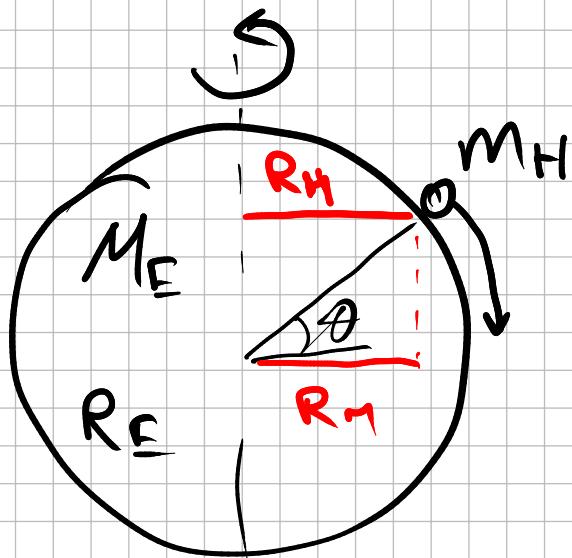


Angular momentum conservation

if $\vec{\tau}_{\text{ext net}} = 0 \Rightarrow \vec{L} = \text{const}$



$$R_H = R_E \cdot \cos\theta$$

$$I = \sum_i m_i r_i^2 =$$

$$= \underbrace{\sum_{i \in E} m_i r_i^2}_{\parallel I_E} + \underbrace{\sum_{i \in H} m_i r_i^2}_{I_H}$$

$$\frac{2}{5} M_E \cdot R_E^2$$

$$\vec{L} = \text{const} = (I_E + I_H) \cdot \omega$$

$$(I_E + I_{Hg}) \omega_i = (I_E + I_{Hf}) \omega_f$$

//

$$\frac{2\pi}{T_i}$$

$\frac{2\pi}{T_f}$

~~$$\frac{T_i}{2\pi} \frac{1}{I_E + I_{Hg}} = \frac{T_f}{2\pi} \frac{1}{I_E + I_{Hf}}$$~~

$$T_f = \frac{I_E + I_{Hf}}{I_E + I_{Hg}} \cdot T_i$$

$$\Delta T = T_f - T_i = \left(\frac{I_E + I_{Hf}}{I_E + I_{Hg}} - 1 \right) T_i$$

$$\Delta T = \left[\frac{\cancel{I_E} \left(1 + \frac{I_{M_f}}{I_E} \right)}{\cancel{I_E} \left(1 + \frac{I_{M_i}}{I_E} \right)} - 1 \right] T_i$$

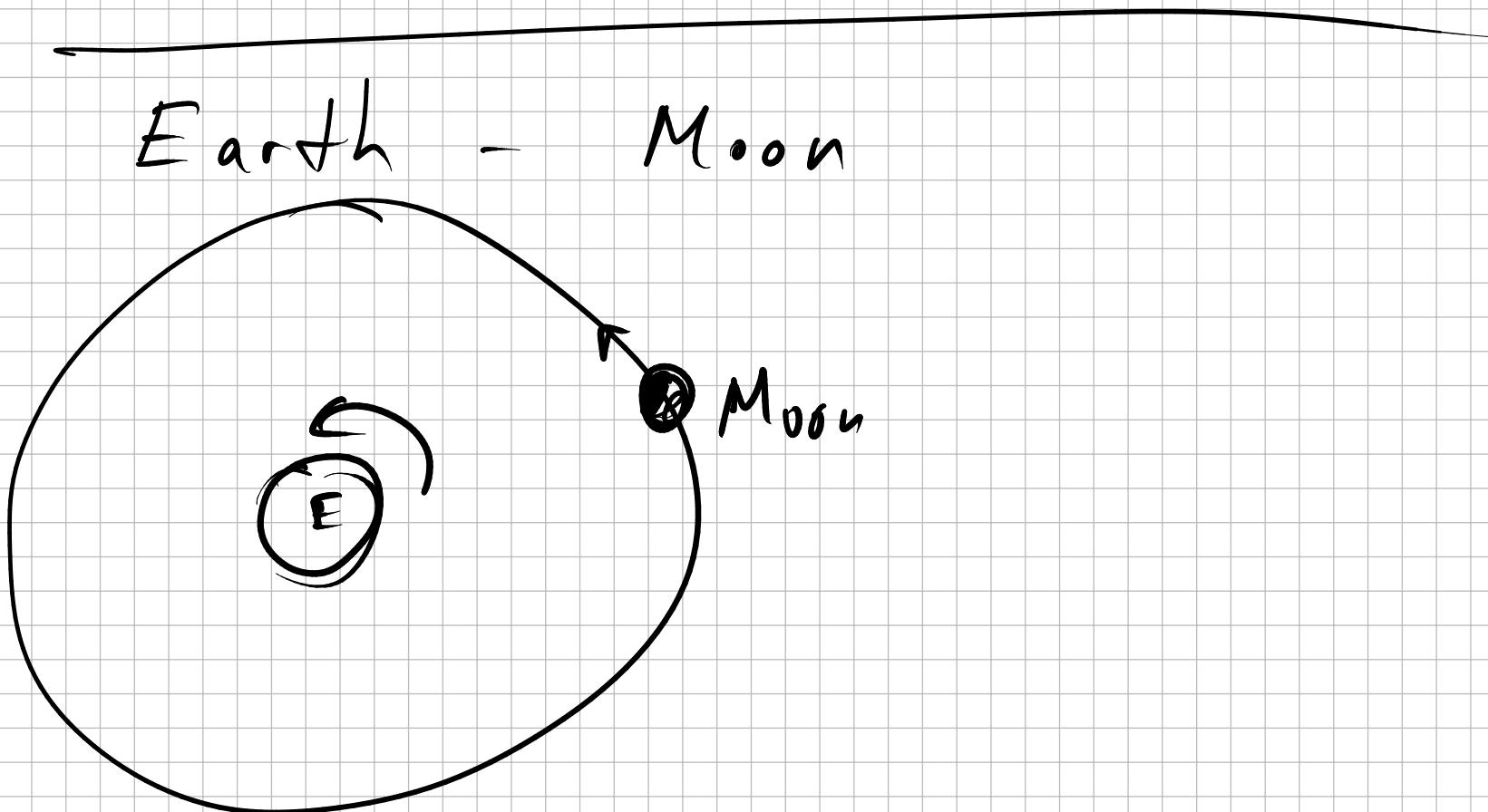
~~$\frac{1}{1+x}$~~ $\xrightarrow{x \rightarrow 0} \approx 1 + x$ *

