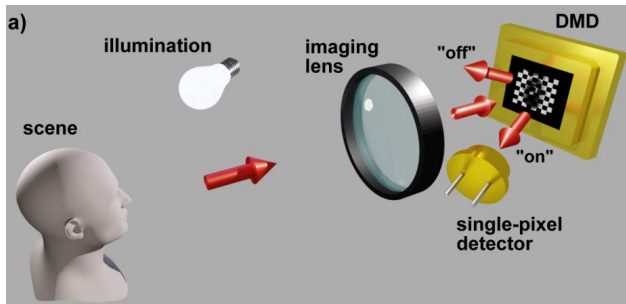
¹*School of Physics and Astronomy, University of Glasgow, Glasgow G12 8QQ, UK*

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³*steven.johnson@glasgow.ac.uk*

⁴*miles.padgett@glasgow.ac.uk*

<https://www.gla.ac.uk/schools/physics/ourresearch/groups/optics/>



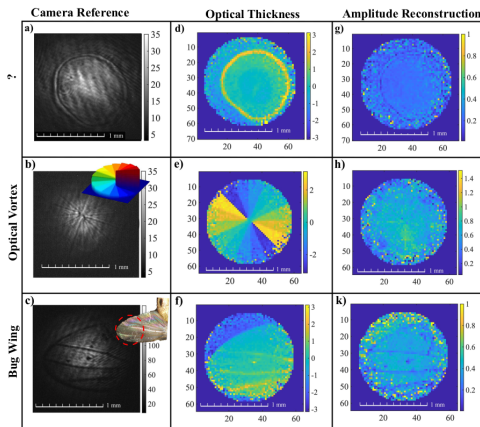
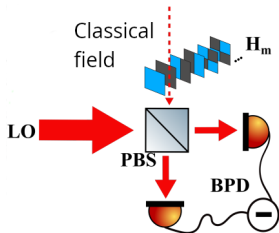
Reconstructed object

$$Ob(x, y) = \frac{1}{M} S_m P_m(x, y)$$

Structural light classical homodyning

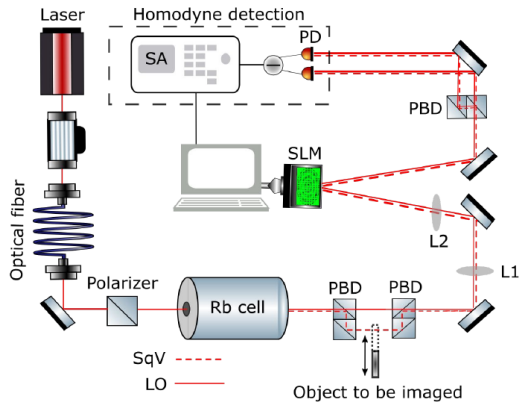


Charris Gabaldon



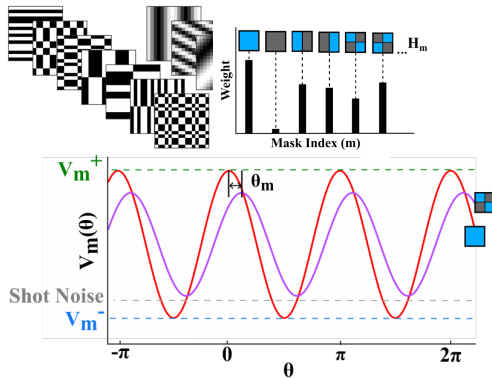
"Wave-Front Reconstruction via Single-Pixel Homodyne Imaging", Optics Express, Issue 21, 30, 37938–37945, (2022).

Structural light imaging with quantum noise



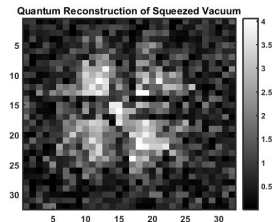
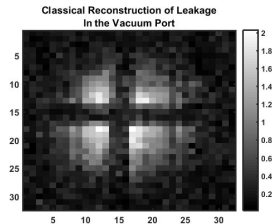
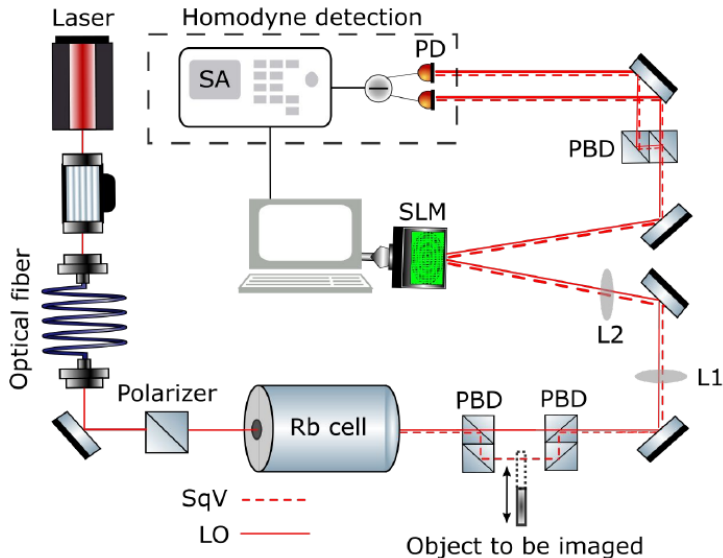
$$V_m = 1 + (\delta X_{sq/asq}^2 - 1) |\mathcal{O}_m|^2$$

