# Data interpolation 

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Lecture 23

## Data interpolation - filling the voids

Very rarely there is enough data. Often taking a data point takes a lot of time or it is expensive. But we would like to have some presentation of the system in the voids.


## Nearest neighbor interpolation

The name says it, for each interpolated point $x_{\text {interpolated }}$ find its nearest neighbor along the $x_{i}$ axis in the data set and use its $y_{i}$ value.


## Linear interpolation

We will split our data set with $N$ points to $N-1$ intervals and interpolate the values in the given interval as a line passing through the border points $\left(x_{i}, y_{i}\right)$ and $\left(x_{i+1}, y_{i+1}\right)$


## Polynomial fit

You can always find a polynomial of $N-1$ degree passing through $N$ data points.

$$
y(x)=p_{1} x^{n}+p_{2} x^{n-1}+\cdots+p_{n} x+p_{n+1}
$$

Matlab has the 'polyfit ' function which returns the polynomial coefficient.

```
% calculate coefficients
p=polyfit(xdata, ydata, (length(xdata)-1) );
% interpolate
yi=polyval(p,xi);
```



Interpolated values tend to oscillate for the polinomial of a high degree.
Do not use it!
Unless you know what you are doing.

## Cubic spline interpolation

We will interpolate $N$ data points by a polynomial of 3rd degree for each $i_{t h}$ interval between data point

$$
f_{i}(x)=p_{1_{i}} x^{3}+p_{2_{i}} x^{2}+p_{3_{i}} x+p_{4_{i}}, x \in\left[x_{i}, x_{i+1}\right]
$$



## Cubic spline interpolation demystified

We will interpolate $N$ data points by a polynomial of 3rd degree for each $i_{t h}$ interval between data point

$$
f_{i}(x)=p_{1_{i}} x^{3}+p_{2_{i}} x^{2}+p_{3_{i}} x+p_{4_{i}}, x \in\left[x_{i}, x_{i+1}\right]
$$

Interpolation must pass through data points

$$
\begin{aligned}
f_{i}\left(x_{i}\right) & =y_{i} \\
f_{i}\left(x_{i+1}\right) & =y_{i+1}
\end{aligned}
$$

Two data points (at the interval border) are not enough to set equations for 4 polynomial coefficients.

So we will request twice continuous differentiable

$$
\begin{aligned}
f_{i}^{\prime}\left(x_{i+1}\right) & =f_{i+1}^{\prime}\left(x_{i+1}\right) \\
f_{i}^{\prime \prime}\left(x_{i+1}\right) & =f_{i+1}^{\prime \prime}\left(x_{i+1}\right)
\end{aligned}
$$

At the end points second derivative must be set to 0 (so called natural cubic spline)

$$
\begin{aligned}
f_{1}^{\prime \prime}\left(x_{1}\right) & =0 \\
f_{N-1}^{\prime \prime}\left(x_{N}\right) & =0
\end{aligned}
$$

## Matlab built in interpolation

Use matlab interp1 (xdata, ydata, xi, method) for some of above methods
Where method could be
'nearest' Nearest neighbor interpolation
'linear' Linear interpolation (default)
'spline' Cubic spline interpolation other see more in help

## Extrapolation - voids outside the measurements region

## Do not extrapolate!!!

Unless you have a physical model of the process.

