

Review

Forces acting on the rod:

$$\vec{F}_{\text{net}} = \vec{0} = \vec{T} + M\vec{g} + \vec{F}_H$$

$$\vec{\tau}_{\text{net}} = \vec{0}$$

$$= \vec{\tau}_T + \vec{\tau}_g + \vec{\tau}_H = 0$$

with respect to **A**: $\vec{\tau}_{\text{net}} \Rightarrow$

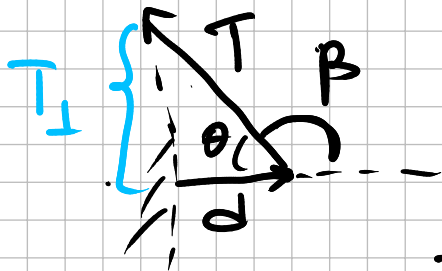
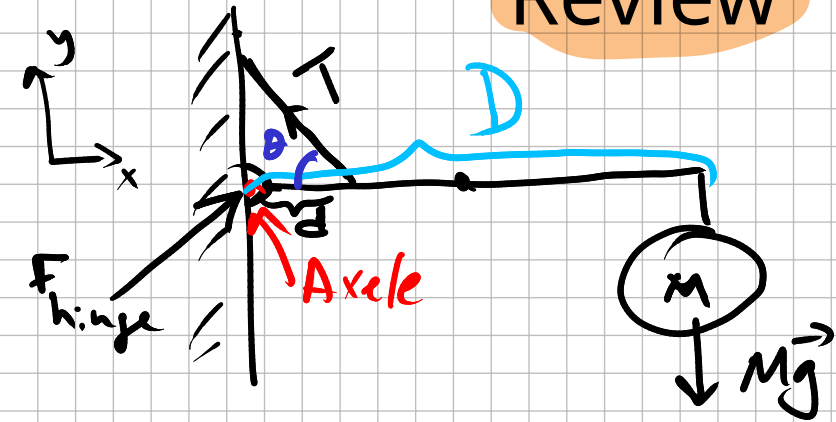
$$\text{CW: } \tau_{\text{net}} = -d \cdot T \sin \beta + D \cdot Mg \cdot \sin 90^\circ + 0 \cdot F_H$$