$$\mathcal{O}_m = \int_A P_m u_{lo} u_q^* T dA$$



$$u_{lo} u_q^* T = \frac{1}{M} \sum \mathcal{O}_m P_m(x, y)$$

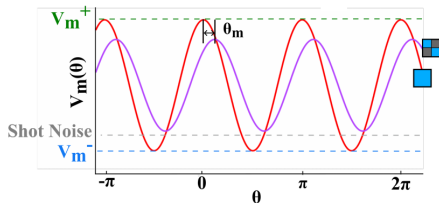
Structural light imaging with quantum noise



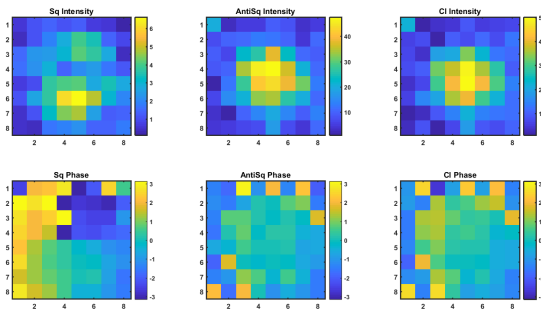
Structural light using different quadratures

$$V_m = 1 + (\delta X_{sq/asq}^2 - 1)|\mathcal{O}_m|^2$$

$$\mathcal{O}_m = \int_A P_m u_{lo} u_q^* T dA$$



$$u_{lo} u_q^* T = \frac{1}{M} \sum \mathcal{O}_m P_m(x, y)$$



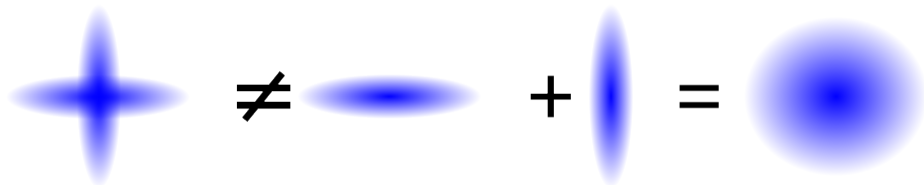
"Quantum fluctuations spatial mode profiler", AVS Quantum Science, 5, 025005, (2023).

What is the mode?

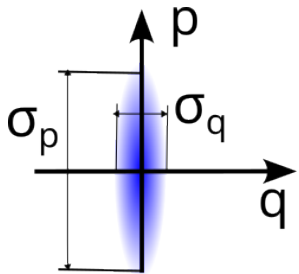
Classical modes (Electric field distribution)

$$\mathbf{CL} = \mathbf{C} + \mathbf{L} = \mathbf{C}^T + \mathbf{C}_L$$

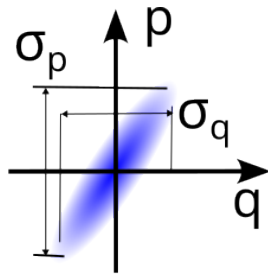
Quadratures probability



Gaussian state, joint probability density and covariance matrix



$$W(q, p) = \frac{1}{2\pi} \frac{1}{\sigma_q \sigma_p} e^{-\frac{1}{2} \left(\frac{q^2}{\sigma_q^2} + \frac{p^2}{\sigma_p^2} \right)}$$



$$W(q, p) = \frac{1}{2\pi} \frac{1}{\sqrt{|\Sigma|}} e^{-\frac{1}{2} ((q, p) \Sigma^{-1} (q, p)^T)}$$

$$\Sigma = \begin{pmatrix} \sigma_q^2 & C \\ C & \sigma_p^2 \end{pmatrix}, C = \langle qp \rangle$$

