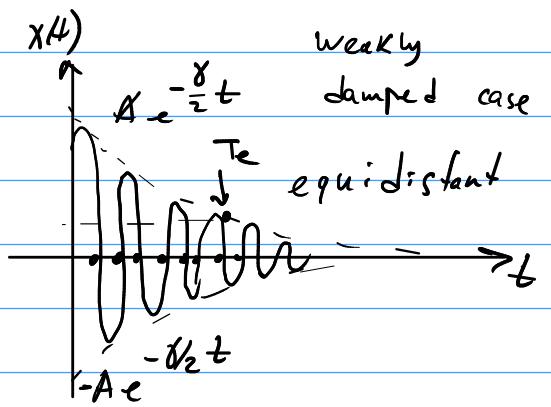


Damped oscillations

$$\ddot{x} = -\omega_0^2 x - \gamma \dot{x}$$

$$x(t) = \underbrace{A_0 e^{-\frac{\gamma}{2}t}}_{A(t)} \cdot \cos(\omega_0 t + \varphi)$$

$$A(T_e) = \frac{A_0}{e} = A_0 e^{-\frac{\gamma}{2}T_e}$$



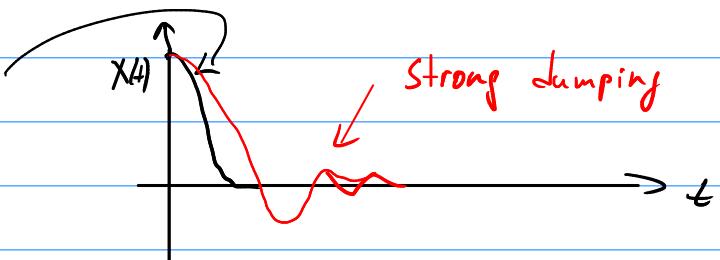
$$\Rightarrow -1 = -\frac{\gamma}{2} T_e = -\frac{\gamma}{2} T \cdot N$$

$$\gamma \ll \omega_0$$

$$1 = \frac{\gamma}{2} T \cdot N = \frac{\gamma}{2} \frac{2\pi}{\omega_0} N = \frac{\gamma \pi}{\omega_0} N = 1$$

$$\boxed{N = \frac{1}{\pi} \frac{\omega_0}{\gamma} = \frac{1}{\pi} Q, \quad Q = \frac{\omega_0}{\gamma}}$$

Over damped

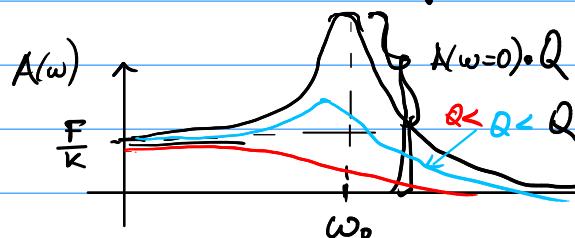


Driven oscillation

$$\ddot{x} = -\omega_0^2 x - \gamma \dot{x} + \frac{F}{m} \cos(\omega t)$$

$$x(t) = A(\omega) \cos(\omega t + \varphi)$$

$$A(\omega) = \frac{F}{m} \sqrt{\frac{1}{(\omega^2 - \omega_0^2)^2 + (\gamma \cdot \omega)^2}}$$

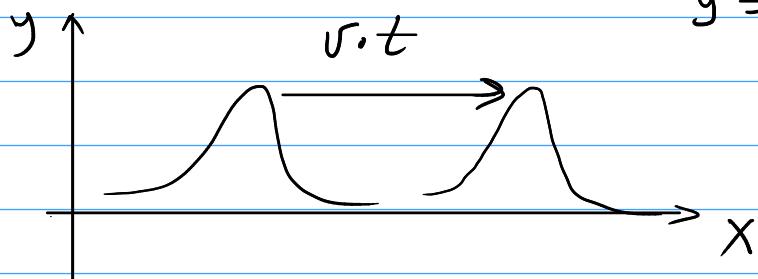


$$A(\omega) = \frac{F}{m} \frac{1}{\omega_0^2} = \frac{F}{m k} \frac{1}{\omega_0^2}$$

$$A(\omega = \omega_0) = \frac{F}{m} \frac{1}{\sqrt{(\gamma \cdot \omega)^2}} = \frac{F Q}{m \omega_0^2}$$

$$R = \frac{\omega_0}{Q}$$

Pulses



$$y = f(x - v_x t)$$

$$= f(x - v_x t)$$

$$y(x, t) = y(u), \quad u = x - v_x t$$

$$\frac{\partial y}{\partial t} = \underbrace{\left(\frac{dy}{du} \right)}_{y'} \cdot \frac{\partial u}{\partial t} = y' \cdot \frac{\partial(x - v_x t)}{\partial t} = y'(-v_x)$$

$$\frac{\partial}{\partial t} \left(\frac{\partial y}{\partial t} \right) = y'' = \frac{\partial^2 y}{\partial u^2}$$

$$\frac{\partial y}{\partial x} = \left(\frac{dy}{du} \right) \left(\frac{\partial u}{\partial x} \right) = y' \frac{\partial(x - v_x t)}{\partial x} = y' \cdot 1$$

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial y}{\partial x} \right) = y''$$

$$\frac{1}{v_x^2} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 y}{\partial x^2}$$

Pulse propagation
equation

$$v_x = \sqrt{\frac{F_T}{M}}$$

← tension

$$M = \frac{\Delta m}{\Delta x}$$

$\frac{\Delta m}{\Delta x}$

linear mass density