

# PHYS 621 Lecture Notes 2

- Today:
- More about Vector Spaces
    - Change of basis
    - Unitary, Hermitian operators
  - Hilbert Space

N1.2

## Matrix representation

$$|v\rangle = \sum_i v_i |i\rangle = \sum_i |i\rangle \underbrace{\langle i|v\rangle}_{v_i}$$

$\uparrow$   
Basis vector

$$(\text{orthonormal basis: } \langle i|j\rangle = \delta_{ij})$$

Basis vectors in matrix representation!

$$|i\rangle = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow 1 \text{ in } i^{\text{th}} \text{ component}$$

Matrix element of operator  $\hat{A}$  in  $\{|i\rangle\}$  basis:

$$A_{ij} = \langle i|\hat{A}|j\rangle$$

$\uparrow$  row       $\nwarrow$  column

$$(\hat{A}\hat{B})_{ij} = \sum_k \langle i | \hat{A} | k \rangle \langle k | \hat{B} | j \rangle$$

$$= \sum_k A_{ik} B_{kj}$$

$$= (\underline{A} \underline{B})_{ij}$$

— like matrix multiplication

$\underline{A}$  = matrix with elements  $A_{ij}$ .

Operator Inverse:  $\hat{A}^{-1}$  defined s.t.

$$\hat{A}\hat{A}^{-1} = \hat{A}^{-1}\hat{A} = \mathbb{1}$$

### N1.3 Dual Space

+ Adjoint operators: transpose and complex conjugate

$$(|v\rangle)^{\dagger} = (v_1^*, v_2^*, \dots, v_n^*)$$

$$\langle v | u \rangle = \sum_i v_i^* u_i = (v_1^*, \dots, v_n^*) \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix}$$

$$\Rightarrow \langle v | = (|v\rangle)^{\dagger}$$

$|u\rangle \in$  vector space  $V$  ket vector

$\langle v| \in$  dual space  $V^*$  bra vectors

$$\langle \alpha v| = (|\alpha v\rangle)^{\dagger} = \alpha^* \langle v|$$

$\uparrow$   $\uparrow$   
Scalar vector

$$|v\rangle = \sum_i v_i |i\rangle$$

$$\langle v| = \sum_i v_i^* \langle i|$$

Adjoint operation on operators

$$(\hat{A}^{\dagger})_{ij} \equiv \langle j|\hat{A}|i\rangle^* = A_{ji}^*$$

writing  $\hat{A}|v\rangle = |\hat{A}v\rangle,$

$$\langle \hat{A}v| = (|\hat{A}v\rangle)^{\dagger} = \langle v|\hat{A}^{\dagger}$$

Transpose of product reverses order:

$$(\hat{A}\hat{B})^{\dagger} = \hat{B}^{\dagger}\hat{A}^{\dagger}$$

## Change of basis:

Orthonormal basis  $\{|i\rangle\}$

Different orthonormal basis  $\{|i'\rangle\}$ .

Question: How can  $\{|i\rangle\}$  and  $\{|i'\rangle\}$  be related.

(Compare with rotation of spatial basis vectors  $\hat{x}, \hat{y}, \hat{z}$ .)

Suppose  $|i'\rangle = \sum_j U_{ji} |j\rangle$  (linear transformation)

The power of the bra-ket notation:

$$\langle k|i'\rangle = \sum_j \langle k| U_{ji} |j\rangle$$

$\uparrow$  inner product

$$= \sum_j U_{ji} \langle k|j\rangle$$

$$= \sum_j U_{ji} \delta_{kj}$$

$\uparrow$  1, if  $k=j$   
0, if  $k \neq j$

$$= U_{ki}$$

Define operator  $\hat{U}$  s.t.  $\langle k | \hat{U} | i \rangle = U_{ki}$

$$= \langle k | \hat{U} | i \rangle$$

$$= \langle k | i' \rangle$$

$$\Rightarrow \hat{U} | i \rangle = | i' \rangle$$

Suppose  $| i \rangle = \sum_j V_{ji} | j' \rangle$  (inverse relation)

$$\langle k' | i \rangle = \sum_j V_{ji} \langle k' | i' \rangle$$

$$= V_{ki}$$

$$= (\langle i | k' \rangle^*) = U_{ik}^*$$

$$= \hat{U}_{ki}^+$$

$$\Rightarrow \hat{V} = \hat{U}^+$$

$$| i \rangle \xrightarrow{\hat{U}} | i' \rangle \xrightarrow{\hat{U}^+} | i \rangle$$

$$\hat{U}^+ \hat{U} | i \rangle = | i \rangle$$

$$\Rightarrow \hat{U}^+ \hat{U} = \hat{1}$$

Similarly,

$$\hat{U} \hat{U}^+ = \hat{1}$$

$$\left. \begin{array}{l} \hat{U}^+ \hat{U} = \hat{1} \\ \hat{U} \hat{U}^+ = \hat{1} \end{array} \right\} \hat{U}^{-1} = \hat{U}^+$$

- Unitary operator.

$$\det(\underline{U} \underline{U}^\dagger) = (\det U)(\det U^\dagger) = \det(\mathbb{1}) = 1.$$

↑  
Matrix represents  
U

$$= (\det U)(\det(U^\dagger))^* \\ = (\det U)(\det U)^* \\ = |\det U|^2 = 1$$

$$\rightarrow |\det U| = 1$$

★ Scalar product is invariant under change of basis.