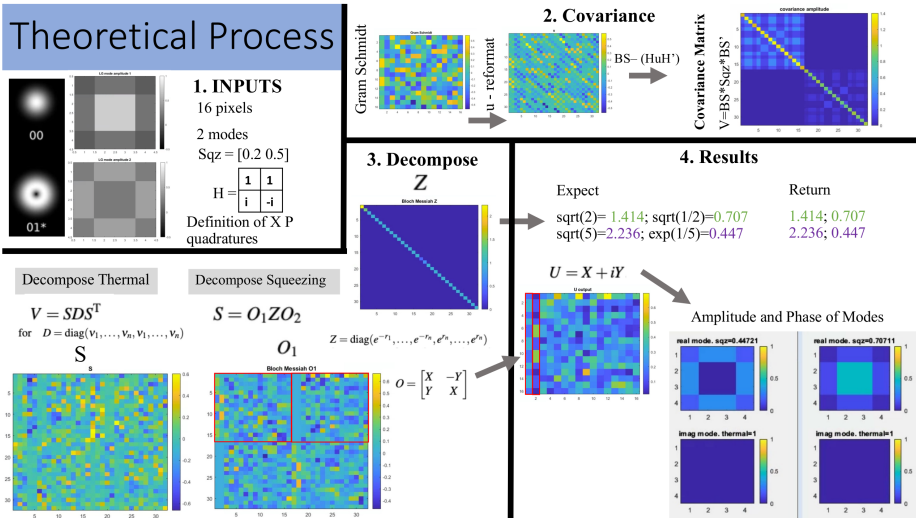
Gaussian states mixture

$$W(q_1, p_1, q_2, p_2, \dots, q_n, p_n) = \frac{1}{(2\pi)^n} \frac{1}{\sqrt{\Sigma}} e^{-\frac{1}{2}((q_1, p_1, q_2, p_2, \dots, q_n, p_n) \Sigma^{-1} (q_1, p_1, q_2, p_2, \dots, q_n, p_n)^T)}$$

$$\Sigma = \begin{pmatrix} \Sigma_1 & & & & \\ & \Sigma_2 & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & & \Sigma_n \end{pmatrix}$$

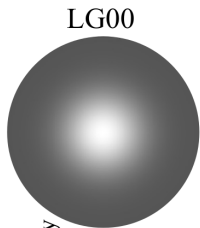
$$\Sigma_i = \begin{pmatrix} \sigma_{q_i}^2 & C_i \\ C_i & \sigma_{p_i}^2 \end{pmatrix}, C_i = \langle q_i p_i \rangle$$

