

# Eigenvalues and eigenstate of an operator

In general, an operator changes the state it acts on

$$|\text{fin}\rangle = \hat{A} |\text{ini}\rangle \quad |\text{fin}\rangle \neq |\text{ini}\rangle.$$

However, most operators have eigenstates, that are unchanged, and the ~~not~~ average value of an operator in such a state is definite  $\rightarrow$  eigenvalue.

$$\hat{A} |\alpha_i\rangle = A_i |\alpha_i\rangle$$

$\alpha_i$  - possible outcomes

$\hat{A}$  - operator (a matrix)

$|\alpha_i\rangle$  - eigenstate (a vector)

$\alpha_i$  - eigenvalue (a number)

Example:  $\hat{J}_z$  is the operator representing the  $z$ -component of the angular momentum (for a free particle  $\hat{J}_z \equiv \hat{S}_z$  - spin ang. momentum)

We already know the eigenstates and eigenvalues of  $\hat{J}_z$ :

$$\hat{J}_z |+z\rangle = \frac{\hbar}{2} |+z\rangle$$

$$\hat{J}_z |-z\rangle = -\frac{\hbar}{2} |-z\rangle$$

What is the matrix of  $\hat{J}_z$ ?

$$\begin{aligned} \hat{J}_z &= \begin{pmatrix} \langle +z | \hat{J}_z | +z \rangle & \langle +z | \hat{J}_z | -z \rangle \\ \langle -z | \hat{J}_z | +z \rangle & \langle -z | \hat{J}_z | -z \rangle \end{pmatrix} = \begin{pmatrix} \frac{\hbar}{2} & 0 \\ 0 & -\frac{\hbar}{2} \end{pmatrix} = \\ &= \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{\hbar}{2} \hat{\sigma}_z \quad \boxed{\hat{\sigma}_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}} \end{aligned}$$

$$\hat{J}_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \frac{\hbar}{2} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \frac{\hbar}{2} |+z\rangle \langle +z| - \frac{\hbar}{2} |-z\rangle \langle -z| =$$

$$= \frac{\hbar}{2} (\hat{P}_+ - \hat{P}_-)$$

What about  $\hat{J}_x$  and  $\hat{J}_y$ ?

$$\hat{J}_x |+x\rangle = \frac{\hbar}{2} |+x\rangle \quad \hat{J}_x |-x\rangle = -\frac{\hbar}{2} |-x\rangle$$

In the  $z$ -basis we can calculate the matrix for  $J_x$  by evaluating the matrix elements

$$\begin{aligned}\langle +z | \hat{J}_x | +z \rangle &= \langle +z | \hat{J}_x \left( \frac{1}{\sqrt{2}} |+x\rangle + \frac{1}{\sqrt{2}} |-x\rangle \right) = \\ &= \langle +z | \frac{1}{\sqrt{2}} \frac{\hbar}{2} |+x\rangle + \frac{1}{\sqrt{2}} \left( -\frac{\hbar}{2} \right) |-x\rangle = \\ &= \frac{\hbar}{2} \langle +z | \left( \frac{1}{\sqrt{2}} |+x\rangle - \frac{1}{\sqrt{2}} |-x\rangle \right) = \frac{\hbar}{2} \langle +z | -z \rangle = 0\end{aligned}$$

Similarly  $\langle -z | \hat{J}_x | -z \rangle = 0$

$$\begin{aligned}\langle +z | \hat{J}_x | -z \rangle &= \langle +z | \hat{J}_x \left( \frac{1}{\sqrt{2}} |+x\rangle - \frac{1}{\sqrt{2}} |-x\rangle \right) = \\ &= \langle +z | \left( \frac{1}{\sqrt{2}} \frac{\hbar}{2} |+x\rangle - \frac{1}{\sqrt{2}} \left( -\frac{\hbar}{2} \right) |-x\rangle \right) = \frac{\hbar}{2} \langle +z | \left( \frac{1}{\sqrt{2}} |+x\rangle + \frac{1}{\sqrt{2}} |-x\rangle \right) \\ &= \frac{\hbar}{2} \quad \langle -z | \hat{J}_x | +z \rangle = \langle +z | \hat{J}_x | -z \rangle^* = \frac{\hbar}{2}\end{aligned}$$

$$\hat{J}_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{\hbar}{2} \hat{\sigma}_x \Rightarrow \hat{\sigma}_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Following the same steps

$$\hat{J}_y = \frac{\hbar}{2} \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} = \frac{\hbar}{2} \hat{\sigma}_y \quad \hat{\sigma}_y = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$$

Pauli matrices

$$\hat{\sigma}_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \hat{\sigma}_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \hat{\sigma}_y = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$$

$$\hat{\sigma}_z^2 = \hat{\sigma}_x^2 = \hat{\sigma}_y^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \hat{\mathbb{1}}$$