(c.f.  $\vec{a} \cdot \vec{b}$  invariant under rotations)

Do this —  $|v'\rangle = \hat{U}|v\rangle, |w'\rangle = \hat{U}|w\rangle$

$$\langle w'|v'\rangle = \langle \hat{U}w | \hat{U}v \rangle \\ = \langle w | \hat{U}^\dagger \hat{U} | v \rangle$$

OR

$$\langle w'|v'\rangle = \langle w|v\rangle$$

Instead of acting on vectors (active) can act on operators (passive) - c.f. rotating vectors vs. rotating coordinates.

Do this —  $\langle i|\hat{A}|j\rangle = \langle i|\hat{U}^\dagger \hat{A} \hat{U}|j\rangle \rightarrow \hat{A}' = \hat{U}^\dagger \hat{A} \hat{U}$   
Not both!

## Hermitean Operators

Hermitean = self-adjoint

$$\hat{A}^\dagger = \hat{A}$$

Hermitean

$$\hat{A}^\dagger = -\hat{A}$$

anti-Hermitean

Every operator can be written as a sum of a Hermitean and anti-Hermitean operator.

$$\hat{A} = \frac{\hat{A} + \hat{A}^\dagger}{2} + \frac{\hat{A} - \hat{A}^\dagger}{2}$$

↑  
Hermitean

↑  
anti-Hermitean

★ For a Hermitean operator (not a general operator):

$$A_{ij} = \langle i | \hat{A} | j \rangle = (\langle j | \hat{A}^\dagger | i \rangle)^\dagger$$

$$= (\langle j | \hat{A} | i \rangle)^\dagger \quad \text{— because } \hat{A}^\dagger = \hat{A}$$

$$= A_{ji}^*$$

Suppose we want an eigenvector of the operator  $\hat{A}$ , i.e. a solution to

$$\hat{A}|v\rangle = \lambda|v\rangle = \lambda \hat{1}|v\rangle.$$

$\lambda$   
↑  
eigenvalue —  $\lambda \in \mathbb{C}$  complex #.

$$(\hat{A} - \lambda \hat{1})|v\rangle = 0$$

$$\langle v|(\hat{A} - \lambda \hat{1})|v\rangle = 0$$

$$\rightarrow \underline{A} - \lambda \underline{1} = 0 \quad \text{Matrix eq.}$$

$$\boxed{\det(A - \lambda \underline{1}) = 0} \quad \text{— Eigenvalue condition}$$

— determining eigenvalues  $\lambda$ .

Theorem: All eigenvalues of a Hermitian op. are real.

Proof: Suppose  $|v\rangle$  is an eigenvector of  $\hat{A} = \hat{A}^\dagger$

with eigenvalue  $\lambda$ :

$$\hat{A}|v\rangle = \lambda|v\rangle \rightarrow \langle v|\hat{A}|v\rangle = \lambda \|v\|^2$$

$$\text{Also, } (\hat{A}|v\rangle)^\dagger = \lambda^* \langle v|$$

$$= \langle v|\hat{A}^\dagger = \langle v|\hat{A} \Rightarrow \langle v|\hat{A}|v\rangle = \lambda^* \langle v|v\rangle$$

↑ Hermitian

$$= \lambda^* \|v\|^2$$

$$\Rightarrow \boxed{\lambda = \lambda^*} \quad \text{real}$$



Theorem: For a Hermitian operator,  $\exists$  orthonormal basis of eigenvectors for  $V$ .

In that basis:  $\underline{A} = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix}$  diagonal

$\Rightarrow$  We can always diagonalize a Hermitian operator by a unitary transformation s.t.

$$(\hat{U}^\dagger \hat{A} \hat{U})_{ij} = \lambda_i \delta_{ij}$$

## Hilbert Spaces — vector space with a scalar product

and corresponding norm s.t. all vectors can be normalized to  $\|v\|=1$  (proper vectors), with continuity & completeness with respect to the inner product.

— If  $\|v\|^2 = \langle v|v \rangle = 1$ , then

$$\text{with } |v\rangle = \sum_i v_i |i\rangle, \quad \leftarrow \text{basis vector,}$$

$$1 = \langle v|v \rangle = \sum_{i,j} \langle j|v_j^* v_i|i\rangle$$

$$= \sum_{i,j} v_j^* v_i \langle j|i\rangle$$

$$= \sum_{i,j} v_j^* v_i \delta_{ij}$$

$$= \sum_i v_i^* v_i = \sum_i |v_i|$$

$$= \sum_i |\langle i|v\rangle|^2 \quad \leftarrow v_i$$

★ The state space for quantum mechanics is a Hilbert space.