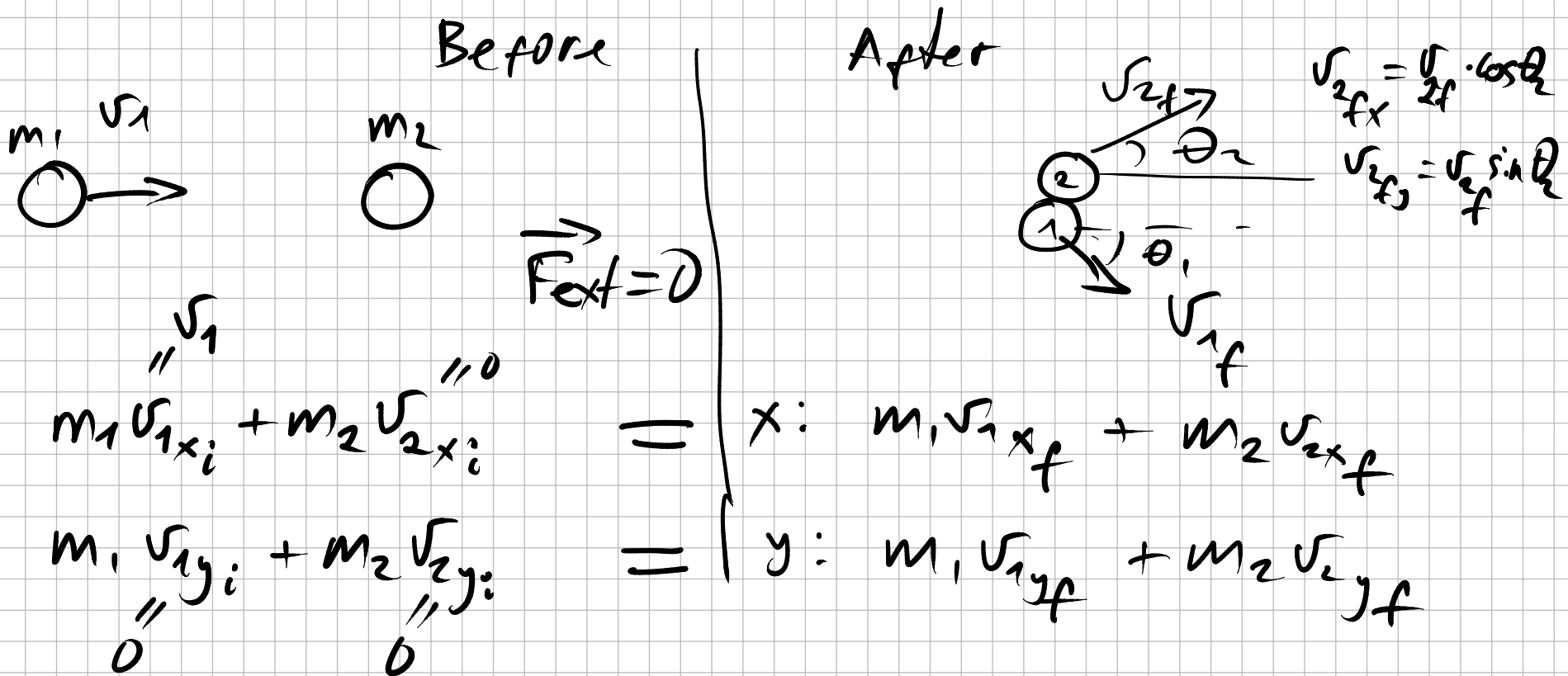


# Linear momentum in 3D

$$\vec{F}_{\text{ext}} = \frac{d\vec{P}}{dt}$$

$$\vec{P} = \sum_i m_i \vec{v}_i$$

if  $\vec{F}_{\text{ext}} = 0 \Rightarrow \vec{P}$  is a constant  
i.e. conserves



$$x: \quad m_1 v_1 = m_1 v_{1f} \cdot \cos \theta_1 + m_2 v_{2f} \cdot \cos \theta_2$$