$$\Delta T = \left[\left(1 + \frac{I_{M_f}}{I_E} \right) \left(1 - \frac{I_{M_i}}{I_E} \right) - 1 \right] T_i$$

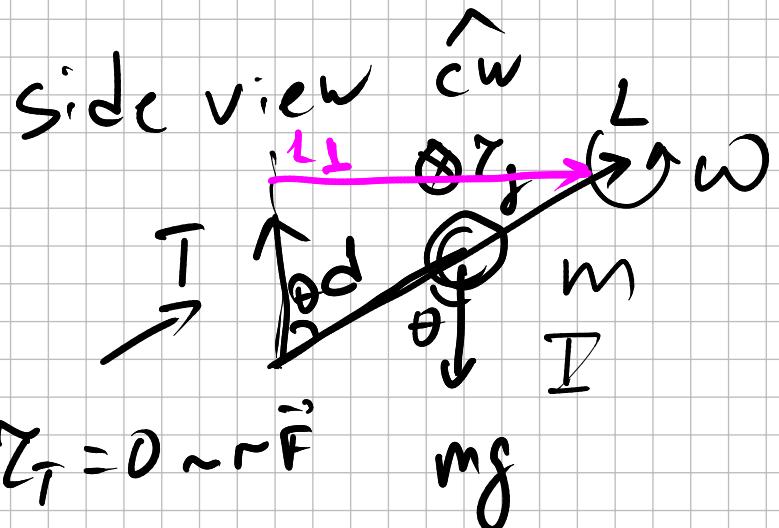
$$= \left[1 + \frac{I_{M_f}}{I_E} - \frac{I_{M_i}}{I_E} + \frac{I_{M_i} I_{M_f}}{I_E} - 1 \right] T_i$$

$$= \frac{I_{M_f} - I_{M_i}}{I_E} \cdot T_i = \frac{m_H R_E^2 - m_M R_E^2 \cos \theta}{\frac{2}{3} M_E R_E^2} \cdot T_i$$

$$2T_i \cdot \frac{5}{2} \frac{m_m}{M_E} \sin^2 \theta \approx 3.6 \cdot 10^{-17} \text{ s}$$

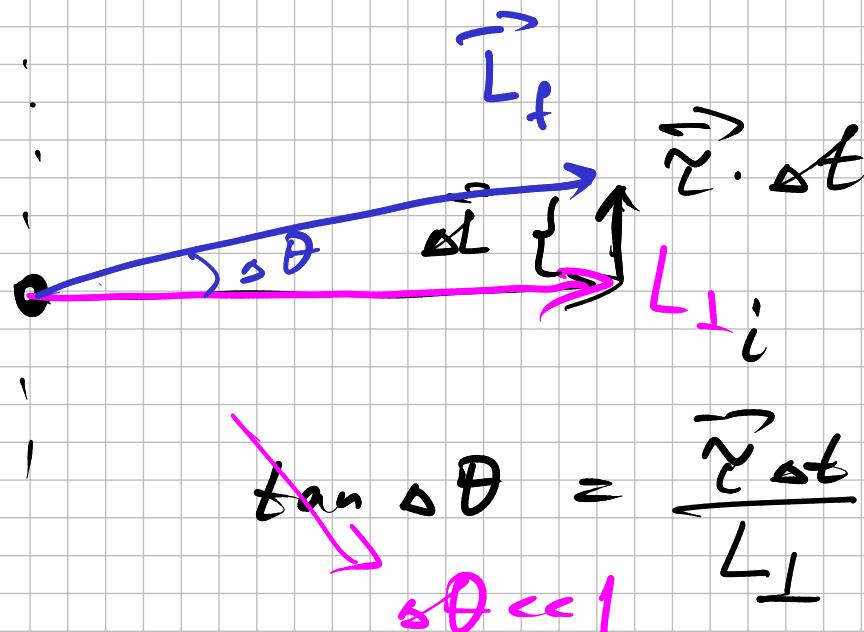


Gyroscope Precession



$$\frac{d\vec{L}}{dt} = \vec{\tau}_{ext} = \vec{\tau}_g = d \cdot mg \cdot \sin\theta \cdot \hat{cw}$$