De-composition of covariance matrix to a basic states

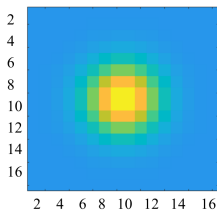


Single mode in pixel space

Shape $U(x, y)$

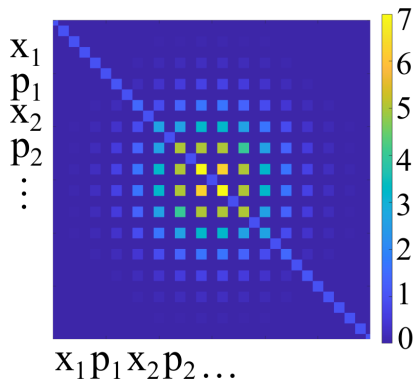


Imaginary field: $\mathbf{p}$
Real field: $\mathbf{x}$



Sqz= $[\mathbf{10}; \frac{1}{10}]$

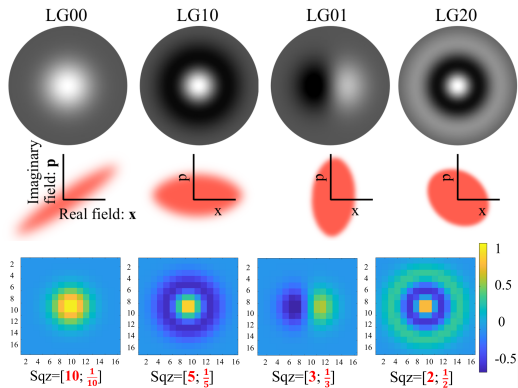
Covariance matrix Σ



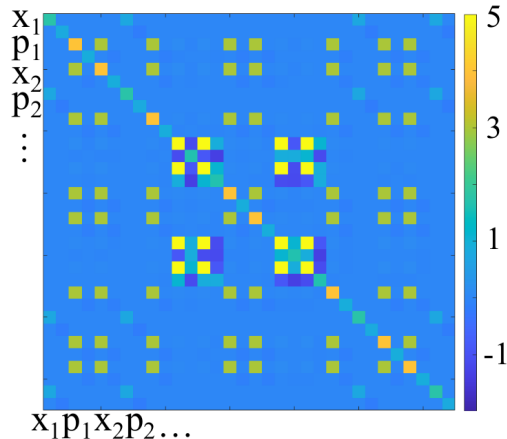
Probability $W(x, p)$

Gaussian states mixture

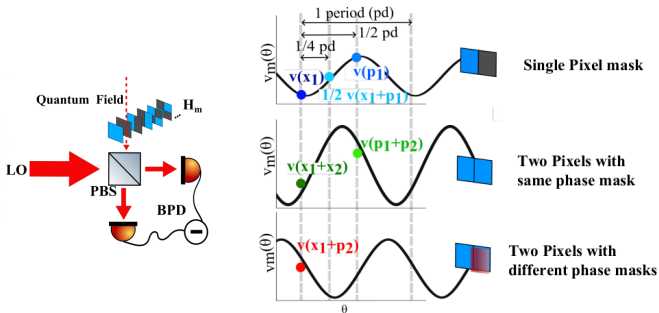
Input states



Truncated covariance matrix Σ



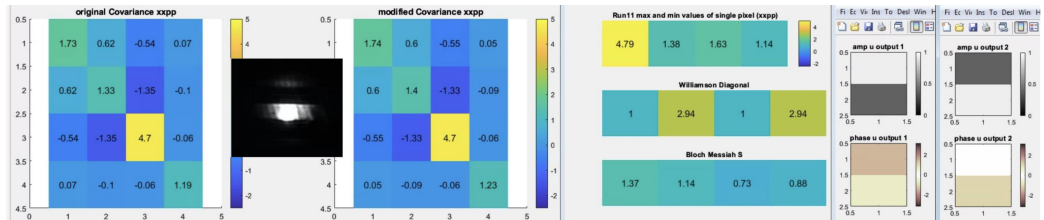
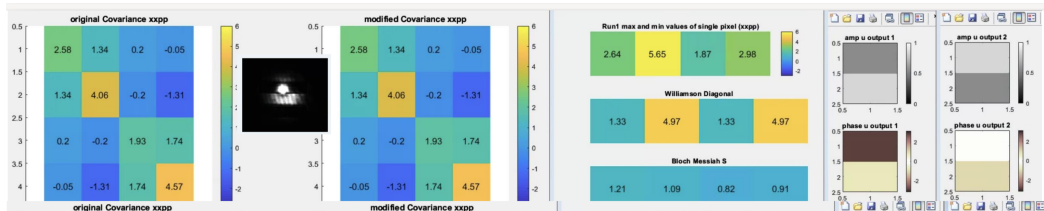
How to measure covariance matrix



	x_1	p_1	x_2	p_2
x_1	$v(x_1)$	$2\text{Cov}(x_1, p_1) = v(x_1 + p_1) - v(x_1) - v(p_1)$	$2\text{Cov}(x_1, x_2) = v(x_1 + x_2) - v(x_1) - v(x_2)$	$2\text{Cov}(x_1, p_2) = v(x_1 + p_2) - v(x_1) - v(p_2)$
p_1	$2\text{Cov}(p_1, x_1) = v(p_1 + x_1) - v(p_1) - v(x_1)$	$v(p_1)$	$2\text{Cov}(p_1, x_2) = v(p_1 + x_2) - v(p_1) - v(x_2)$	$2\text{Cov}(p_1, p_2) = v(p_1 + p_2) - v(p_1) - v(p_2)$
x_2	$2\text{Cov}(x_2, x_1) = v(x_2 + x_1) - v(x_2) - v(x_1)$	$2\text{Cov}(x_2, p_1) = v(x_2 + p_1) - v(x_2) - v(p_1)$	$v(x_2)$	$2\text{Cov}(x_2, p_2) = v(x_2 + p_2) - v(x_2) - v(p_2)$
p_2	$2\text{Cov}(p_2, x_1) = v(p_2 + x_1) - v(p_2) - v(x_1)$	$2\text{Cov}(p_2, p_1) = v(p_2 + p_1) - v(p_2) - v(p_1)$	$2\text{Cov}(p_2, x_2) = v(p_2 + x_2) - v(p_2) - v(x_2)$	$v(p_2)$

Required measurements: $(2N_p)^2/2$

Real data



Summary

