

# Ordinary Differential equations continued

Eugeniy E. Mikhailov

The College of William & Mary



Lecture 20

Notes

---

---

---

---

---

---

---

---

## Recall the Euler's method

We are solving

$$\vec{y}' = \vec{f}(x, \vec{y})$$

There is the exact way to write the solution

$$\vec{y}(x) = \int_{x_0}^x \vec{f}(x, \vec{y}) dx$$

The Euler's method assumes that the  $\vec{f}(x, \vec{y})$  is constant over a small interval of  $(x, x + h)$

$$\vec{y}(x_{i+1}) = \vec{y}(x_i + h) = \vec{y}(x_i) + \vec{f}(x_i, \vec{y}_i)h + \mathcal{O}(h^2)$$

Notes

---

---

---

---

---

---

---

---

## The second-order Runge-Kutta method

Using the multi-variable calculus and the Taylor expansion

$$\begin{aligned} \vec{y}(x_{i+1}) &= \vec{y}(x_i + h) = \\ &= \vec{y}(x_i) + C_0 \vec{f}(x_i, \vec{y}_i)h + C_1 \vec{f}(x_i + ph, \vec{y}_i + qh \vec{f}(x_i, \vec{y}_i))h + \mathcal{O}(h^3) \end{aligned}$$

where

$$C_0 + C_1 = 1, \quad C_1 p = 1/2, \quad C_1 q = 1/2$$

There are a lot of possible choices of parameters  $C_0$ ,  $C_1$ ,  $p$ , and  $q$ . One choice generally has no advantage over another. One intuitive choice is  $C_0 = 0$ ,  $C_1 = 1$ ,  $p = 1/2$ , and  $q = 1/2$  gives

### Modified Euler's method or midpoint method (error $\mathcal{O}(h^3)$ )

$$\begin{aligned} k_1 &= h \vec{f}(x_i, \vec{y}_i) \\ k_2 &= h \vec{f}(x_i + \frac{h}{2}, \vec{y}_i + \frac{1}{2} k_1) \\ \vec{y}(x_i + h) &= \vec{y}_i + k_2 \end{aligned}$$

Notes

---

---

---

---

---

---

---

---

## The fourth-order Runge-Kutta method

Higher order expansion leads to another possible choice

### truncation error $\mathcal{O}(h^5)$

$$\begin{aligned} k_1 &= h \vec{f}(x_i, \vec{y}_i) \\ k_2 &= h \vec{f}(x_i + \frac{h}{2}, \vec{y}_i + \frac{1}{2} k_1) \\ k_3 &= h \vec{f}(x_i + \frac{h}{2}, \vec{y}_i + \frac{1}{2} k_2) \\ k_4 &= h \vec{f}(x_i + h, \vec{y}_i + k_3) \\ \vec{y}(x_i + h) &= \vec{y}_i + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4) \end{aligned}$$

Notes

---

---

---

---

---

---

---

---

## Matlab built-in ODEs solvers

Have a look in help files for ODEs. In particular, pay attention to

- `ode45` - adaptive explicit 4th order Runge-Kutta method (good default method)
- `ode23` - adaptive explicit 2nd order Runge-Kutta method
- `ode113` - "stiff" problem solver
- and others

Adaptive stands for no need to choose  $h$ , the algorithm will do it by itself. However, remember the rule about not trusting a computer's choice.

Run `odeexamples` to see some of the demos for ODEs solvers

Notes

---

---

---

---

---

---

---

---

Notes

---

---

---

---

---

---

---

---

Notes

---

---

---

---

---

---

---

---

Notes

---

---

---

---

---

---

---

---