

# Lecture 05

(P1)


Derivation of Kepler's laws.

i.e. classical mechanics at work.

Kepler (1571 - 1630).

In 1609 first two laws

-1- Orbits of the planets are ellipses, sun is at the focus of them &

-2- line connecting a planet and the sun sweeps out equal areas at the same time interval  
  
10 years later

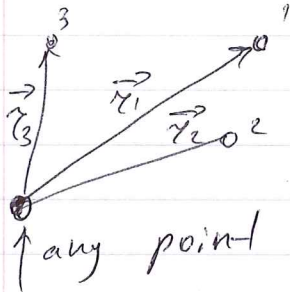
-3-

$P^2 = a^3$   
→ period of the orbit ← average distance of a planet to the sun measured in a.u.

## Classical mechanics

total angular momentum conservation

we have  $N$  particles and no external force



so particles are acting only on themselves

$$L = \sum_{i=1}^N m_i \vec{v}_i \times \vec{r}_i$$

$$\frac{dL}{dt} = \sum [m_i \vec{v}_i \times \vec{v}_i + m_i \vec{v}_i \times \vec{a}_i] =$$

$\vec{v}_i \times \vec{v}_i = 0$

$$= \sum m_i \vec{a}_i \times \vec{r}_i = \sum \vec{F}_i \times \vec{r}_i =$$

$$= \sum_i \left( \sum_{j \neq i} \vec{F}_{ij} \times \vec{r}_i \right) =$$

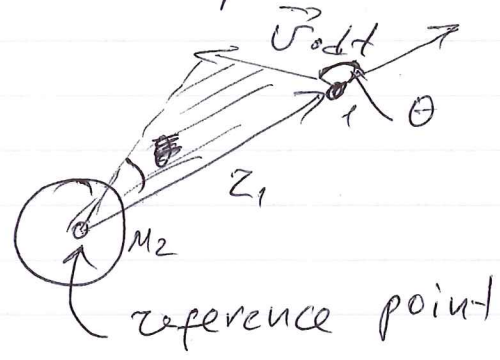
$$= \sum_i \sum_{j \neq i} |\vec{F}_{ij}| \cdot (\vec{r}_i - \vec{r}_j) \times \vec{r}_i =$$

$$= \sum_{\text{pairs of } i \text{ and } j} |\vec{F}_{ij}| \cdot \underbrace{(\vec{r}_i - \vec{r}_j) \times \vec{r}_i}_{= -\vec{r}_j \times \vec{r}_i} - \underbrace{|\vec{F}_{ij}| (\vec{r}_i - \vec{r}_j) \times \vec{r}_j}_{= \vec{r}_i \times \vec{r}_j}$$

$$= \sum_{\text{pairs}} |\vec{F}_{ij}| \cdot \left[ \underbrace{-\vec{r}_j \times \vec{r}_i - \vec{r}_i \times \vec{r}_j}_{\vec{r}_i \times \vec{r}_j} \right] = 0$$

$$\Rightarrow \frac{dL}{dt} = \text{const} \Rightarrow \boxed{L = \text{const}} !$$

One particle around immobile Massive body

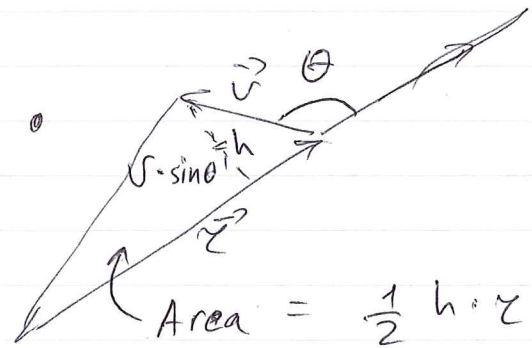


$$L_{\text{total}} = m_1 \vec{v}_1 \times \vec{r}_1 = \text{const}$$

$$\frac{d}{dt} L_{\text{total}} = m_1 (\vec{v}_1 \times \vec{r}_1) \cdot \frac{d}{dt} \vec{r}_1$$

$$= m_1 (\vec{v}_1 \cdot \frac{d}{dt} \vec{r}_1) \times \vec{r}_1 \Rightarrow$$

$$| \frac{d}{dt} L_{\text{total}} | = m_1 \cdot \underbrace{(v_1 \cdot r_1 \cdot \sin \theta)}_{\text{const}} dt$$

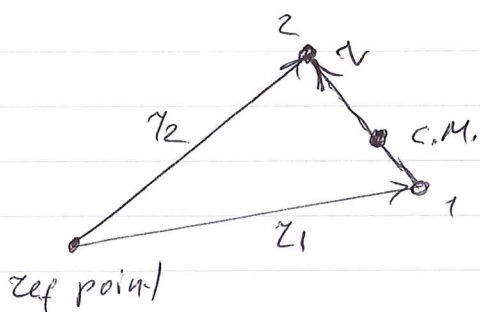


const  
2A  
h

$$\text{Area} = \frac{1}{2} h \cdot r_1 = \frac{1}{2} (v_1 \sin \theta) \cdot r_1$$

