

Root finding

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Lecture 05

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Example

$$3x^3 + 2 = \sin x \quad \rightarrow \quad 3x^3 + 2 - \sin x = 0$$

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A general search algorithm is the following

- make a guess i.e. trial
- make intelligent new guess (x_{i+1}) judging from this trial (x_i)
- continue as long as $|f(x_{i+1})| > \varepsilon_f$ and $|x_{i+1} - x_i| > \varepsilon_x$

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Example

Let's play a simple game:

- some one think of any number between 1 and 100
- I will make a guess
- you provide me with either “less” or “more” depending where is my guess with respect to your number

How many guesses do I need?

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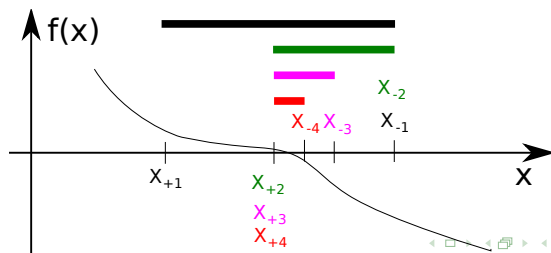
- some one think of any number between 1 and 100
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How many guesses do I need? At most **7**

Bisection method pseudo code

Works for any **continuous function** in vicinity of function root

- make initial bracket for search x_+ and x_- such that
 - $f(x_+) > 0$
 - $f(x_-) < 0$
- loop begins
- make new guess value $x_g = (x_+ + x_-)/2$
- if $|f(x_g)| \leq \varepsilon_f$ or $|x_+ - x_g| \leq \varepsilon_x$
stop we found the solution with desired approximation
- otherwise if $f(x_g) > 0$ then $x_+ = x_g$ else $x_- = x_g$
- continue the loop



Bisection - simplified matlab implementation

```
function x_sol=bisection(f, xn, xp, eps_f, eps_x)
% solving f(x)=0 with bisection method

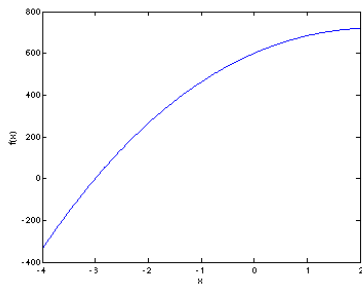
xg=(xp+xn)/2; % initial guess
fg=f(xg);     % initial function evaluation

while ( (abs(fg) > eps_f) & (abs(xg-xp)>eps_x) )
    if (fg>0)
        xp=xg;
    else
        xn=xg;
    end
    xg=(xp+xn)/2; % update guess
    fg=f(xg);     % update function evaluation
end
x_sol=xg; % solution is ready
end
```

Bisection - example of use

Let's define simple test function in the file 'function_to_solve.m'

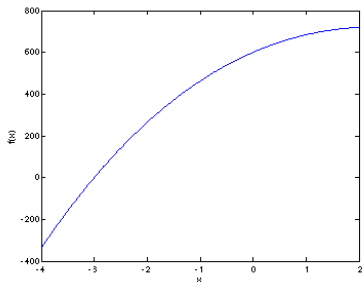
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function ret=function_to_solve(x)
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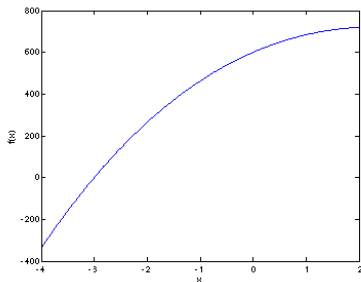
pay attention to the function handle operator @

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eps_x=1e-8;
eps_f=1e-6;
x0=bisection(...
    @function_to_solve,...
    -4.1, 2, ...
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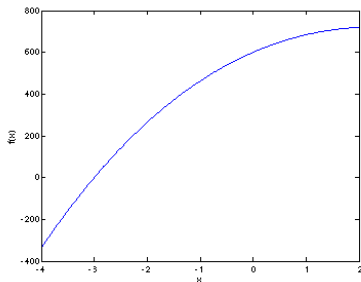
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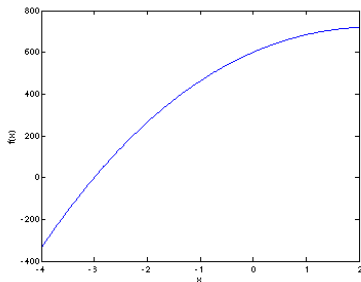
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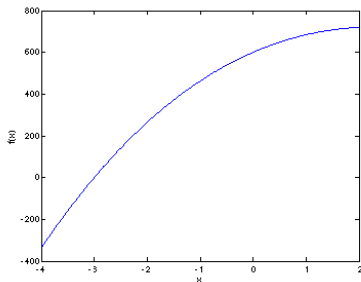
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So what should we check for sure

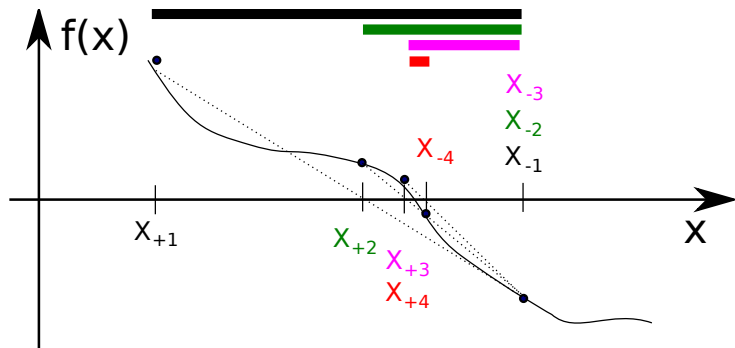
- 1 $f(xn) < 0$
- 2 $f(xp) > 0$

It would be handy to return secondary outputs

- with the value of function at the found solution point
- the number of iterations (good for performance tests)

False position (*regula falsi*) method

In this method we naively approximate our function as a line.



False position method - pseudo code

- make initial bracket for search x_+ and x_- such that
 - $f(x_+) > 0$
 - $f(x_-) < 0$
- loop begins
- draw a chord between points $(x_-, f(x_-))$ and $(x_+, f(x_+))$
- make new guess value at the point of the chord intersection with the 'x' axis

$$x_g = \frac{x_- f(x_+) - x_+ f(x_-)}{f(x_+) - f(x_-)}$$

- if $|f(x_g)| \leq \varepsilon_f$ or $|x_+ - x_g| \leq \varepsilon_x$
stop we found the solution with desired approximation
- otherwise if $f(x_g) > 0$ then $x_+ = x_g$ else $x_- = x_g$
- continue the loop

Note: it looks like bisection except the way of updating x_g

Solution convergence

We say that algorithm has defined convergence if it is possible to express

$$\lim_{k \rightarrow \infty} (x_{k+1} - x_0) = c(x_k - x_0)^m$$

Where x_0 is true root of the equation, c is some constant, and m is the order of convergence.

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- it is generally impossible to define convergence order for the false position method

Generally the speed of the algorithm is related to its convergence order. How ever other factors may affect the speed.