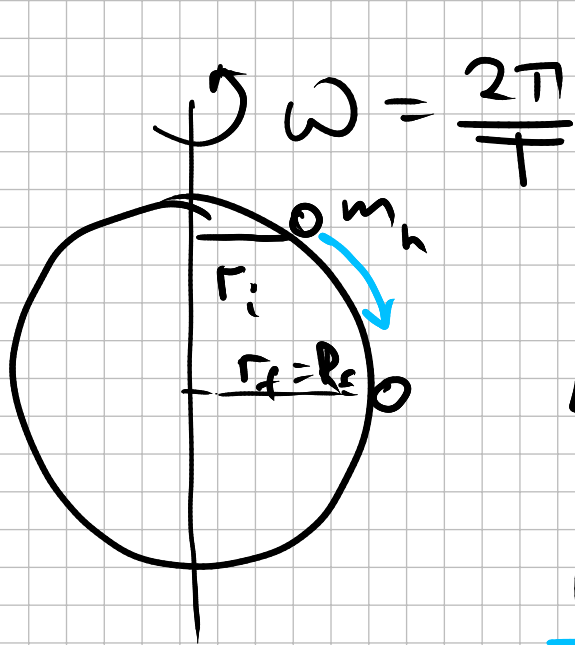


Angular momentum conservation

$$\frac{d\vec{L}}{dt} = \vec{\sum} \text{all external forces}$$



$$\frac{d\vec{L}}{dt} = 0$$

$$L = I_i \omega_i = I_f \omega_f$$

$$(I_E + I_{h_i}) \omega_i = (I_E + I_{h_f}) \omega_f$$

$\underbrace{\hspace{10em}}_{m_i \cdot r_i^2} \qquad \underbrace{\hspace{10em}}_{m_i \cdot r_f^2}$

$$\frac{2}{5} M R_E^2$$

$$I_E = \frac{2}{5} M R_E^2 = \frac{2}{5} (5.9 \cdot 10^{24} \text{ kg}) \cdot (6.378 \cdot 10^6 \text{ m})^2$$

$$\Gamma_i = 0$$

$$\Gamma_f = R_E = 6.378 \cdot 10^6 \text{ m}$$

$$\frac{\omega_f}{\omega_i} = \frac{I_E + I_{hi} = 0 \leftarrow \Gamma_i = 0}{I_E + I_{hf}}$$

$$\frac{2\pi}{T_i} \left(\frac{2\pi}{T_f} \right) \frac{\omega_i}{\omega_f} = \frac{I_E + I_{hf}}{I_E + I_{hi}} = \frac{T_f}{T_i} = \frac{T_i + \Delta T}{T_i}$$

$$\frac{\cancel{I_E} \left(1 + \frac{I_{hf}}{\cancel{I_E}} \right)}{\cancel{I_E} \left(1 + \frac{I_{hi}}{\cancel{I_E}} \right)} = \frac{\cancel{T_i}}{\cancel{T_i}} \left(1 + \frac{\Delta T}{\cancel{T_i}} \right)$$

$$\frac{1}{1+x} \text{ (where } x \ll 1) \approx 1-x$$

$$\left(1 + \frac{I_{hf}}{I_E}\right) \left(1 - \frac{I_{hi}}{I_E}\right) = 1 + \frac{\Delta T}{T_i}$$

$$\cancel{1} + \frac{I_{hf}}{I_E} - \frac{I_{hi}}{I_E} - \frac{I_{hf} I_{hi}}{I_E \cdot I_E} = \cancel{1} + \frac{\Delta T}{T_i}$$

$$\Delta T = T_i \cdot \left(\frac{I_{hf} - I_{hi}}{I_E} \right)$$

$$= 24 \cdot 3600 \text{ s} \cdot \frac{4.06 \cdot 10^{15} - 0}{9.6 \cdot 10^{32}} =$$

$$= 3.6 \cdot 10^{-18} \text{ s}$$

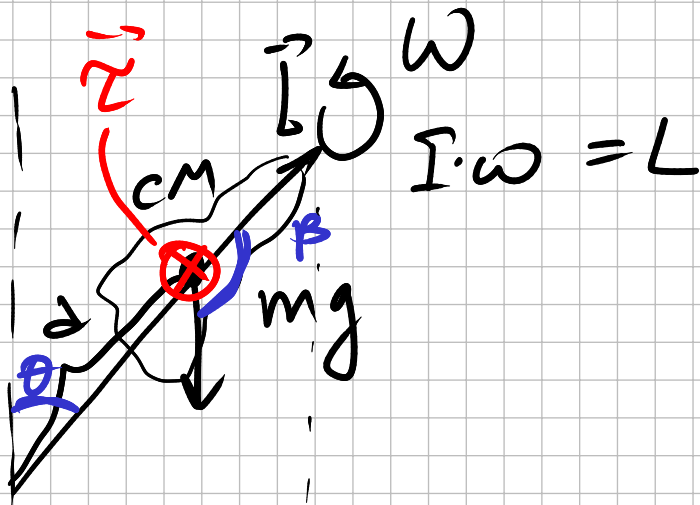
Gyroscope precession

$$\tau = \vec{r} \times \vec{F}$$

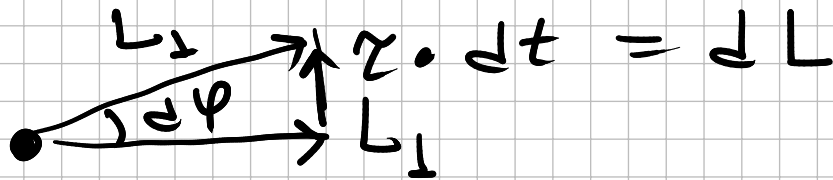
$$L = I\omega$$

$$\frac{dL}{dt} = \tau = d \cdot mg \cdot \sin\theta$$

//
sinθ



Top view



$$d\phi = \frac{dL}{L_1} = \frac{\tau \cdot dt}{L_1} = \frac{d \cdot mg \cdot \sin\theta \cdot dt}{L_1 \cdot \sin\theta}$$

Precession speed

$$\frac{d\phi}{dt}$$

$$= \omega_{\text{Precession}}$$

$$\frac{d \cdot m g}{L}$$

=

$$\frac{d \cdot m g}{I \cdot \omega}$$