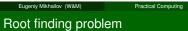


Root finding problem

Generally we want to solve the following canonical problem

f(x) = 0



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Example

 $2\sin(x) - 1 = 0$

Root finding problem

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Root finding problem

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Example

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$$2\sin(x)-1=0$$

Often we have a problem which looks slightly different

$$h(x)=g(x)$$

f(x)=h(x)-g(x)=0

But it is easy to transform to canonical form with

 $3x^3 + 2 = \sin x \quad \rightarrow \quad 3x^3 + 2 - \sin x = 0$

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Trial and error method

One can try to get the solution by just guessing with a hope to hit the solution. This is not highly scientific.

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Trial and error method

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Trial and error method

One can try to get the solution by just guessing with a hope to hit the solution. This is not highly scientific.

However each guess can provide some clues. A general search algorithm is the following

- make a guess i.e. trial
- make intelligent new guess (x_{i+1}) judging from this trial (x_i)
- continue as long as $|f(x_{i+1})| > \varepsilon_f$ and $|x_{i+1} x_i| > \varepsilon_x$

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Example

Let's play a simple game:

- some one think of any number between 1 and 100
- I will make a guess
- you provide me with either "less" or "more" depending where is my guess with respect to your number

How many guesses do I need?

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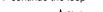
How many guesses do I need? At most 7

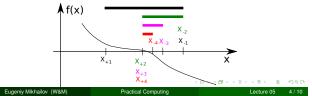
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Bisection method pseudo code

Works for any continuous function in vicinity of function root

- make initial bracket for search *x*₊ and *x*₋ such that
 - $f(x_+) > 0$
 - $f(x_{-}) < 0$
- loop begins
- make new guess value $x_g = (x_+ + x_-)/2$
- if $|f(x_g)| \le \varepsilon_f$ or $|x_+ x_g| \le \varepsilon_x$ stop we found the solution with desired approximation
- otherwise if $f(x_g) > 0$ then $x_+ = x_g$ else $x_- = x_g$
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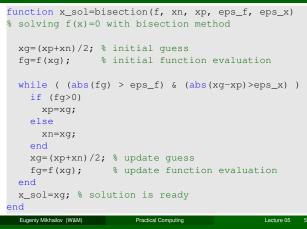


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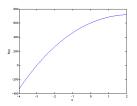




Bisection - example of use

Let's define simple test function in the file 'function_to_solve.m'

function ret=function_to_solve(x)
 ret=(x-10) * (x-20) * (x+3);
end



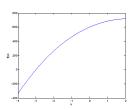
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pay attention to the function handle operator @

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eps_x=1e-8; eps_f=1e-6; x0=bisection(... @function_to_solve,... -4.1, 2, ... eps_f, eps_x)

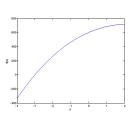
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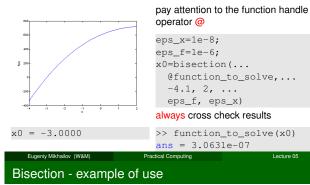
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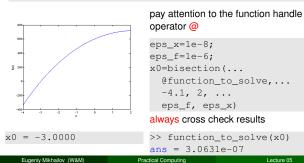
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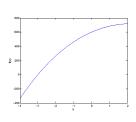
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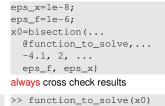
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ans = 3.0631e-07
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What is missing in the bisection code?

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The simplified bisection code is missing validation of input arguments.

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Eugeniy Mikhailov (W&M) Practical Computing Lecture 05 7/10 What is missing in the bisection code?

The simplified bisection code is missing validation of input arguments. People make mistakes, typos and all sorts of misuse.

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"If something can go wrong it will"

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Muphry's Law

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Never expect that user will put valid inputs.

Notes

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"If something can go wrong it will"

Muphry's Law

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Lecture 05

Lecture 05

Never expect that user will put valid inputs.

So what should we check for sure

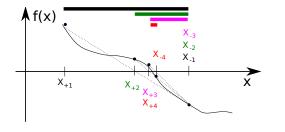
- f(xn) < 0
- 2 f(xp) > 0

It would be handy to return secondary outputs

- with the value of function at the found solution point
- the number of iterations (good for performance tests)

Eugeniy Mikhailov (W&M) Practical Computing False position (*regula falsi*) method

In this method we naively approximate our function as a line.



False position method - pseudo code

- make initial bracket for search x_+ and x_- such that
 - $f(x_+) > 0$

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- $f(x_{-}) < 0$
- loop begins
- draw a chord between points $(x_-, f(x_-))$ and $(x_+, f(x_+))$
- make new guess value at the point of the chord intersection with the 'x' axis $x = f(x_1) x = f(x_2)$

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$$x_g = \frac{x_-f(x_+) - x_+f(x_-)}{f(x_+) - f(x_-)}$$

- if $|f(x_g)| \le \varepsilon_f$ or $|x_+ x_g| \le \varepsilon_x$ stop we found the solution with desired approximation
- otherwise if $f(x_g) > 0$ then $x_+ = x_g$ else $x_- = x_g$
- continue the loop

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Note: it looks like bisection except the way of updating x_g

Solution convergence

Notes

We say that algorithm has defined convergence if it is possible to express

$$\lim_{k \to \infty} (x_{k+1} - x_0) = c(x_k - x_0)^n$$

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Where x_0 is true root of the equation, *c* is some constant, and *m* is the order of convergence.

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The best algorithm have quadratic convergence i.e. m = 2

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- it is generally impossible to define convergence order for the false position method

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- it is generally impossible to define convergence order for the false position method

Generally the speed of the algorithm is related to its convergence order. How ever other factors may affect the speed.

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