$$y: \quad 0 = -m_1 v_{1f} \cdot \sin \theta_1 + m_2 v_{2f} \sin \theta_2$$

Assuming elastic collision

$\Rightarrow$  Energy conserved

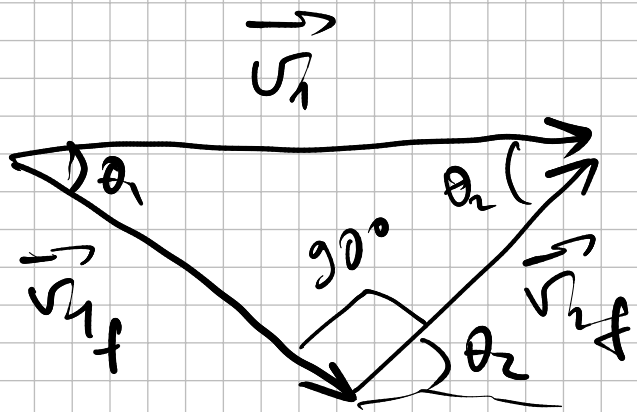
$$\underbrace{\frac{m_1 v_1^2}{2} + \frac{m_2 v_2^2}{2}}_{\text{before}} = \frac{m_1 v_{1f}^2}{2} + \frac{m_2 v_{2f}^2}{2}$$

Assuming  $m_1 = m_2 = m$

$$x: \quad v_1 = v_{1f} \cos \theta_1 + v_{2f} \cos \theta_2$$

$$y: \quad 0 = -v_{1f} \sin \theta_1 + v_{2f} \sin \theta_2$$

$$E: \quad v_1^2 = v_{1f}^2 + v_{2f}^2$$

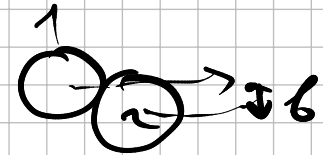


momentum  
conservation

$$\theta_1 + \theta_2 = 90^\circ$$

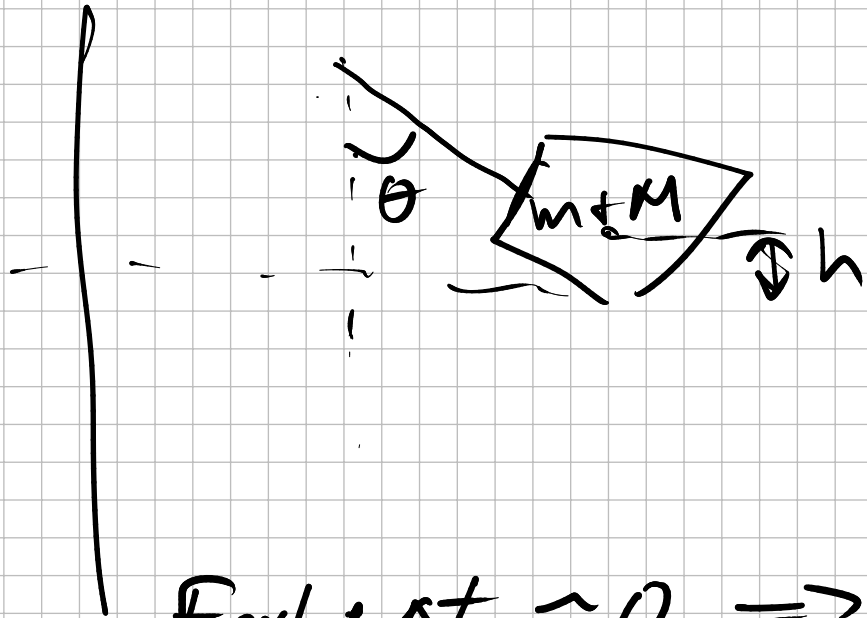
$$v_{1f} = v_1 \cdot \cos \theta_1 = v_1 \sin \theta_2$$

