

# Simulated annealing/Metropolis and genetic optimization

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Lecture 18

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## Nature's way to find a minimum energy

- We see that probing full space permitted by combinatorics is not practical even for a reasonably small size problem.

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## Nature's way to find a minimum energy

- We see that probing full space permitted by combinatorics is not practical even for a reasonably small size problem.
- However, nature seems to handle the problem of the energy minimization without any trouble.
- For example, if you heat up a piece of metal and then **slowly** cool it, i.e. anneal, then the system will reach the minimum energy state.

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## Simulated annealing or modified Metropolis algorithm

Below is modified Metropolis and coworkers' algorithm, suggested in 1953, mimicking the Boltzmann energy distribution law.

- 1 set the temperature to a high value, so  $kT$  is larger than typical energy (merit) function fluctuation.
  - This requires some experiments if you do not know this a priori
- 2 assign a state  $\vec{x}$  and calculate the energy ( $E$ ) at this point
- 3 change, somehow, the old  $\vec{x}$  to generate a new one,  $\vec{x}_{new}$ 
  - $\vec{x}_{new}$  should be somewhat **close/related** to the old optimal  $\vec{x}$
- 4 calculate the energy at the new point  $E_{new} = E(\vec{x})$
- 5 if  $E_{new} < E$  then  $x = x_{new}$  and  $E = E_{new}$ 
  - i.e., we move to the new point of the lower energy
- 6 otherwise, move to the new point with probability  $p = \exp(-(E_{new} - E)/kT)$ 
  - this resembles the Boltzmann energy distribution probability
- 7 decrease the temperature a bit, i.e., keep annealing
- 8 repeat from the step 3 for a given number of cycles
- 9  $\vec{x}$  will hold the local optimal solution

## Simulated annealing/Metropolis algorithm facts

In finite time (limited number of cycles), the algorithm is guaranteed to find only the local minimum.

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There is a theorem which states:

The probability to find the best solution goes to 1, if we run the algorithm for a longer and longer time with a slower and slower rate of cooling.

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Unfortunately, this theorem is of no use since it does not give a recipe of how long to run the algorithm. It is even suggested that it will need more cycles than the brute force combinatorial search.

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- the main challenge is to find a good way to choose a new  $\vec{x}$  to probe

## Backpack problem with Metropolis algorithm

- The main challenge is to find a good routine to generate a new candidate for the  $\vec{x}_{new}$ . We **do not want** to randomly jump to **an arbitrary position** of problem space.
- Recall that  $\vec{x}$  generally looks like  $[0, 1, 1, 0, 1, \dots, 0, 1, 1]$  so lets just randomly toggle/mutate **some** choices/bits
  - note that a random mutation could lead to the overfilled backpack
- The rest is quite straight forward, as long as we remember, that we are looking for the maximum value in the backpack, while the Metropolis algorithm is designed for the merit function minimization. So, we choose our merit function to be the negative value of all items in the backpack. Also, we need to add a **big penalty** for the case of the overfilled backpack.
- See the realization of the algorithm in the `backpack_metropolis.m` file.
- it will find quite a good solution for the "30 items to choose" problem within a second instead of 13 hours of combinatorial search.

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## Genetic algorithm

The idea is taken from nature, which is usually able to find the optimal solution via the natural selection.

This algorithm has many modifications but the main idea is the following

- 1 Generate a population (set of  $\{\vec{x}\}$ ).
  - It is up to you to decide how large this set should be.
- 2 Find the fitness (i.e. merit) function for each member of the population.
- 3 Remove from the pool all but the most fitted.
  - How many should stay is up to the heuristic tweaks.
- 4 From the most fitted (parents) breed a new population (children) to the size of the original population.
- 5 Repeat several times starting from step 2.
- 6 Select the fittest member of your population to be the final solution.

Navigation icons

## How to generate children from parents

As usual, the most important question is the generation of a new  $\vec{x}$ , i.e. a child, from the older ones.

Let's use the recipe provided by nature. We will refer to  $\vec{x}$  as a chromosome or genome.

- 1 choose two parents randomly
- 2 **crossover/recombine** parents chromosomes i.e. take randomly gens (  $\vec{x}$  components) from either parent and assign them to a new child chromosome/genome
- 3 **mutate** (change) randomly some gens

Some algorithm modifications allow parents to be in the new cycle of selection, others eliminate them in the hope to escape from a local minimum.

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## What to expect when using the genetic algorithm

- To find a good solution, you need a large population, since this lets you to explore a larger parameter space. Think about evolution strategies of microbes versus humans. But this in turn leads to a longer computational time for every selection cycle.
- The algorithm is not guaranteed to find the global optimum in finite time.
- A nice feature of the genetic algorithm is that it suits the parallel computation paradigm: you can evaluate the fitness of each child on a different CPU and then compare their fitness.

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