

Phys 475 S'10 Problem Set 3 Solutions

4.21 Two vectors are orthogonal iff their dot product vanishes.

$$\text{Let } \vec{C} = \vec{B}|\vec{A}| + \vec{A}|\vec{B}| \text{ and } \vec{D} = \vec{A}|\vec{B}| - \vec{B}|\vec{A}|$$

$$\begin{aligned} \vec{C} \cdot \vec{D} &= (\vec{B}|\vec{A}| + \vec{A}|\vec{B}|) \cdot (\vec{A}|\vec{B}| - \vec{B}|\vec{A}|) \\ &= \vec{B} \cdot \vec{A} |\vec{A}||\vec{B}| + \vec{A} \cdot \vec{A} |\vec{B}||\vec{B}| - \vec{B} \cdot \vec{B} |\vec{A}||\vec{A}| - \vec{A} \cdot \vec{B} |\vec{B}||\vec{A}| \end{aligned}$$

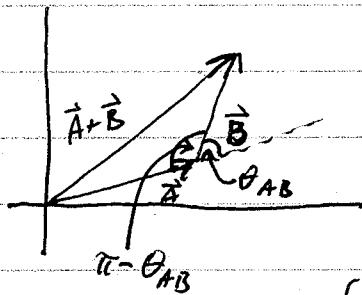
Using $\vec{B} \cdot \vec{A} = \vec{A} \cdot \vec{B}$ the first and last terms cancel.

$$\vec{A} \cdot \vec{A} = |\vec{A}||\vec{A}| \cos(0) = |\vec{A}|^2$$

$$\text{Similarly, } \vec{B} \cdot \vec{B} = |\vec{B}|^2.$$

$$\text{Hence, } \vec{C} \cdot \vec{D} = |\vec{A}|^2 |\vec{B}|^2 - |\vec{B}|^2 |\vec{A}|^2 = 0, \text{ and } \vec{C} \perp \vec{D}.$$

4.22



$$\begin{aligned} (\vec{A} + \vec{B}) \cdot (\vec{A} + \vec{B}) &= |\vec{A}|^2 + |\vec{B}|^2 + 2\vec{A} \cdot \vec{B} \\ &= |\vec{A}|^2 + |\vec{B}|^2 + 2|\vec{A}||\vec{B}| \cos \theta_{AB} \\ &= |\vec{A}|^2 + |\vec{B}|^2 - 2|\vec{A}||\vec{B}| \cos(\pi - \theta_{AB}) \end{aligned}$$

$$(\vec{A} + \vec{B}) \cdot (\vec{A} + \vec{B}) = |\vec{A} + \vec{B}|^2$$

We recognize the boxed equation as the law of cosines, where $\pi - \theta_{AB}$ is the angle indicated in the figure.

6.6

$$A^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}$$

$$B^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}$$

$$C^2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}$$

$$AB = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, \quad BA = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix}$$

$$BC = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}, \quad CB = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix}$$

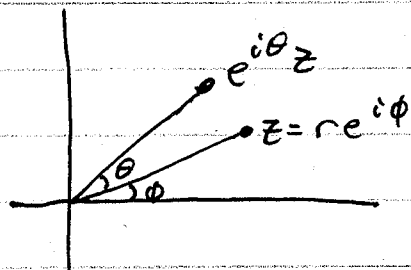
$$AC = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad CA = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

From these products it immediately follows that

$$AB = -BA, \quad AC = -CA, \quad BC = -CB, \text{ and}$$

$$AB - BA = 2iC, \quad BC - CB = 2iA, \quad CA - AC = 2iB.$$

7.19



$$\begin{aligned}
 e^{i\theta}z &= e^{i\theta}(\alpha + iy) \\
 &= (\cos\theta + i\sin\theta)(\alpha + iy) \\
 &= (\cos\theta\alpha - \sin\theta y) \\
 &\quad + i(\sin\theta\alpha + \cos\theta y) \\
 &= X + iY, \text{ where}
 \end{aligned}$$

$$X = \cos\theta\alpha - \sin\theta y$$

$$Y = \sin\theta\alpha + \cos\theta y$$

These two relations are equivalent to:

$$\begin{pmatrix} X \\ Y \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} \alpha \\ y \end{pmatrix} \quad \checkmark$$

Note that $\sin\theta$ and $-\sin\theta$ in the rotation matrix are reversed from our discussion in class. This transformation represents an active rotation of the vector (α, y) by an angle θ . In class we described a passive transformation in which the vector was fixed, but the coordinates rotated by an angle θ , which has an opposite effect on the components of the vector.

