

Possibly useful relations:

$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$	$ \vec{A} = \sqrt{A_x^2 + A_y^2 + A_z^2}$
$\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t}$	$\vec{v}(t) = \frac{\vec{r}}{dt}$
$\vec{a}(t) = \frac{d\vec{v}}{dt}$	$\vec{v}_f = \vec{v}_i + \vec{a}t$
$x_f = x_i + v_i t + \frac{1}{2} a t^2$	$\vec{r}_f = \vec{r}_i + \vec{v}_i t + \frac{1}{2} \vec{a} t^2$
$v_f^2 = v_i^2 + 2a\Delta x$	$x_f = x_i + v_{\text{avg}} t$
$v = \frac{2\pi r}{T}$	$a_c = \frac{v^2}{r}$
$\vec{v}_{AB} = \vec{v}_{AC} + \vec{v}_{CB}$	$v = r\omega$
$\vec{W} = m\vec{g}$	$\Sigma \vec{F} = m\vec{a}$
$W = F\Delta x$	$f_S \leq \mu_S N$
$W = \Delta K$	$W = \vec{F} \cdot \Delta \vec{r}$
$\vec{A} \cdot \vec{B} = AB \cos \theta = A_x B_x + A_y B_y + A_z B_z$	$K = \frac{1}{2}mv^2$
$F = -kx$	$\Delta U = -W$
$U = mgy + U_0$	$U = \frac{1}{2}kx^2 + U_0$
$\Delta U + \Delta K + \Delta E_{\text{int}} = W^{\text{ext}}$	$F_x = -\frac{dU}{dx}$
$P = \frac{dE}{dt}$	$K_i + U_i = K_f + U_f$
$\vec{p} = m\vec{v}$	$E_{\text{total}}^{\text{isolated}} = \text{const.}$
$\vec{I} = \Delta \vec{p} = \int \vec{F} dt = \vec{F}_{\text{av}} \Delta t$	$P = \vec{F} \cdot \vec{v}$
$\Sigma \vec{F}_{\text{ext}} = M\vec{a}_{\text{cm}}$	$\vec{F} = \frac{d\vec{p}}{dt}$
$\cos \theta = \text{adj.}/\text{hypo.}$	$\vec{r}_{\text{cm}} = \frac{1}{M} \sum \vec{r}_i m_i$
$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$	$M\vec{v}_{\text{cm}} = \vec{p}_{\text{total}}$
	$\sin \theta = \text{opp.}/\text{hypo.}$
	$\tan \theta = \frac{\sin \theta}{\cos \theta}$
	$g = 9.8 \text{ m/s}^2$ downward