

Non-Abelian Symmetries

We have studied the consequences of a number of continuous symmetries in this course. Some examples are the rotations in 3-dimensions, Lorentz transformations in 3+1 dimensions, the transformations $\psi \rightarrow e^{i\theta}\psi$ of a Dirac spinor.

Each of these classes of symmetry transformations share the mathematical properties of a group:

1. Closure: $\forall a, b \in G, ab \in G$
2. Associativity: $(ab)c = a(bc)$
3. Identity element: $\exists e \in G$ st $ea = ae = a \quad \forall a \in G$
4. Inverse element: $\forall a \in G \exists a^{-1} \in G$ st $aa^{-1} = a^{-1}a = e$

Continuous groups can also be defined as smooth manifolds. Such groups are called Lie groups.

Commutative groups (eg. $\{e^{i\theta}\}$ w/ usual multiplication) are called Abelian.

Non-commutative groups (eg. rotations in $d > 2$ dimensions) are called Non-Abelian.

In particle physics there are a number of approximate non-Abelian global symmetries (eg. isospin) and gauge invariances (color and weak interactions). To discuss the consequences of non-Abelian symmetries, and to build the Standard Model of Particle Physics, we first have to discuss non-Abelian groups.

Lie Groups and Lie Algebras

Examples: Rotations $SO(3)$ }
 Spin $SU(2)$ }
 $\psi \rightarrow e^{i\theta\gamma} \psi$ $U(1)$

The group describes how to transform elements of a vector space to other elements.

$$g: \Phi \rightarrow D(g)\Phi \equiv g\Phi, \quad g \in G = \text{a group of unitary } N \times N \text{ matrices.}$$

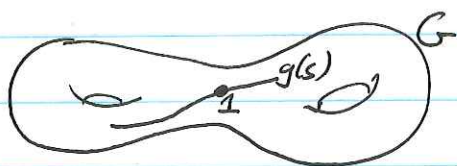
$\Phi \in N$ -dim'l vector space.

Example: $\underbrace{\begin{pmatrix} x \\ y \end{pmatrix}}_{\Phi} \rightarrow \underbrace{\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}}_g \underbrace{\begin{pmatrix} x \\ y \end{pmatrix}}_{\Phi}, \quad g \in SO(2)$

" group of orthogonal 2×2 matrices w/ determinant 1.

Lie groups are parametrized by continuous parameters, like θ in $SO(2) \sim U(1)$.

Consider a path in group space that passes through the identity element $e = 1$.



$g(s)$ = path in space of $N \times N$ unitary matrices st $g(0) = 1$.

Define $\boxed{\left. \frac{dg}{ds} \right|_{s=0}} \equiv -iT$ = $N \times N$ matrix

g Unitary: $gg^\dagger = g^\dagger g = 1$

$$0 = \left. \frac{d}{ds} (gg^\dagger) \right|_{s=0} = g(0) \left. \frac{dg^\dagger}{ds} \right|_{s=0} + \left. \frac{dg}{ds} \right|_{s=0} g^\dagger(0)$$

$$= 1(iT^\dagger) + (-iT)1$$

$$\rightarrow \boxed{T^\dagger = T} \quad \text{Hermitian}$$

Parametrize elements of the group by x^a , $a=1, \dots, \dim G$.
s.t. $x^a=0$ at $g(x^a)=1$.

$$\left. \frac{dg}{ds} \right|_{s=0} = \sum_a \left. \frac{dx^a}{ds} \right|_{s=0} \frac{\partial g}{\partial x^a} \equiv -i \sum_a \left. \frac{dx^a}{ds} \right|_{s=0} T^a$$

The T^a 's form a $(\dim G)$ -dimensional vector space called $\mathcal{A}(G) = \underline{\text{Lie Algebra}}$ of G .

The T^a 's are called generators of G .