9.15 a) $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

$$B = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$C = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$A^\dagger = \overline{(A^T)} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = A \quad \checkmark$$

$$B^\dagger = \overline{(B^T)} = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = B \quad \checkmark$$

$$C^\dagger = \overline{(C^T)} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = C \quad \checkmark$$

b) From problem 6.6, $[A, B] = AB - BA = 2iC,$

$$[B, C] = 2iA, \quad [C, A] = 2iB$$

$$[A, [B, C]] + [B, [C, A]] + [C, [A, B]] =$$

$$= [A, 2iA] + [B, 2iB] + [C, 2iC]$$

$$= 2i(AA - AA) + 2i(BB - BB) + 2i(CC - CC)$$

$$= 0 \quad \checkmark$$

$$9.15 \quad c) [A, [B, C]] = A(BC - CB) - (BC - CB)A \\ = ABC - ACB - BCA + CBA$$

$$[B, [C, A]] = B(CA - AC) - (CA - AC)B \\ = BCA - BAC - CAB + ACB$$

$$[C, [A, B]] = C(AB - BA) - (AB - BA)C \\ = CAB - CBA - ABC + BAC$$

Summing these three expressions, we check the Jacobi identity:

$$[A, [B, C]] + [B, [C, A]] + [C, [A, B]] = 0 \quad \checkmark$$

Additional Problems

$$1. \quad M = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$e^{iM\theta/2} = \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{iM\theta}{2}\right)^n$$

$$M^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}$$

Hence, $M^{2m} = \mathbb{1} \quad \forall$ integer m .

$M^{2m+1} = M \quad \forall$ integer m .

$$e^{iM\theta/2} = \sum_{n=0}^{\infty} \frac{1}{(2n)!} \left(\frac{i\theta}{2}\right)^{2n} M^{2n} + \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} \left(\frac{i\theta}{2}\right)^{2n+1} M^{2n+1}$$

$$= \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} \left(\frac{\theta}{2}\right)^{2n} \mathbb{1} + \sum_{n=0}^{\infty} \frac{i(-1)^n}{(2n+1)!} \left(\frac{\theta}{2}\right)^{2n+1} M$$

$$= \cos\left(\frac{\theta}{2}\right) \mathbb{1} + i \sin\left(\frac{\theta}{2}\right) M$$

$$= \cos\left(\frac{\theta}{2}\right) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + i \sin\frac{\theta}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$= \begin{pmatrix} \cos\theta/2 & 0 \\ 0 & \cos\theta/2 \end{pmatrix} + \begin{pmatrix} 0 & \sin\theta/2 \\ -\sin\theta/2 & 0 \end{pmatrix} = \boxed{\begin{pmatrix} \cos\theta/2 & \sin\theta/2 \\ -\sin\theta/2 & \cos\theta/2 \end{pmatrix}}$$

2.

$$M = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$M^{2n} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} = M^{2n} \quad \forall \text{ integer } n > 0 \quad (M^0 = \mathbf{1})$$

$$M^{2n+1} = M \quad \forall n \text{ integer.}$$

$$e^{iM\theta} = \sum_{n=0}^{\infty} \frac{1}{n!} (i\theta)^n M^n$$

$$= \mathbf{1} + \sum_{n=1}^{\infty} \frac{1}{(2n)!} (i\theta)^{2n} M^{2n} + \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} (i\theta)^{2n+1} M^{2n+1}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \sum_{n=1}^{\infty} \frac{(-1)^n}{(2n)!} \theta^{2n} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \sum_{n=0}^{\infty} \frac{i(-1)^n \theta^{2n+1}}{(2n+1)!} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} \theta^{2n} & \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} \theta^{2n+1} & 0 \\ - \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} \theta^{2n+1} & \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} \theta^{2n} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\} a) \vec{D} = (\vec{A} \cdot \vec{C}) \vec{B} - (\vec{A} \cdot \vec{B}) \vec{C}$$

$$\vec{D} \cdot \vec{A} = (\vec{A} \cdot \vec{C})(\vec{B} \cdot \vec{A}) - (\vec{A} \cdot \vec{B})(\vec{C} \cdot \vec{A})$$

$$= 0 \text{ using } \vec{A} \cdot \vec{C} = \vec{C} \cdot \vec{A} \text{ and } \vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}.$$

b) IF \vec{B} is parallel to \vec{C} then $\vec{B} = k\vec{C}$ for some real number k .

$$\text{Then } \vec{D} = (\vec{A} \cdot \vec{C}) k\vec{C} - (\vec{A} \cdot (k\vec{C})) \vec{C}$$

$$= k(\vec{A} \cdot \vec{C}) \vec{C} - k(\vec{A} \cdot \vec{C}) \vec{C}$$

$$= 0$$

↑ using linearity of the dot product.