$$= -dT \cdot \sin(180^\circ - \theta) + D \cdot Mg$$

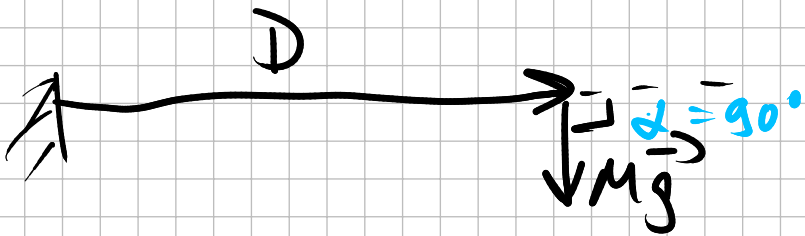
$$+ D \cdot Mg$$

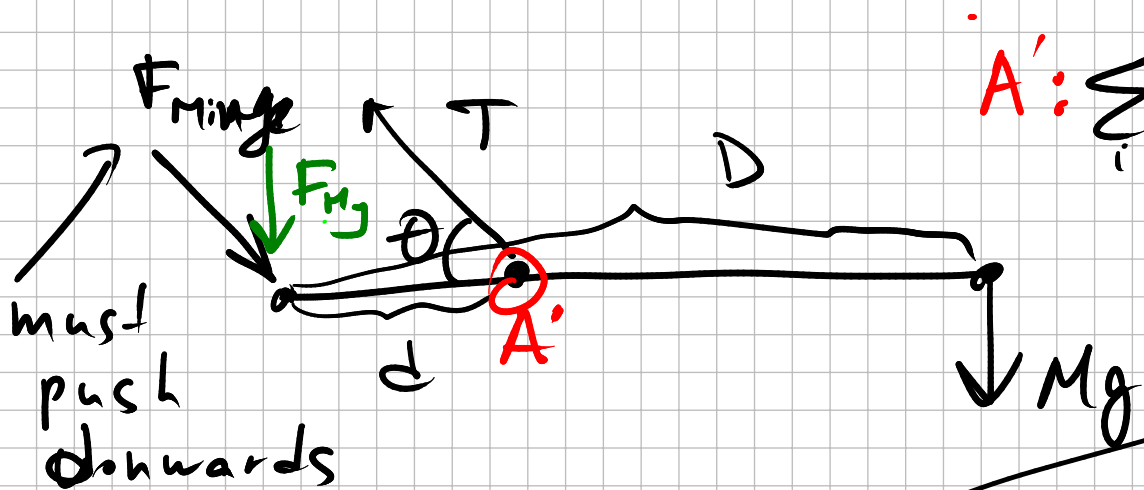
$$= -dT \sin(\theta) + D \cdot Mg$$

$$\Rightarrow \boxed{T = \frac{D}{d \cdot \sin \theta} Mg}$$



