

2nd Newton's law

$$\Rightarrow m\vec{a} = \vec{F}_{\text{net}} = \vec{T} + \vec{F}_g$$

$$\begin{cases} x: m\overset{-a}{a}_x = T_x + \cancel{F_{gx}} \\ y: \cancel{mgy} = T_y + \cancel{F_{gy}} \end{cases}$$

0 by construction

$$\begin{cases} x: -ma = -T \sin \theta \\ y: 0 = T \cos \theta + (-mg) \end{cases}$$

$$\Rightarrow T = \frac{mg}{\cos \theta}$$

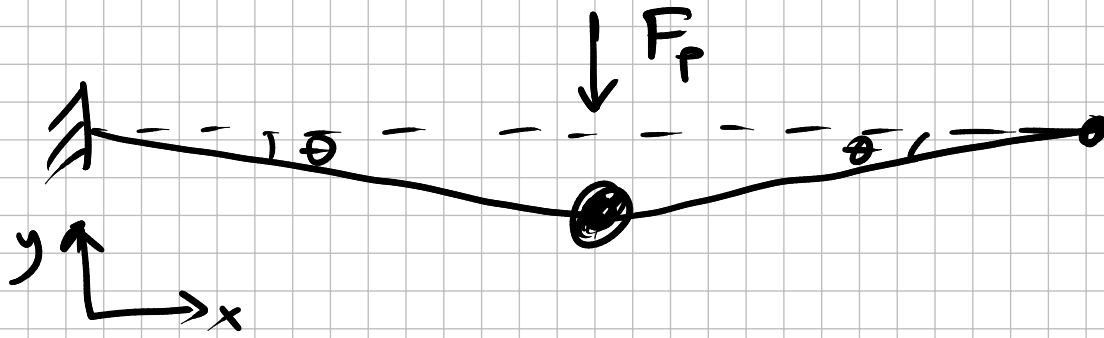
$$-ma = -\frac{mg}{\cos \theta} \sin \theta$$

$$a = g \tan \theta$$

if $\theta = 45^\circ \Rightarrow$

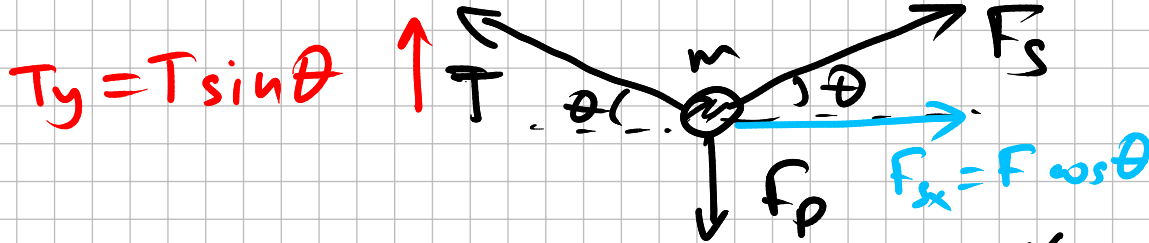
$$a = g \cdot \tan 45^\circ = g$$

Ex



b/s everything
0 is static

$$\begin{aligned} m\vec{a} &= \vec{F}_{\text{ext}} = \\ &= \vec{F}_p + \vec{F}_s + \vec{T} \end{aligned}$$



$$\vec{0} = \vec{F}_p + \vec{F}_s + \vec{T}$$

x: $0 = F_{px} + F_{sx} + T_x$

y: $0 = F_{py} + F_{sy} + T_y$

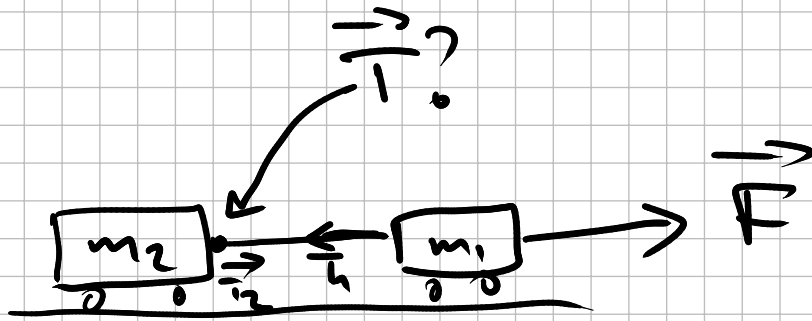
$$0 = -F_p + F_s \sin\theta + T \sin\theta$$

x: $T_x = -F_{sx}$
 $-T \cos\theta = -F_s \cos\theta$

$$F_p = 2 F_s \sin\theta$$

$$F_s = \frac{F_p}{2 \sin\theta}$$

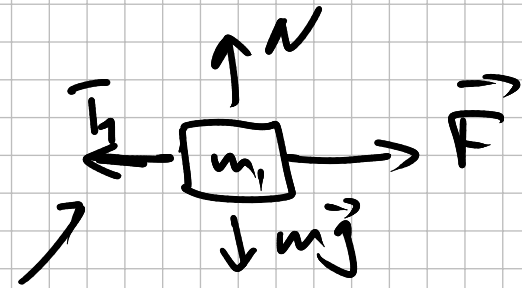
Applic. of 3rd Newton's law



No friction force

$Q^?$

$$1: m_1 \vec{a}_1 = \vec{F} + \cancel{\vec{N}} + \cancel{m_1 \vec{g}} + \vec{T}_1$$



3rd Newton's law

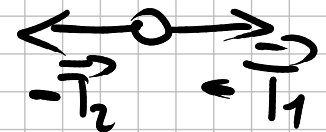
$$2: m_2 \vec{a}_2 = \vec{T}_2$$

3rd law



$$3 \text{ (rope)} \quad m_{\text{rope}} \vec{a}_{\text{rope}} = \ominus \vec{T}_2 \ominus \vec{T}_1$$

$$x: m_r a_{rx} = -|T_{2x}| + |T_{1x}|$$



if $m_r = 0 \Rightarrow$ Tension is same everywhere in a rope