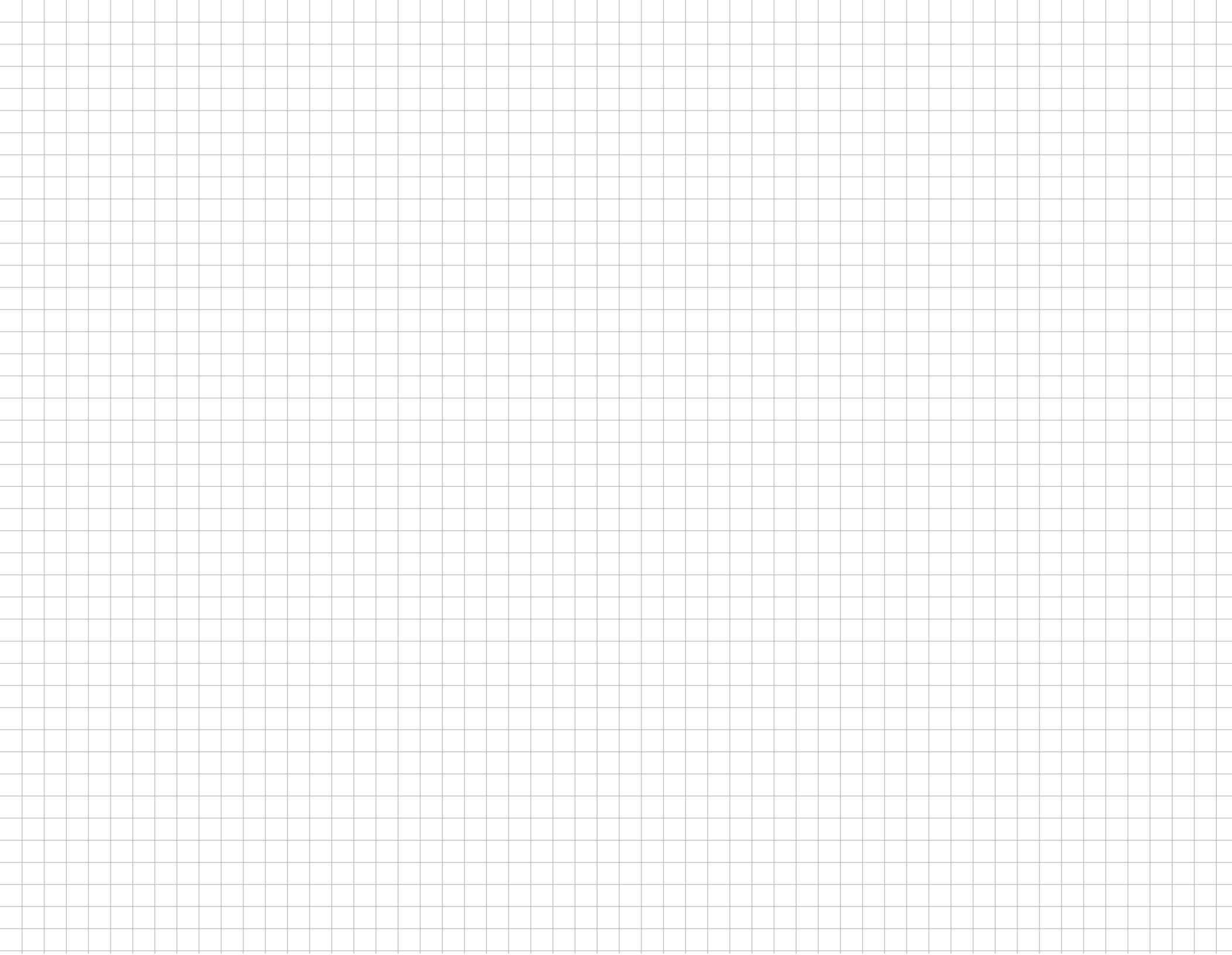
Top view



$$\omega_p = \frac{\Delta\theta}{\Delta t} = \frac{\vec{\tau} \cdot \delta t}{\delta t \cdot L_\perp}$$

$$\geq \frac{d \cdot mg \cdot \sin\theta}{I \cdot \omega \cdot \sin\theta}$$

$$\boxed{\omega_p = \frac{d \cdot mg}{I \cdot \omega}}$$



$$M_e = 5,9 \cdot 10^{24} \text{ kg}$$

$$R_e = 6.378 \cdot 10^6 \text{ m}$$