$$\tau_T = \vec{d} \times \vec{T} = d \cdot T_{\perp}$$





$$A: \sum \vec{\tau}_i = 0 \Rightarrow \downarrow \cdot F_{my} - (D-d)Mg$$

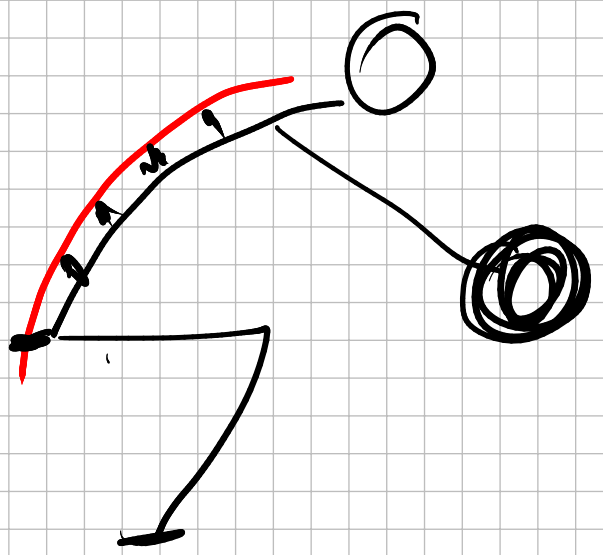
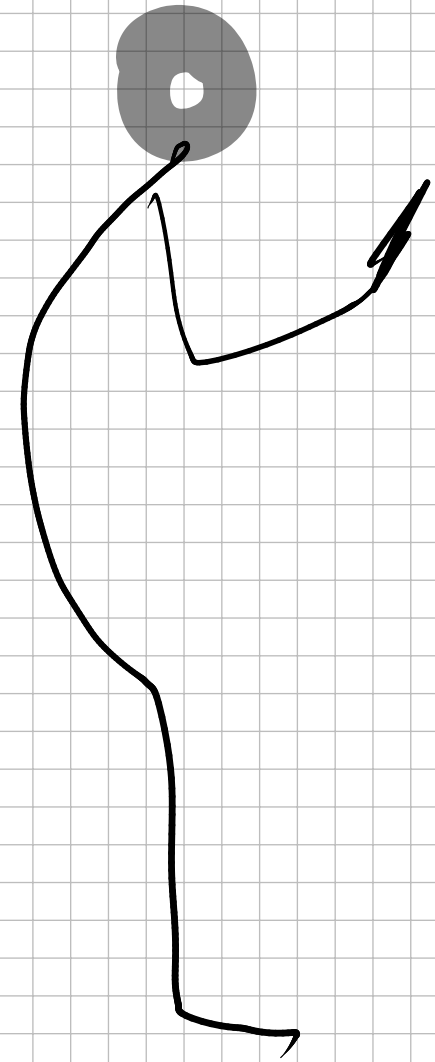
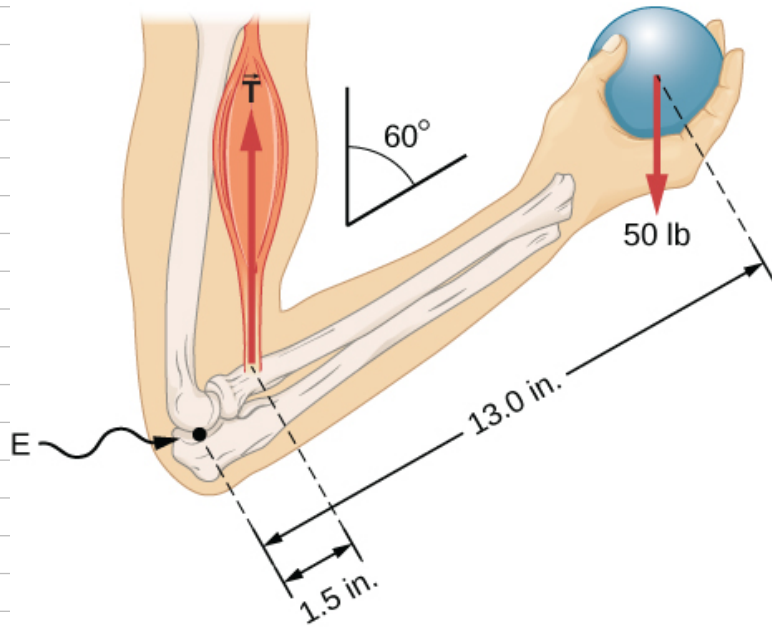
$$\sum \vec{F}_i = 0$$