## More quantum operator properties

$$|\psi_{\text{fin}}\rangle = \hat{A} |\psi_{\text{ini}}\rangle \quad | \quad \langle \psi_{\text{fin}}| = \langle \psi_{\text{ini}}| \hat{A}^{\dagger}$$

$\hat{A}^{\dagger}$  *dagger (not plus!)*

adjoint operator

$$\langle \alpha | \hat{A} | \beta \rangle^* = \langle \psi_{\text{fin}} | \alpha \rangle = \langle \beta | \hat{A}^{\dagger} | \alpha \rangle$$

$\psi_{\text{fin}}$

$$A_{\beta\alpha}^* = A_{\alpha\beta}^{\dagger}$$

The matrix corresponding to an adjoint operator  $\hat{A}^{\dagger}$  is transposed and complex conjugate matrix of the operator  $\hat{A}$

Hermitian operators : describe reversible state evolution and physically ~~are~~ possible operation

$$|\psi_{\text{fin}}\rangle = A |\psi_{\text{ini}}\rangle = A^+ |\psi_{\text{ini}}\rangle \quad \hat{A} = \hat{A}^+$$

$$\langle \alpha | \hat{A} | \beta \rangle^* = \langle \beta | \hat{A}^+ | \alpha \rangle = \langle \beta | \hat{A} | \alpha \rangle$$

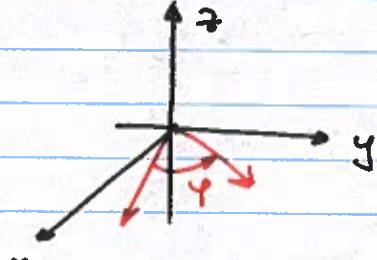
The diagonal elements of a Hermitian operator matrix are real numbers

The eigen values of a Hermitian operator are also real (hence, possible measurement outcomes)

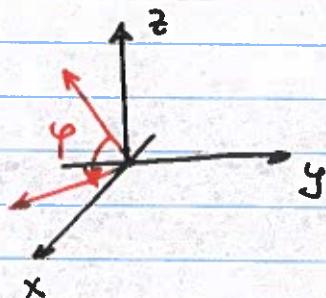
The expectation value of an operator  $\hat{A}$  in the state  $|\alpha\rangle$  is

$$\langle A \rangle_{\alpha} = \langle \alpha | \hat{A} | \alpha \rangle \quad (\text{in any basis})$$

# Rotation operators



Rotation in the x-y plane  
→ around z-axis



Rotation in the x-z plane  
→ around y-axis

Rotation operator general notation  $\hat{R}(\varphi \vec{n})$

angle of rotation axis of rotation

We can transform quantum states see state vectors using the rotation operators. For example, to rotate a state in x-y plane, we need to rotate it around  $\vec{k}$  (z) axis

$$|f_{in}\rangle = R(\vec{d}, \vec{d}) \hat{R}(\varphi \vec{k}) |f_{ini}\rangle = e^{-i \frac{\hbar}{\tau} \vec{j}_2 \cdot \varphi / \hbar} |f_{ini}\rangle$$

$e^{-i \frac{\hbar}{\tau} \vec{j}_2 \cdot \varphi / \hbar}$  can be calculated using Taylor expansion

$$e^x = 1 + x + \frac{1}{2!} x^2 + \frac{1}{3!} x^3 + \dots$$

$$\begin{aligned} e^{-\frac{i\varphi}{\hbar} \vec{j}_2} &= \hat{1} + \left(-\frac{i\varphi}{\hbar}\right) \vec{j}_2 + \frac{1}{2!} \left(-\frac{i\varphi}{\hbar}\right)^2 \vec{j}_2^2 + \frac{1}{3!} \left(-\frac{i\varphi}{\hbar}\right)^3 \vec{j}_2^3 + \dots \\ &= \hat{1} - i\varphi_2 \hat{j}_2 + \frac{1}{2!} \varphi^2/4 \hat{j}_2^2 - i\varphi^3/8 \hat{j}_2^3 + \frac{1}{4!} \varphi^4/16 \hat{j}_2^4 - \dots \end{aligned}$$

This can actually be simplified further, knowing that  $\hat{j}_2^2 = \hat{1}$ ,  $\hat{j}_2^3 = \hat{j}_2$ , etc.

$$e^{-\frac{i\varphi}{\hbar} \vec{j}_2} = \cos(\varphi/2) \hat{1} - i \sin(\varphi/2) \hat{j}_2$$

$$\hat{R}(\varphi \vec{k}) |+z\rangle = e^{-i \frac{\hbar}{\tau} \vec{j}_2 \cdot \varphi / \hbar} |+z\rangle = e^{-i \frac{\hbar}{\tau} \cdot \frac{\varphi}{2} / \hbar} |+z\rangle = e^{-i \varphi/2} |+z\rangle$$

This rotation doesn't change the state, but adds an extra phase