

$$T = mg \frac{L}{d \cdot \sin \theta} > mg$$

$$\sum \vec{F}_i = 0 = \vec{F}_w + \vec{T} + m\vec{g}$$

$$\sum \vec{\tau}_i = 0$$

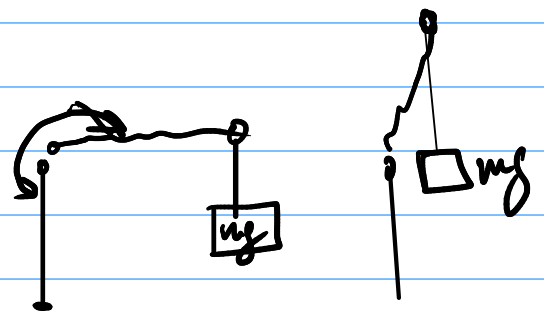
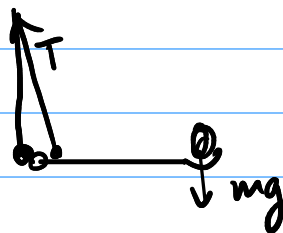
$$\text{W.R.A: } \sum \vec{\tau}_i = \vec{\tau}_w + \vec{\tau}_T + \vec{\tau}_g$$

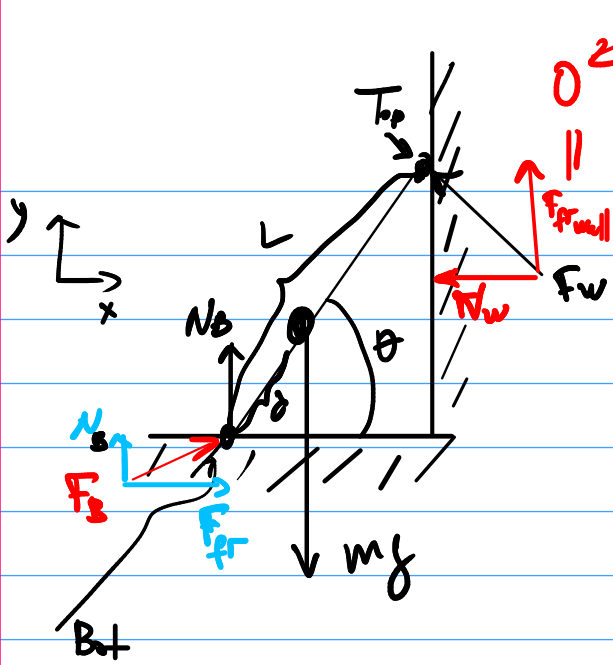
$$x: \quad \underline{\sum F_x = 0 = F_{wx} + T_x + mg_x = F_{wx} - T \cdot \cos \theta + 0}$$

$$y: \quad \underline{\sum F_y = 0 = F_{wy} + T_y + (-mg)} \quad \left. \begin{array}{l} F_{wx} = T \cos \theta = mg \frac{L}{d} \frac{\cos \theta}{\sin \theta} \\ F_{wy} = mg - T \sin \theta = mg - mg \frac{L}{d} \frac{\sin \theta}{\sin \theta} \end{array} \right\}$$

$$F_{wy} = mg - T_y = mg - T \cdot \sin \theta = mg - mg \frac{L}{d} \frac{\sin \theta}{\sin \theta}$$

$$F_{wy} = mg \left( 1 - \frac{L}{d} \right) < 0$$





Forced

$$\sum \vec{\tau}_i = \vec{\tau}_g + \vec{\tau}_B + \vec{\tau}_w = 0$$

$$\sum \vec{F}_i = 0 = F_B + F_g + F_w$$

$$x: \sum F_x = 0 + N_{wx} + F_{frx} = \\ = N_{wx} + F_{fr} = 0$$

$$y: 0 = N_B - mg \\ \boxed{N_B = mg}$$

$$\text{w.r. B} : \sum \vec{\tau}_i = 0 = mg \cdot d \cdot \cos \theta + L N_w \cdot \sin \theta \hat{ccw}$$