$$x: F_{H_x} + T_x = 0$$

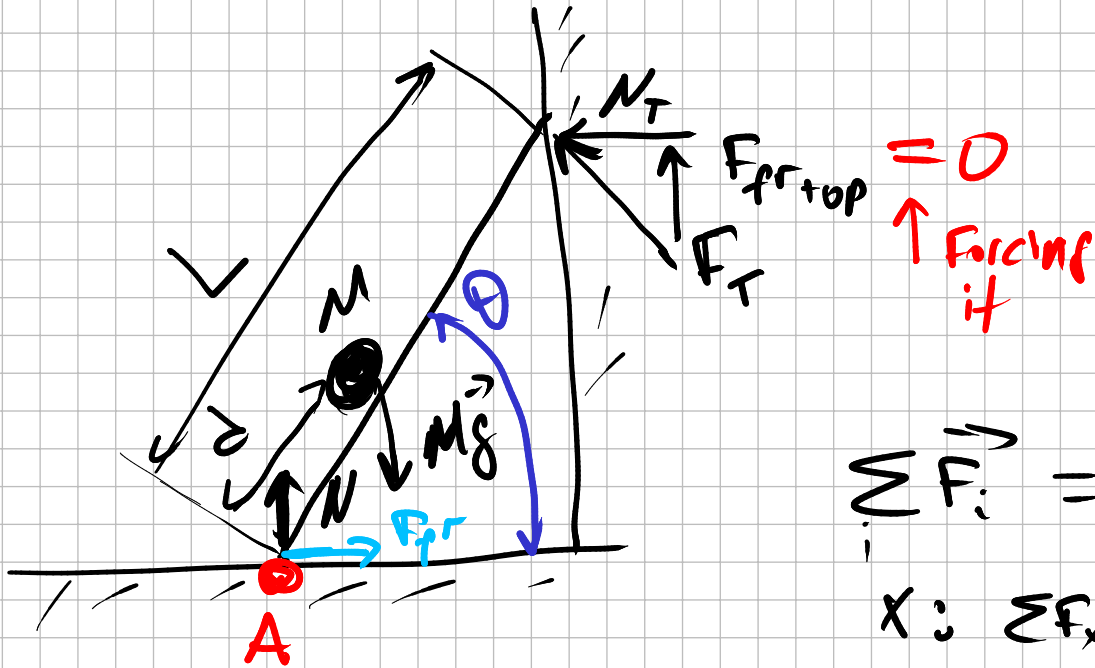
$$y: F_{H_y} + T_y + Mg_y = 0$$

$$F_{H_y} = \frac{D-d}{d} \cdot Mg$$

$$\Rightarrow F_{H_x} = T \cos \theta$$



Climbing ladder



$$\sum \vec{F}_i = 0$$

$$\sum \vec{\tau}_i = 0$$

$$\sum \vec{F}_i = \vec{N} + m\vec{g} + \vec{F}_{fr} + \vec{N}_T = \vec{0}$$

$$x: \sum F_x = 0 + 0 + F_{fr} - N_T$$

$$y: \sum F_y = 0 = N - mg$$

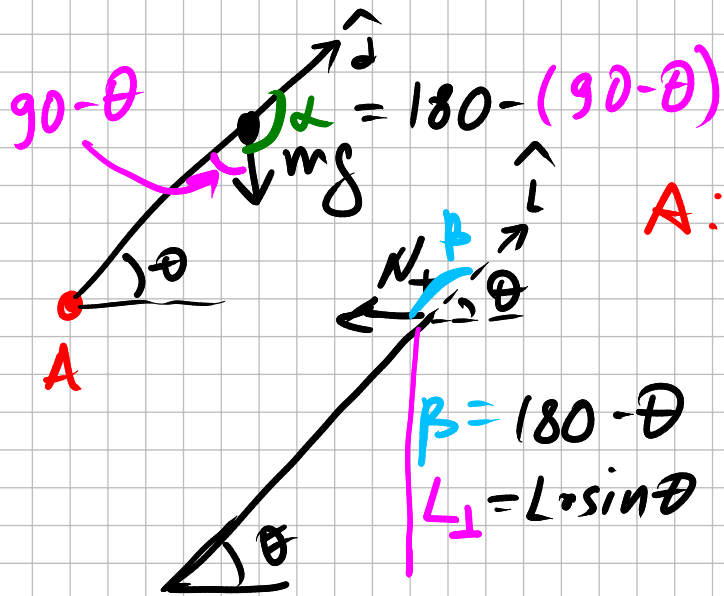
$$\sum \vec{\tau}_i = \vec{0} = \vec{\tau}_N + \vec{\tau}_g + \vec{\tau}_{fr} + \vec{\tau}_{N_T}$$

$$= 0 + d \cdot Mg \cdot \sin \alpha \cdot \hat{c}_w + 0 + L \cdot N_T \sin \beta \cdot \hat{c}_w$$

$$= d \cdot Mg \hat{c}_w \cdot \sin \alpha - L N_T \cdot \sin \beta \cdot \hat{c}_w$$

$$d \cdot Mg \sin(180 - 90 + \theta)$$

$$- L N_T \sin(180 - \theta) = 0$$



\hat{c}_w :

$$d \cdot M \cdot g \cdot \underbrace{\sin(90^\circ + \theta)}_{\cos \theta} - L N_T \sin \theta = 0$$

$$d M g \cos \theta - L N_T \sin \theta = 0$$

$$N_T = \frac{d M g}{L} \frac{\cos \theta}{\sin \theta}$$

$F_{fr} - ? \xrightarrow{F_x}$ $F_{fr} - N_T = 0$

$$F_{fr} = \frac{d M g}{L} \frac{\cos \theta}{\sin \theta} \leq N \cdot \mu = \mu M g$$

$$\frac{1}{\mu} \frac{d}{L} \leq \frac{\sin \theta}{\cos \theta}$$

$$\tan \theta \geq \frac{1}{\mu} \frac{d}{L}$$