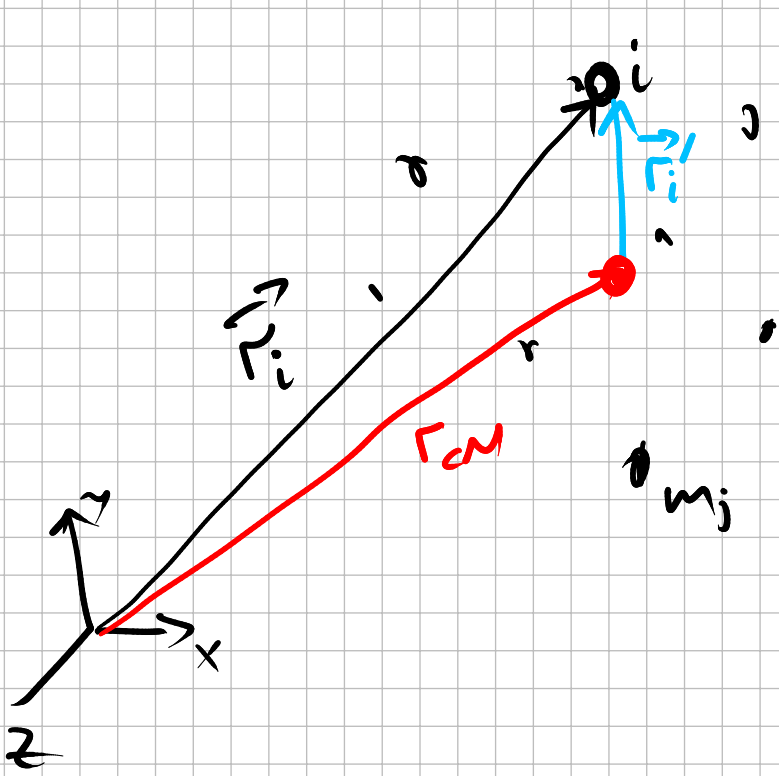


Center of mass

$$\vec{F}_{\text{ext net}} = \frac{d\vec{p}}{dt} = M_{\text{tot}} \cdot \frac{d^2}{dt^2} \vec{r}_{\text{cm}} = M_{\text{TOT}} \cdot \vec{a}_{\text{cm}}$$

$$M_{\text{tot}} = \sum_i m_i$$

$$\vec{r}_{\text{cm}} = \frac{\sum_i m_i \cdot \vec{r}_i}{M_{\text{tot}}}$$



$$\vec{F}_{ext} = \frac{d}{dt} \sum m_i \vec{v}_i = \frac{d}{dt} (M \vec{v}_{cm} + \sum m_i \vec{v}_i')$$

$$= \sum m_i \frac{d^2 \vec{r}_i}{dt^2} = \sum m_i \frac{d^2}{dt^2} (\vec{r}_{cm} + \vec{r}_i')$$

$$= \left(\sum m_i \right) \frac{d^2 \vec{r}_{cm}}{dt^2} + \frac{d^2}{dt^2} \sum m_i \vec{r}_i'$$

$M_{tot} \vec{a}_{cm} + \frac{d^2}{dt^2} \sum m_i \vec{r}_i'$

$$\vec{F}_{ext} = M_{tot} \vec{a}_{cm} + \frac{d}{dt} \sum m_i \vec{v}_i' = 0$$

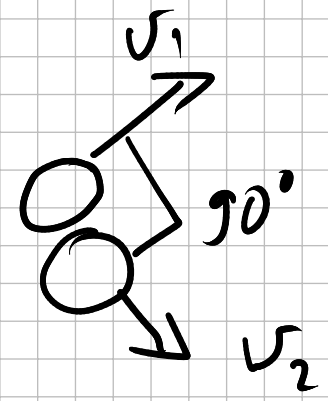
$\vec{F}_{ext} = M_{tot} \vec{a}_{cm} = \vec{F}_{ext}$

$$\sum_{i=1}^n m_i \vec{p}_i' = 0$$

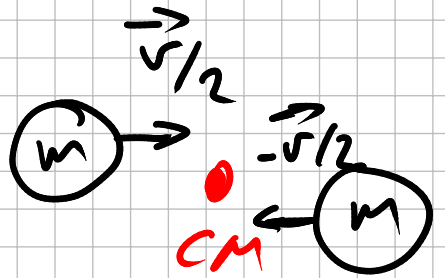
$$\Rightarrow \sum_{i=1}^n m_i \vec{p}_i' = 0$$

in C.M.
system of coordinates

ex:

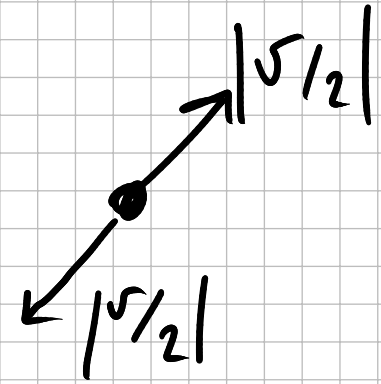


C.M.

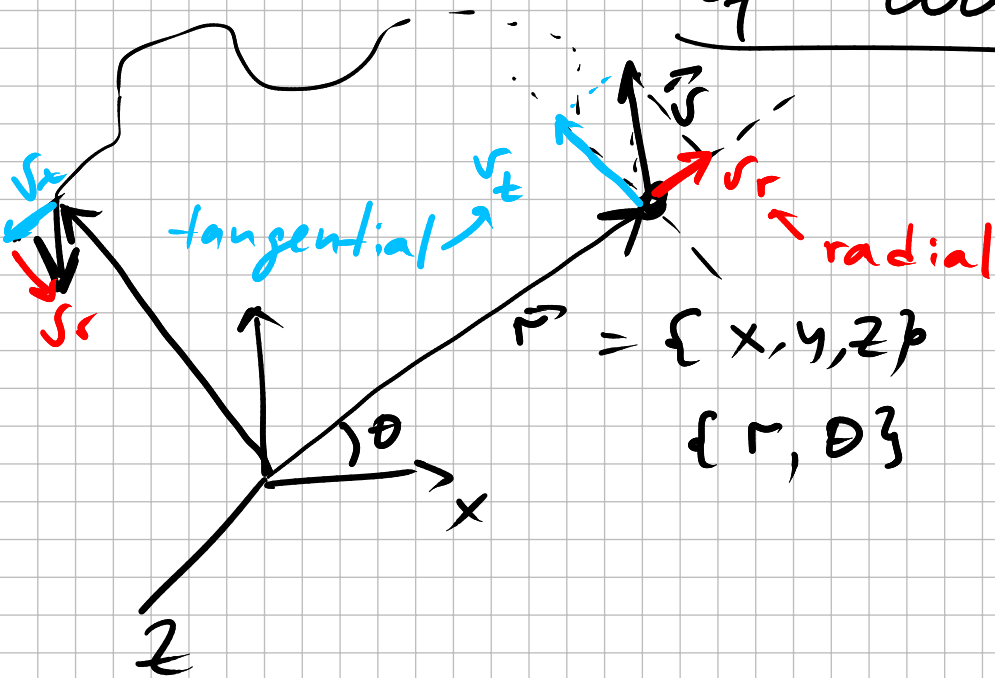


CM:

$$\sum p_i = \frac{M}{2} \frac{v_1}{2} + m \cdot \frac{v_2}{2}$$



Polar / spherical system of coordinates



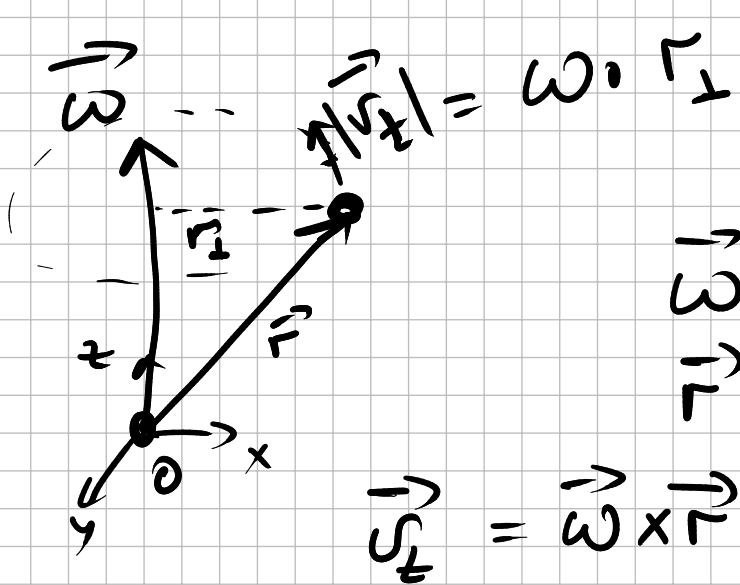
$$\vec{v} = \{v_x, v_y, v_z\}$$

$$= \{v_r, v_t\}$$

$$\{v_r, \omega \cdot r\}$$

$$\vec{r} = \{x, y, z\}$$

$$\{r, \theta\}$$



$$\vec{v}_t = \vec{\omega} \times \vec{r}$$

$$= \{\hat{i}, \hat{j}, \hat{k}\}$$

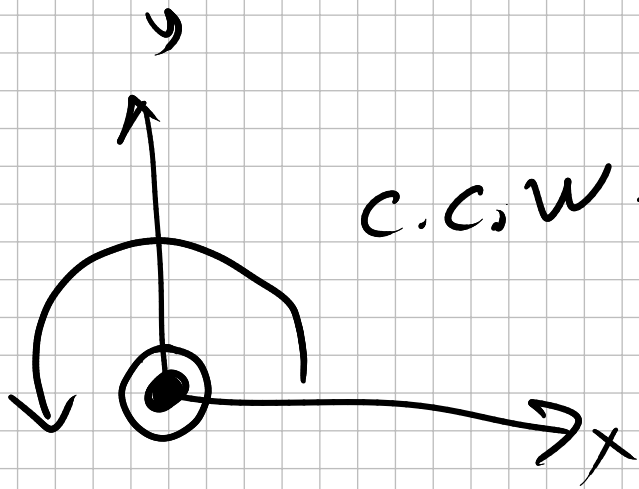
$$= \{\omega_x, \omega_y, \omega_z\}$$

$$= \{x, y, z\}$$

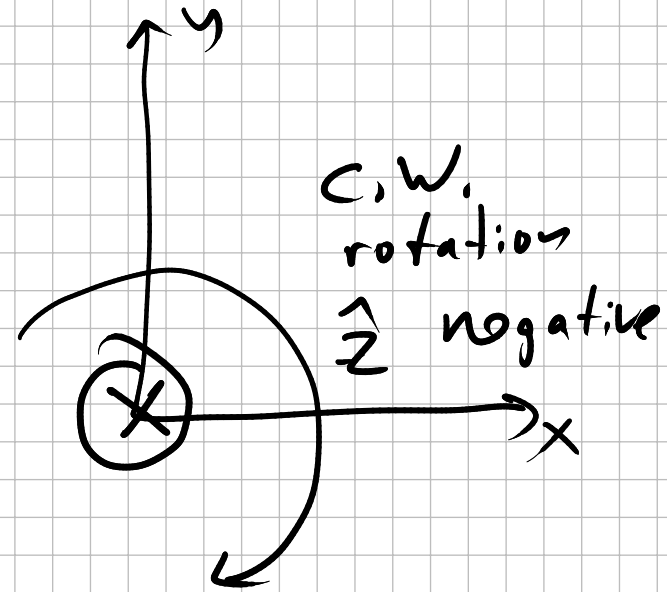
$$\vec{v}_t = \vec{\omega} \times \vec{r}$$

vector
product

$$\vec{\omega} \times \vec{r} = \hat{i} (\omega_y \cdot z - \omega_z \cdot y) \\ + \hat{j} (\omega_z \cdot x - \omega_x \cdot z) \\ + \hat{k} (\omega_x \cdot y - \omega_y \cdot x)$$



C.C.W. $\Rightarrow \hat{z}$ positive



C.W. rotation
 \hat{z} negative