

Adiabatic Approximation

Let's assume that our Hamiltonian depends on a certain parameter s and

$$H[s] |n[s]\rangle = E_n[s] |n[s]\rangle$$

$$\langle m[s] | n[s] \rangle = \delta_{mn}$$

Thus, we can define eigenstates and eigenenergies for any value of s .

Now let's consider the situation when $s = s(t)$. Obviously, we can now identify the eigenstates and energies for any moment of time, but this basis will be changing in time.

Slow change in s means small variation in states, but the change after a longer time evolution can be significant.

Now we need to solve the time-dependent Schrödinger equation

$$i\hbar \frac{\partial}{\partial t} \psi(t) = \hat{H}[s(t)] \psi(t)$$

As usual, we are going to decompose the state in the basis of eigenfunctions

$$|\psi(t)\rangle = \sum_n c_n(t) e^{i\theta_n(t)} |n[s(t)]\rangle$$

comparing this with the time-independent \hat{H} case

$$|\psi(t)\rangle = \sum_n c_n e^{-i \frac{E_n t}{\hbar}} |n\rangle$$

and writing for small Δt $\theta_n(\Delta t) \approx -\frac{iE_n \Delta t}{\hbar}$,

we can find that

$$\theta_n(t) = -\frac{i}{\hbar} \int_0^t E_n[S(t')] dt' \quad \dot{\theta}_n = -\frac{iE_n}{\hbar}$$

$$i\hbar \frac{\partial |d\rangle}{\partial t} = i\hbar \sum_n \left[\dot{c}_n e^{i\theta_n} |n[S(t)]\rangle + c_n e^{i\theta_n} \frac{\partial}{\partial t} |n[S(t)]\rangle + c_n e^{i\theta_n} \frac{\partial}{\partial t} |n\rangle \right]$$

$$= \hat{H} |d\rangle = \sum_n c_n e^{i\theta_n} E_n |n\rangle$$

$$i\hbar \sum_n \left[\dot{c}_n e^{i\theta_n} |n\rangle + c_n e^{i\theta_n} \frac{\partial}{\partial t} |n[S(t)]\rangle \right] = 0$$

$$i\hbar \dot{c}_m e^{i\theta_m} = -\sum_n c_n e^{i\theta_n} \langle m | \frac{\partial}{\partial t} |n[S(t)]\rangle$$

$$\dot{c}_m = -\sum_n c_n e^{i(\theta_n - \theta_m)} \langle m | \frac{\partial}{\partial t} |n[S(t)]\rangle$$

At the same time

$$H[S(t)] |n[S(t)]\rangle = E_n[S(t)] \cdot |n[S(t)]\rangle$$

$$\frac{\partial H}{\partial t} |n\rangle + H_n \frac{\partial |n\rangle}{\partial t} = \frac{\partial E_n}{\partial t} |n\rangle + E_n \frac{\partial |n\rangle}{\partial t}$$

$$\langle m | \frac{\partial H}{\partial t} |n\rangle + E_m \langle m | \frac{\partial |n\rangle}{\partial t} = \frac{\partial E_n}{\partial t} \delta_{nm} + E_n \langle m | \frac{\partial |n\rangle}{\partial t}$$

for $m \neq n$

for $m = n$

$$\langle m | \frac{\partial |n\rangle}{\partial t} = \frac{1}{E_n - E_m} \langle m | \dot{H} |n\rangle; \quad \langle m | \frac{\partial H}{\partial t} |m\rangle = \frac{\partial E_m}{\partial t}$$

or, more precisely

$$\langle m | \frac{\partial}{\partial t} |n[S(t)]\rangle = \frac{1}{E_n - E_m} \langle m | \dot{H}[S(t)] |n\rangle$$

$$\dot{c}_m = - c_m \underbrace{\langle m | \frac{\partial}{\partial t} | m \rangle}_{\text{evolution of the same state}} - \underbrace{\sum_{n \neq m} c_n e^{i(\theta_n - \theta_m)} \frac{\langle m | H | n \rangle}{E_n - E_m}}_{\text{transitions b/w state}}$$

Adiabatic approximation \rightarrow we assume that the system stays in the same quantum state $|m\rangle$ as time progresses. That means the second term is negligible.

$$|\langle m | \frac{\partial | m \rangle}{\partial t} | \sim \frac{E_m}{\hbar} \quad ; \quad \langle m | H | m \rangle \sim \frac{\partial E_m}{\partial t} \sim \frac{E_m}{\tau}$$

So in order for the first term to dominate

$$\frac{E_m}{\hbar} \gg \frac{E_m}{\tau(E_m - E_n)} \sim \frac{1}{\tau}$$

τ - characteristic time-scale for $S(t)$ change

Adiabatic approximation \Rightarrow
 $\tau \gg \hbar/E_m$ slow variation

Then

$$\dot{c}_m = - c_m \langle m | \frac{\partial}{\partial t} | m \rangle$$

$$c_m = c_m(s_0) e^{-\int_0^t \langle m | \frac{\partial}{\partial t} | m \rangle dt'} = c_m(s_0) e^{i\gamma_m(t)}$$

