

Root finding

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Lecture 05

Notes

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But it is easy to transform to canonical form with

$$f(x) = h(x) - g(x) = 0$$

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Example

$$3x^3 + 2 = \sin x \rightarrow 3x^3 + 2 - \sin x = 0$$

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A general search algorithm is the following

- make a guess i.e. trial
- make intelligent new guess (x_{i+1}) judging from this trial (x_i)
- continue as long as $|f(x_{i+1})| > \varepsilon_f$ and $|x_{i+1} - x_i| > \varepsilon_x$

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Example

Let's play a simple game:

- some one think of any number between 1 and 100
- I will make a guess
- you provide me with either "less" or "more" depending where is my guess with respect to your number

How many guesses do I need?

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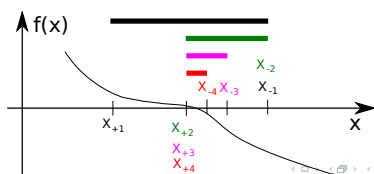
How many guesses do I need? At most 7

Notes

Bisection method pseudo code

Works for any **continuous function** in vicinity of function root

- make initial bracket for search x_+ and x_- such that
 - $f(x_+) > 0$
 - $f(x_-) < 0$
- loop begins
- make new guess value $x_g = (x_+ + x_-)/2$
- if $|f(x_g)| \leq \varepsilon_f$ and $|x_+ - x_g| \leq \varepsilon_x$
stop we found the solution with desired approximation
- otherwise if $f(x_g) > 0$ then $x_+ = x_g$ else $x_- = x_g$
- continue the loop



Notes

Bisection - simplified matlab implementation

```
function x_sol=bisection(f, xn, xp, eps_f, eps_x)
% solving f(x)=0 with bisection method

xg=(xp+xn)/2; % initial guess
fg=f(xg); % initial function evaluation

while ( (abs(fg) > eps_f) & (abs(xg-xp)>eps_x) )
    if (fg>0)
        xp=xg;
    else
        xn=xg;
    end
    xg=(xp+xn)/2; % update guess
    fg=f(xg); % update function evaluation
end
x_sol=xg; % solution is ready
end
```

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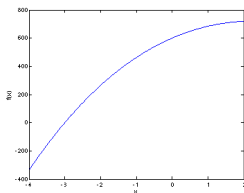
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Bisection - example of use

Let's define simple test function in the file 'function_to_solve.m'

```
function ret=function_to_solve(x)
ret=(x-10)*(x-20)*(x+3);
end
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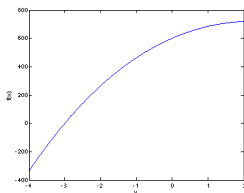
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pay attention to the function handle operator @

```
eps_x=1e-8;
eps_f=1e-6;
x0=bisection(...
    @function_to_solve,...
    -4.1, 2, ...
    eps_f, eps_x)
```

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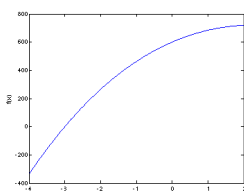
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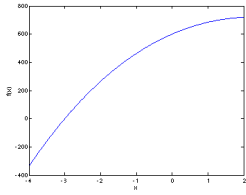
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always cross check results

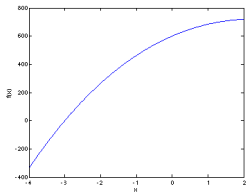
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ans = 3.0631e-07
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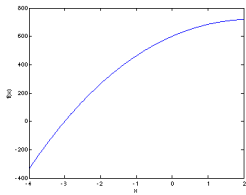
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So what should we check for sure

- 1 $f(x_n) < 0$
- 2 $f(x_p) > 0$

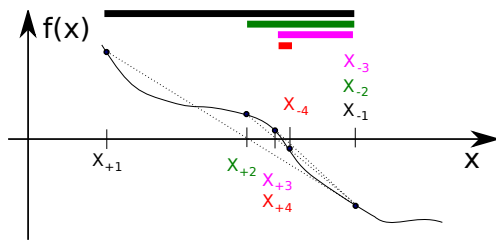
It would be handy to return secondary outputs

- with the value of function at the found solution point
- the number of iterations (good for performance tests)

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False position (*regula falsi*) method

In this method we naively approximate our function as a line.



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False position method - pseudo code

- make initial bracket for search x_+ and x_- such that
 - $f(x_+) > 0$
 - $f(x_-) < 0$
- loop begins
- draw a chord between points $(x_-, f(x_-))$ and $(x_+, f(x_+))$
- make new guess value at the point of the chord intersection with the 'x' axis
$$x_g = \frac{x_- f(x_+) - x_+ f(x_-)}{f(x_+) - f(x_-)}$$
- if $|f(x_g)| \leq \epsilon_f$ and $|x_+ - x_g| \leq \epsilon_x$ stop we found the solution with desired approximation
- otherwise if $f(x_g) > 0$ then $x_+ = x_g$ else $x_- = x_g$
- continue the loop

Note: it looks like bisection except the way of updating x_g

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Solution convergence

We say that algorithm has defined convergence if it is possible to express

$$\lim_{k \rightarrow \infty} (x_{k+1} - x_0) = c(x_k - x_0)^m$$

Where x_0 is true root of the equation, c is some constant, and m is the order of convergence.

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- the bisection algorithm has linear rate of convergence ($m = 1$) and $c = 1/2$
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- the bisection algorithm has linear rate of convergence ($m = 1$) and $c = 1/2$
- it is generally impossible to define convergence order for the false position method

Generally the speed of the algorithm is related to its convergence order. However, other factors may affect the speed.

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