$$v_{2f} = v_1 \cdot \sin \theta_1 = v_1 \cos \theta_2$$





$$\Delta t \approx 0 \Rightarrow$$



$$F_{ext} \cdot \Delta t \approx 0 \Rightarrow P_{conserved}$$

Right after collision

$$x: m v + M \cdot 0$$

$$= m v_f + M \cdot v_f$$

$$y: 0 + 0 = 0 + 0$$

embedding the bullet

$$v_f \approx \frac{m v}{m + M}$$

Collision does not need to preserve Energy

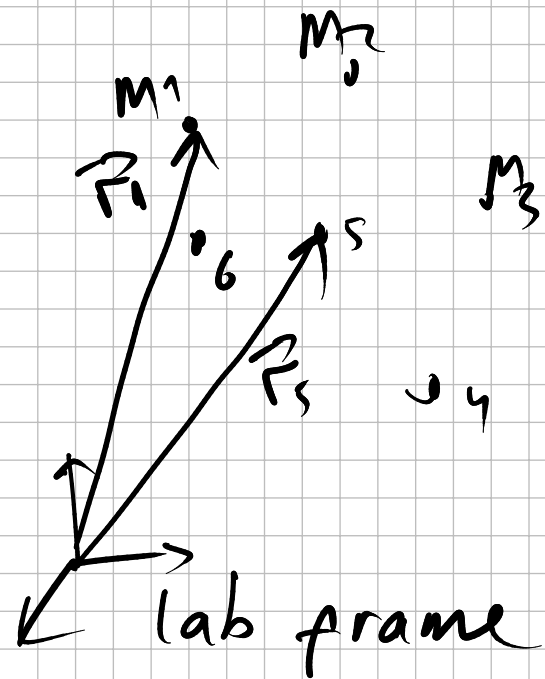
After collision energy preserved

$$\frac{m v_f^2}{2} + \frac{M v_f^2}{2} = (m+M) g h$$

~~$$(m+M) \frac{v_f^2}{2} = (m+M) g h$$~~

$$\left( \frac{m}{M+m} v \right)^2 \frac{1}{2} = g h$$

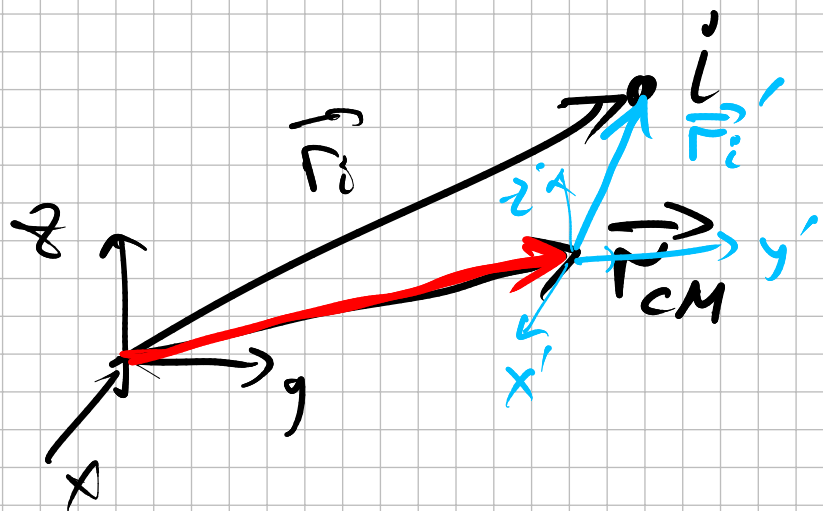
# Center of mass



$$M_{\text{tot}} = \sum_i m_i$$

$$\vec{r}_{\text{CM}} = \frac{\sum_i m_i \vec{r}_i}{M_{\text{tot}}}$$

center of mass position



$$\vec{r}_i = \vec{r}_{\text{CM}} + \vec{r}'_i$$

$$\vec{F}_{\text{net ext}} = \frac{d\vec{p}}{dt} = \frac{d}{dt} \left( \sum_i m_i \vec{v}_i \right) =$$

$$= \frac{d}{dt} \left( \sum_i m_i \frac{d\vec{r}_i}{dt} \right) =$$

$$= \frac{d}{dt} \cdot \frac{d}{dt} \left( \sum_i m_i \vec{r}_i \right) \frac{M_{\text{tot}}}{M_{\text{tot}}} =$$

$$= M_{\text{tot}} \cdot \frac{d^2}{dt^2} \vec{r}_{\text{cm}} =$$

$$\vec{F}_{\text{net ext}} = M_{\text{tot}} \vec{a}_{\text{cm}}$$