Consider $h g(s) h^{-1}$, $h \in G$.

$$h g(0) h^{-1} = h \cdot 1 \cdot h^{-1} = 1$$

$$i \frac{d}{ds} [h g(s) h^{-1}] \Big|_{s=0} = \boxed{h T h^{-1} \in \mathfrak{A}(G)}$$

Consider $i \frac{d}{ds} [h(s) T h^{-1}(s)] \Big|_{s=0}$, $h(s) \in G$ st $h(0) = 1$.

$$i \frac{d}{ds} h(s) \Big|_{s=0} = T' \text{ for some } T' \in \mathfrak{A}(G)$$

$$\text{So, } i \frac{d}{ds} [h(s) T h^{-1}(s)] \Big|_{s=0} = \boxed{[T', T] \in \mathfrak{A}(G)}$$

The Lie Algebra of G is specified by the commutation relations,

$$\boxed{[T^a, T^b] = i f^{abc} T^c}, \quad a, b, c = 1, \dots, \dim G$$

↑ structure constants of $\mathfrak{A}(G)$.

Choose a basis s.t. $\text{Tr } T^a T^b = c \delta^{ab}$ for some c .

$$\text{Then, } \frac{1}{c} \text{Tr}([T^a, T^b] T^d) = \frac{i}{c} f^{abc} \text{Tr}(T^c T^d) = \frac{i}{c} \cdot c f^{abc} \delta^{cd}$$

$$\rightarrow \boxed{f^{abd} = -\frac{i}{c} \text{Tr}([T^a, T^b] T^d)}$$

Structure constants are antisymmetric: $f^{abc} = -f^{bac}$, etc.
cyclic: $f^{abc} = f^{cab} = f^{bca}$

For any T^a, T^b, T^c there is an identity,

$$[T^a, [T^b, T^c]] + [T^b, [T^c, T^a]] + [T^c, [T^a, T^b]] = 0$$

$$\boxed{f^{ade} f^{bcd} + f^{bde} f^{cad} + f^{cde} f^{abd} = 0} \quad \text{Jacobi Identity}$$

Group elements from Algebra elements:

Infinitesimal deviation from identity

$$\Phi \rightarrow (1 + i\theta^a T^a) \Phi, \quad \theta^a \ll 1.$$

$$\Phi \text{ complex: } \Phi^* \rightarrow (1 - i\theta^a (T^a)^*) \Phi^* \\ = (1 - i\theta^a (T^a)^T) \Phi^*$$

Hence, the set of matrices $-(T^a)^T$ are the generators of a representation of G . If T^a are the generators of G , in a representation r , then $-(T^a)^T$ are the generators of the conjugate representation to r .

$$\text{Adjoint Representation } (T^b)_{ac} = i f^{abc}$$

$$\text{Jacobi ID} \rightarrow [T^a, T^b]_{de} = i f^{abc} T^c_{de}$$

f^{abc} — real, antisymmetric

$\rightarrow T^a = -(T^a)^T$ in adjoint rep \rightarrow real representation.

Examples: $U(1)$ $g = e^{i\theta}$, $\dim G = 1$.

$$\left. \frac{dg}{d\theta} \right|_{\theta=0} = i \rightarrow T = 1$$

$[T, T] = 0 \rightarrow$ Abelian group.

$SU(2)$ = group of unitary 2×2 matrices w/ determinant 1.

$$g = e^{i\theta^a \sigma^a / 2} \quad \dim G = 3$$

$\sigma^a =$ Pauli σ -matrices

\rightarrow Fundamental representation of $SU(2)$

$$\text{Tr } T^a T^b = \frac{1}{2} \delta^{ab} \text{ in Fundamental rep.}$$

\uparrow You can fix the constant arbitrarily but (but not the same) once fixed for one rep, it's fixed for all reps.

$SU(3)$ = group of unitary 3×3 matrices w/ determinant 1.

$$g = e^{i\theta^a T^a}, \quad a=1, \dots, 8 \quad \dim G = 8$$

In fundamental rep, can choose basis:

Cell-Mann
matrices

$$\left\{ \begin{array}{l} T^1 = \frac{1}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad T^2 = \frac{1}{2} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad T^3 = \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \\ T^4 = \frac{1}{2} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad T^5 = \frac{1}{2} \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}, \quad T^6 = \frac{1}{2} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \\ T^7 = \frac{1}{2} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}, \quad T^8 = \frac{1}{2\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \end{array} \right.$$