$s_0 = [t=0]$

$$\gamma_m = i \int_0^t \langle m | \frac{\partial}{\partial t} | m \rangle dt'$$

γ_m is real

$$\frac{\partial}{\partial t} \langle m | m \rangle = \left[\frac{\partial}{\partial t} \langle m | \right] | m \rangle + \langle m | \left[\frac{\partial}{\partial t} | m \rangle \right] = 0$$

$$\langle m | \frac{\partial}{\partial t} | m \rangle = - \left(\frac{\partial}{\partial t} \langle m | \right)^* | m \rangle = - \left(\langle m | \frac{\partial}{\partial t} | m \rangle \right)^*$$

\swarrow purely imaginary

So if we start at one of the eigenstates at $t=0$

$$|d(t=0)\rangle = |n\rangle \quad c_n = 1, \quad c_m = 0 \quad m \neq n$$

then $|d(t)\rangle = e^{i\gamma_n} e^{i\theta_n} |n[s(t)]\rangle$

if $s(t) = s_0$ no time dependence

$$\gamma_n = i \int_0^t \langle n | \frac{\partial}{\partial t} |n\rangle dt = i \int_0^t \left(\frac{-iE_n}{\hbar} \right) dt = \frac{E_n t}{\hbar}$$

$$\theta_n = - \frac{iE_n t}{\hbar}$$

and $|d(t)\rangle = |n\rangle$

So in adiabatic approximation the only consequence of time variation of the parameters is an extra phase factor $e^{i\gamma_n}$. But the phase of the wave function does not matter, right?!

Berry's Phase

$$\gamma_n = i \int_0^t \langle n | \frac{\partial}{\partial t} |n[s(t)]\rangle dt$$

$$\frac{\partial}{\partial t} |n[s(t)]\rangle = \sum_i \frac{\partial |n\rangle}{\partial s_i} \frac{\partial s_i}{\partial t}$$

where s_i are dimensions of the parameter s
 $s = 3D$ vector $\vec{s} = \{s_1, s_2, s_3\}$

Example: s is $\vec{r} = \begin{matrix} x \\ y \\ z \end{matrix}$

$$\frac{\partial}{\partial t} |n(\vec{r}(t))\rangle = \frac{\partial |n\rangle}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial |n\rangle}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial |n\rangle}{\partial z} \frac{\partial z}{\partial t}$$

$$\int_0^t \frac{\partial}{\partial t} |n(\vec{r}(t))\rangle dt = \int_0^t \langle n | \left(\nabla |n(\vec{r})\rangle \right) \frac{d\vec{r}}{dt} dt = \int \langle n | \left(\nabla |n(\vec{r})\rangle \right) d\vec{r}$$

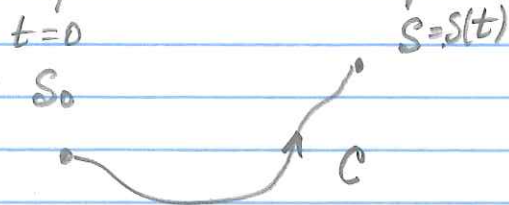
(t) line integral along the trajectory

Obviously, we can generalize this for any s -space, defining $\nabla_s \rightarrow \sum_i \frac{\partial}{\partial s_i} \hat{e}_{s_i}$

Then

$$\gamma_n = i \int_{C(t)} \langle n[s] | \nabla_s | n[s] \rangle d\vec{s}$$

The value of the phase does not depend on time, but rather on the "path" of the system in s -parameter space



Coming back to the question - should we worry about this phase?

If we can get rid of it by re-normalizing the state

$$|\tilde{n}[s]\rangle = e^{i d_n[s]} |n[s]\rangle$$

such that $\tilde{\gamma}_n(t) = \gamma_n(t) + d_n[s_0] - d_n[S(t)]$

If we can find such d_n , then

$\{|\tilde{n}[s]\rangle\}$ and $\{|n[s]\rangle\}$ are equivalent

For this to happen $\gamma_n(t) = 0$ for $S(t) = s_0$ $\forall t$

or
$$\oint_C \langle n[s] | \nabla_s | n[s] \rangle d\vec{s} = 0$$

This also means $\gamma_n(t)$ does not depend on the path $C(t)$.

What if $\gamma_n(t)$ over closed path is not zero?

