

Ordinary Differential equations continued

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Lecture 20

Recall the Euler's method

We are solving

$$\vec{y}' = \vec{f}(x, \vec{y})$$

There is the exact way to write the solution

$$\vec{y}(x) = \vec{y}_0 + \int_{x_0}^x \vec{f}(x, \vec{y}) dx$$

The Euler's method assumes that the $\vec{f}(x, \vec{y})$ is constant over a small interval of $(x, x + h)$

$$\vec{y}(x_{i+1}) = \vec{y}(x_i + h) = \vec{y}(x_i) + \vec{f}(x_i, \vec{y}_i)h + \mathcal{O}(h)$$

The second-order Runge-Kutta method

Using the multi-variable calculus and the Taylor expansion

$$\begin{aligned}\vec{y}(x_{i+1}) &= \vec{y}(x_i + h) = \\ &= \vec{y}(x_i) + C_0 \vec{f}(x_i, \vec{y}_i)h + C_1 \vec{f}(x_i + ph, \vec{y}_i + qh\vec{f}(x_i, \vec{y}_i))h + \mathcal{O}(h^3)\end{aligned}$$

where $C_0 + C_1 = 1$, $C_1 p = 1/2$, $C_1 q = 1/2$ see¹.

There are a lot of possible choices of parameters C_0 , C_1 , p , and q . One choice generally has no advantage over another.

One intuitive choice is $C_0 = 0$, $C_1 = 1$, $p = 1/2$, and $q = 1/2$ gives

Modified Euler's method or midpoint method (error $\mathcal{O}(h^3)$)

$$k_1 = h\vec{f}(x_i, \vec{y}_i)$$

$$k_2 = h\vec{f}\left(x_i + \frac{h}{2}, \vec{y}_i + \frac{1}{2}k_1\right)$$

$$\vec{y}(x_i + h) = \vec{y}_i + k_2$$

¹Holistic Numerical Methods

The forth-order Runge-Kutta method

Higher order expansion leads to another possible choice

The forth-order Runge-Kutta method with truncation error $\mathcal{O}(h^5)$

$$k_1 = h\vec{f}(x_i, \vec{y}_i)$$

$$k_2 = h\vec{f}\left(x_i + \frac{h}{2}, \vec{y}_i + \frac{1}{2}k_1\right)$$

$$k_3 = h\vec{f}\left(x_i + \frac{h}{2}, \vec{y}_i + \frac{1}{2}k_2\right)$$

$$k_4 = h\vec{f}(x_i + h, \vec{y}_i + k_3)$$

$$\vec{y}(x_i + h) = \vec{y}_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

Matlab built-in ODEs solvers

Have a look in help files for ODEs. In particular, pay attention to

- `ode45` - adaptive explicit 4th order Runge-Kutta method (good default method)
- `ode23` - adaptive explicit 2nd order Runge-Kutta method
- `ode113` - “stiff” problem solver
- and others

Adaptive stands for no need to choose h , the algorithm will do it by itself. However, remember the rule about not trusting a computer's choice.

Run `odeexamples` to see some of the demos for ODEs solvers