So we proved 2nd Kepler's law

Now let's prove 2nd Kepler's law in a more general case of 2 body system



We introduce center of Mass position

$$\vec{r}_{cm} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}$$

note  $\vec{r}_2 = \vec{r}_1 + \vec{r}$

$\vec{r}$   
 vector connecting 1 and 2 going from 1 to 2

$$\vec{r}_{cm} = \frac{m_1 \cdot \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2} = \frac{m_1 \vec{r}_1 + m_2 (\vec{r}_1 + \vec{r})}{m_1 + m_2} =$$

$$= \vec{r}_1 + \frac{m_2}{m_1 + m_2} \vec{r}$$

This prove that the C.M sits on a line connecting 1 and 2

If we move to the reference frame of c.m. than

$$\vec{r}_{1cm} = \vec{r}_1 - \vec{r}_{cm} = - \frac{m_2}{m_1 + m_2} \vec{r} =$$

$$= - \frac{m_2 \cdot m_1}{(m_1 + m_2) \cdot m_1} \vec{r} = -$$

$$M = \frac{m_2 m_1}{m_1 + m_2}$$

$\mu$  - reduced mass

$$\vec{r}_{1cm} = - \frac{M}{m_1} \vec{r}$$

similarly

$$\vec{r}_{2cm} = + \frac{M}{m_2} \vec{r}$$

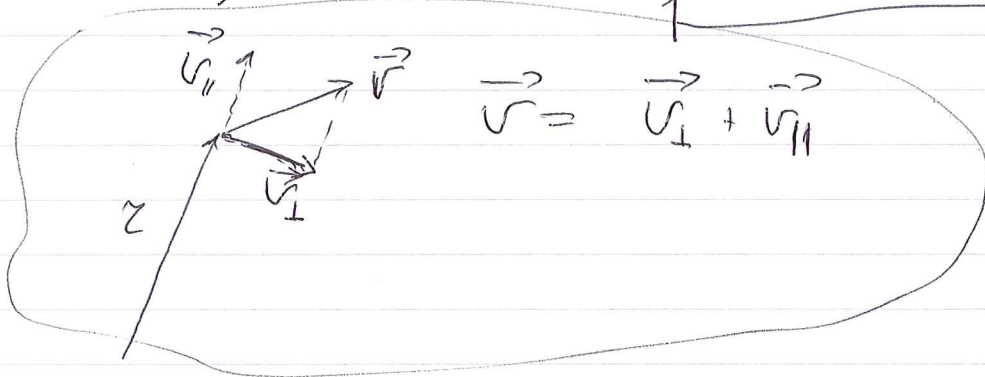


For now on we are always in the c.m. reference frame. So I dropped the c.m. subscript

(PS)

$$\begin{aligned}
 \vec{L} &= m_1 \vec{v}_1 \times \vec{r}_1 + m_2 \vec{v}_2 \times \vec{r}_2 = \\
 &= m_1 \vec{v}_1 \times \left( -\vec{r} \frac{m_1}{m_1} \right) + m_2 \vec{v}_2 \times \left( \vec{r} \frac{m_2}{m_2} \right) = \\
 &= \mu \left( -\vec{v}_1 \times \vec{r} + \vec{v}_2 \times \vec{r} \right) = \\
 &= \mu \left( -\left( \frac{\mu}{m_1} \vec{v}_1 \right) + \left( \frac{\mu}{m_2} \vec{v}_2 \right) \right) \times \vec{r} = \\
 &= \mu \left( \frac{m_2}{m_1+m_2} + \frac{m_1}{m_1+m_2} \right) \vec{v} \times \vec{r} =
 \end{aligned}$$

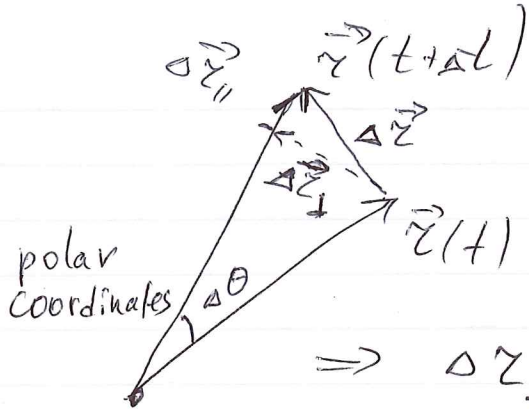
$$= \mu \vec{v} \times \vec{r} = \boxed{\mu \vec{v} \times \vec{r} = L_{\text{total}}}$$



$$\begin{aligned}
 &= \mu (\vec{v}_{\perp} + \vec{v}_{\parallel}) \times \vec{r} = \mu \vec{v}_{\perp} \times \vec{r} + \mu \underbrace{\vec{v}_{\parallel} \times \vec{r}}_{=0} \\
 &= \mu (\vec{v}_{\perp} \cdot \hat{z}) \cdot \hat{z}
 \end{aligned}$$

~~that~~

unit vector  $\hat{z}$  along  $L$  which is  $\perp$  to  $v_{\perp}$  and  $z$



$$\Delta \vec{r} = \Delta \vec{r}_{\perp} + \Delta \vec{r}_{\parallel}$$

$$\Rightarrow \Delta r_{\perp} = r \cdot \Delta \theta$$

$$\boxed{v_{\perp} = r \dot{\theta}}$$

$$\Rightarrow v_{\perp} = \frac{\Delta r_{\perp}}{\Delta t} \xrightarrow{\Delta t \rightarrow 0} \frac{r \Delta \theta}{\Delta t} = r \dot{\theta}$$

$$\Rightarrow |L| = \mu r \cdot \dot{\theta} \cdot r = \mu r^2 \dot{\theta} = \mu \cdot 2 \frac{d \text{Area}}{dt} = \text{const}$$

by previous prove

Same 2nd Kepler law.

~~Note~~

Note interesting fact it is true for any system without external forces. We do not care about the nature of the forces between the bodies: gravity, spring, ~~electric~~ Coulomb force.

It is true for planets - sun, but also true for electron - atom, or 2 bodies connected by a thread