Stokes
Theorem

$$\gamma_n(t) = i \oint_C \langle n | \nabla_{\vec{s}} | n \rangle d\vec{s} = i \int_{A_C} \nabla_{\vec{s}} \times (\langle n | \nabla_{\vec{s}} | n \rangle) d\vec{a}_{\vec{s}}$$

A - an area in \vec{s} -space, enclosed by C
 $d\vec{a}_{\vec{s}}$ - area element

$$\nabla_{\vec{s}} \times (\langle n | \nabla_{\vec{s}} | n \rangle) = (\nabla_{\vec{s}} \langle n |) \times (\nabla_{\vec{s}} | n \rangle) = \sum_m [\nabla_{\vec{s}} \langle n | m \rangle \times \langle m | \nabla_{\vec{s}} | n \rangle]$$

$$\nabla_{\vec{s}} \left(H[s] | n[s] \rangle = E_n[s] | n[s] \rangle \right)$$

$$(\nabla_{\vec{s}} H) \cdot | n \rangle + H \nabla_{\vec{s}} | n \rangle = (\nabla_{\vec{s}} E_n) | n \rangle + E_n (\nabla_{\vec{s}} | n \rangle)$$

for $n \neq m$

$$\langle m | \nabla_{\vec{s}} H | n \rangle + E_m \langle m | \nabla_{\vec{s}} | n \rangle = E_n \langle m | \nabla_{\vec{s}} | n \rangle$$

$$\langle m | \nabla_{\vec{s}} | n \rangle = \frac{\langle m | \nabla_{\vec{s}} H | n \rangle}{E_n - E_m}$$

what about $n=m$?

$$\nabla_{\vec{s}} \langle n | n \rangle = \underbrace{[\nabla_{\vec{s}} \langle n |] | n \rangle}_A + \underbrace{\langle n | [\nabla_{\vec{s}} | n \rangle]}_{-A} = 0$$

$$\text{thus } [\nabla_{\vec{s}} \langle n |] | n \rangle \times \langle n | [\nabla_{\vec{s}} | n \rangle] = 0$$

Thus

$$\gamma_n[C] = i \int_{A_C} \underbrace{\sum_{m \neq n} \frac{\langle n | \nabla_{\vec{s}} H | m \rangle \langle m | \nabla_{\vec{s}} H | n \rangle}{(E_n - E_m)^2}}_{\vec{B}_n[s]} d\vec{a}_{\vec{s}}$$

Berry phase is the flux of the vector \vec{B} through a surface enclosed by the contour C.

Example: a particle with non-zero angular momentum in a slowly varying magnetic field

Out: time-varying parameter $\vec{B} = \vec{B}(t)$

$$\hat{H}[\vec{B}] = \mu \vec{B} \cdot \vec{J} + \hat{H}_0$$

μ - a constant relating magnetic and angular momentum

For any moment of time we direct z-axis along \vec{B} ; $\vec{B} = B_0 \vec{e}_z(t)$

$$\hat{H}[\vec{B}] = \mu B_0 J_z (+ H_0) \quad \left\{ \begin{array}{l} \text{additional } \hat{H} \text{ terms,} \\ \text{independent of } \vec{J} \end{array} \right.$$

$$\hat{H} |m[\vec{B}]\rangle = \mu \vec{B} \cdot \vec{J} |m\rangle = \mu B_0 J_z |m\rangle = \hbar \mu B_0 m |m\rangle$$

$$\nabla_{\vec{B}} \hat{H} = \mu \nabla_{\vec{B}} (\vec{B} \cdot \vec{J}) = \mu \vec{J}$$

We need to calculate μ^2

$$\mu^2 \sum_{m' \neq m} \frac{\langle m | \vec{J} | m' \rangle \langle m' | \vec{J} | m \rangle}{(E_m - E_{m'})^2} \sim \hbar^2 = \frac{m i m \vec{e}_z}{B_0^2} = \frac{i m}{|\vec{B}|^2} \vec{e}_{\vec{B}}$$

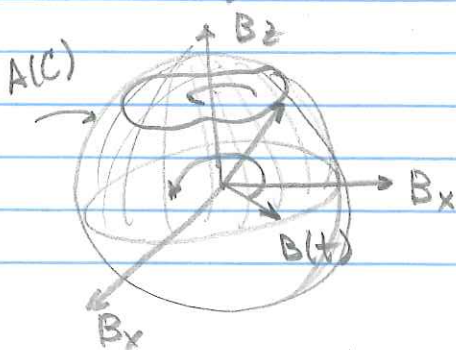
since

$\vec{J} = J_+ \vec{e}_+ + J_- \vec{e}_- + J_z \vec{e}_z$ $m' = \pm m$, and each $\langle m | \vec{J} | m' \rangle$ vector is in x-y plane, so that the vector product is in z-direction

Berry phase

singularity at $B_0 = 0$

$$\gamma = - \int_{A(C)} \frac{i m \vec{B}}{|\vec{B}|^3} \cdot d\vec{a}_{\vec{B}} =$$



Rotating magnetic field
C - circle of radius B_0
 $d\vec{a}_{\vec{B}} = \pi B_0^2 \vec{B}/B_0 d\Omega$

$$\gamma = -m \cdot \Omega = \int \text{solid angle}$$

Phase depends on the value of
the original angular momentum state

$$J_z j = \frac{1}{2} \quad \gamma_{\pm} = \pm \frac{1}{2} \Omega$$

For an experiment with phase sensitivity
(interferometry!) the Berry phase can
be measured